

Tutorial on semidefinite programming (SDP)  
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**Instructor:**

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**Goals:**

- Basic theory of semidefinite and second-order programming
- Some applications
- Acquaintance with some popular solvers
- Current challenges/trends

**Brief and incomplete history of SDP**

- Eigenvalue optimization, LMI problems (1960s – 1970s)
- Lovász theta function (1979) in information theory
- Interior-point algorithms for SDP by Alizadeh, and by Nesterov & Nemirovski (1980s, 1990s)
- Intense development of theory, algorithms, applications (1990s)
- Extension to symmetric cones, development of general-purpose solvers (1990s)
- Currently: homogeneous, hyperbolic, polynomial programming. Solution to large problems.

**Course outline:**

- SDP: generalization of linear programming (LP)
- Examples of SDP applications
- SDP theory: duality, complementarity
- Second-order programming (SOCP)
- SOCP/LP/SDP conic programming
- Examples of SOCP/LP/SDP applications
- Solvers: SeDuMi, SDPT3
- Polynomials and sum-of-squares (SOS), copositive matrices
- Symmetric, homogeneous, hyperbolic cones

**Preamble: Some stuff about symmetric matrices**

$\mathbf{R}^n$  :  $n$ -dim Euclidean vector space

$\mathbf{R}^{n \times n}$ :  $n \times n$  matrices with entries in  $\mathbf{R}$

$\mathbf{S}^n$ :  $n \times n$  symm matrices with entries in  $\mathbf{R}$

$\mathbf{O}^n$ :  $n \times n$  orthogonal matrices

**Thm (spectral decomposition).** If  $X \in \mathbf{S}^n$  then there exist  $\lambda(X) = (\lambda_1(X), \dots, \lambda_n(X)) \in \mathbf{R}^n$  and  $Q \in \mathbf{O}^n$  such that

$$X = Q \text{Diag}(\lambda(X)) Q^T.$$

**Defn:** Let  $X \in \mathbf{S}^n$  be given.

$X$  is *positive semidefinite* if  $\lambda(X) \geq 0$  denoted as  $X \succeq 0$

$X$  is *positive definite* if  $\lambda(X) > 0$ , denoted as  $X \succ 0$

**Prop.** Let  $X \in \mathbf{S}^n$ . Then

$$\begin{aligned} X \succeq 0 &\Leftrightarrow \lambda_{\min}(X) \geq 0 \\ &\Leftrightarrow \exists R \in \mathbf{S}^n \text{ s.t. } X = R^2 \\ &\Leftrightarrow \exists L \in \mathbf{R}^{n \times n} \text{ s.t. } X = LL^T \\ &\Leftrightarrow \forall u \in \mathbf{R}^n \ u^T X u \geq 0. \end{aligned}$$

**Prop.**

(a) If  $M \in \mathbf{R}^{m \times n}$  then  $\|M\|^2 = \lambda_{\max}(M^T M) = \lambda_{\max}(M M^T)$ .

(b) If  $M \in \mathbf{S}^n$  then  $\|M\| = |\lambda_{\max}(M)|$ .

Positive semidefinite cone:

$$\mathbf{S}_+^n := \{X \in \mathbf{S}^n : X \succeq 0\}.$$

### Examples of SDP.

**Example 1 (eigenvalue optimization):** Suppose  $A_0, A_1, \dots, A_m \in \mathbf{S}^n$  and want to solve

$$\min_y \lambda_{\max}(A_0 + y_1 A_1 + \dots + y_m A_m).$$

Can reformulate as

$$\begin{aligned} \min \quad &t \\ \text{s.t.} \quad &A_0 + y_1 A_1 + \dots + y_m A_m \preceq tI \end{aligned}$$

**Example 2 (norm minimization):** Suppose  $A_0, A_1, \dots, A_m \in \mathbf{R}^{p \times q}$  and want to solve

$$\min_y \|A(y)\|,$$

for  $A(y) := A_0 + y_1 A_1 + \dots + y_m A_m$ .

### SDP as a generalization of linear programming (LP)

LP:

$$\begin{aligned} \max_y \quad &b^T y \\ \text{s.t.} \quad &y_1 a_1 + \dots + y_m a_m \leq c, \end{aligned}$$

where  $c, a_1, \dots, a_m \in \mathbf{R}^n$ ,  $b \in \mathbf{R}^m$  are given and  $y \in \mathbf{R}^m$ .

SDP:

$$\begin{aligned} \max_y \quad &b^T y \\ \text{s.t.} \quad &y_1 A_1 + \dots + y_m A_m \preceq C \end{aligned}$$

where  $C, A_1, \dots, A_m \in \mathbf{S}^n$ ,  $b \in \mathbf{R}^m$  are given and  $y \in \mathbf{R}^m$ .

Here  $M \preceq N \Leftrightarrow N - M \succeq 0$ .

Can reformulate as

$$\begin{aligned} \min \quad &t \\ \text{s.t.} \quad &\begin{bmatrix} tI & A(y) \\ A(y)^T & tI \end{bmatrix} \succeq 0 \end{aligned}$$

The formulation relies on the following lemma.

**Schur Complement Lemma:** Suppose  $B, D$  are symmetric and  $B \succ 0$ . Then

$$\begin{bmatrix} B & C \\ C^T & D \end{bmatrix} \succeq 0 \Leftrightarrow D - C^T B^{-1} C \succeq 0.$$

## LP primal and dual forms

Recall that the dual of

$$\begin{aligned} \max \quad & b^T y \\ \text{s.t.} \quad & y_1 a_1 + \dots + y_m a_m \leq c \end{aligned}$$

is

$$\begin{aligned} \min \quad & c^T x \\ \text{s.t.} \quad & a_i^T x = b_i, \quad i = 1, \dots, m \\ & x \geq 0. \end{aligned}$$

The dual can be seen as the “best” upper bound on the primal problem obtained by combining the primal constraints.

## SDP primal and dual forms

The dual of

$$\begin{aligned} \max \quad & b^T y \\ \text{s.t.} \quad & y_1 A_1 + \dots + y_m A_m \preceq C \end{aligned}$$

is

$$\begin{aligned} \min \quad & C \bullet X \\ \text{s.t.} \quad & A_i \bullet X = b_i, \quad i = 1, \dots, m \\ & X \succeq 0. \end{aligned}$$

Can do something similar for SDP.

Endow  $S^n$  with the following inner product: for  $X, S \in S^n$

$$X \bullet S := \text{trace}(XS)$$

**Recall:** for  $X \in \mathbb{R}^{n \times n}$

$$\begin{aligned} \text{trace}(X) &= \sum_{i=1}^n \lambda_i(X) \\ &= \text{coefficient of } -\lambda^{n-1} \text{ in } \det(\lambda I - X) \\ &= \sum_{i=1}^n X_{ii}. \end{aligned}$$

**Notice:** If  $X \in S_+^n$  then  $\text{trace}(X) \geq 0$ .

Frobenius norm  $\|X\|_F := (X \bullet X)^{1/2}$ .

**Fact:** For  $U, V, W \in \mathbb{R}^{n \times n}$ ,  $\text{trace}(UVW) = \text{trace}(VWU)$ .

## More examples/applications of SDP

### Example 3 (positive polynomials).

$p(t) = p_1 + p_2 t + \dots + p_{2d+1} t^{2d}$  satisfies  $p(t) \geq 0 \quad \forall t \in \mathbb{R}$  if and only if  $\exists X \in S_+^{d+1}$  such that

$$p_i = \sum_{j+k=i+1} X_{jk}, \quad i = 1, \dots, 2d+1.$$

The equivalence relies on the following classical result.

**Markov-Lucacs Thm.** Let  $p(t)$  be a  $2d$ -degree polynomial. Then

$$p(t) \geq 0 \quad \forall t \in \mathbb{R} \Leftrightarrow p(t) = q(t)^2 + r(t)^2$$

for some  $d$ -degree polynomials  $q(t), r(t)$ .

**Equivalence SDP/SOS:**

Suppose  $q(t) = q_1 + q_2t + \dots + q_{d+1}t^d$ . Can write  $q(t)$  as

$$\begin{bmatrix} q_1 & \dots & q_{d+1} \end{bmatrix} \begin{bmatrix} 1 \\ t \\ \vdots \\ t^d \end{bmatrix}.$$

Therefore

$$p(t) = q(t)^2 \Leftrightarrow \begin{bmatrix} p_1 & \dots & p_{2d+1} \end{bmatrix} \begin{bmatrix} 1 \\ \vdots \\ t^{2d} \end{bmatrix} = \begin{bmatrix} 1 & \dots & t^d \end{bmatrix} q q^T \begin{bmatrix} 1 \\ \vdots \\ t^d \end{bmatrix}.$$

**Example 4 (Lovász's theta function):** Let  $G = (N, E)$  be an undirected graph, where  $N = \{1, \dots, n\}$ . Put:

$\omega(G)$ : clique number of  $G$

$\chi(G)$ : chromatic number of  $G$ .

Notice that  $\omega(G) \leq \chi(G)$ .

Define

$$\vartheta(\bar{G}) := \max \begin{array}{l} e e^T \bullet X \\ I \bullet X = 1 \\ X_{ij} = 0, ij \notin E \\ X \succeq 0. \end{array}$$

**Thm (Lovász):**  $\omega(G) \leq \vartheta(\bar{G}) \leq \chi(G)$ .

Hence  $p(t) \geq 0 \forall t \in \mathbf{R}$  iff  $p(t)$  is SOS iff for some  $X \succeq 0$

$$\begin{bmatrix} p_1 & \dots & p_{2d+1} \end{bmatrix} \begin{bmatrix} 1 \\ \vdots \\ t^{2d} \end{bmatrix} = \begin{bmatrix} 1 & \dots & t^d \end{bmatrix} X \begin{bmatrix} 1 \\ \vdots \\ t^d \end{bmatrix}$$

But latter identity is the same as

$$p_i = \sum_{j+k=i+1} X_{jk}, i = 1, \dots, 2d + 1.$$

It follows that given a  $2d$ -degree polynomial  $p(t)$  the problem of computing

$$p^* := \min_t p(t)$$

can be formulated as an SDP. (How?)

**Proof of  $\omega(G) \leq \vartheta(\bar{G})$ .**

Assume  $K$  is a clique in  $G$ . Let  $\chi_K \in \{0, 1\}^n$  be the "indicator" vector of  $S$ . Consider

$$X := \frac{1}{|K|} \chi_K \chi_K^T.$$

Observe that  $X$  is feasible for the SDP and

$$e e^T \bullet X = e^T X e = \frac{(e^T \chi_K)^2}{|K|} = \frac{|K|^2}{|K|} = |K|.$$

Thus  $\vartheta(G) \geq |K|$ . □

**Example 5 (Max-cut):** Let  $G = (N, E)$  be an undirected graph, where  $N = \{1, \dots, n\}$ . Assume have edge-weights  $w = (w_{ij}) \in \mathbf{R}_+^E$ . For  $K \subseteq N$ ,  $\delta(K) := \{ij \in E : i \in K, j \notin K\}$ .

MAX-CUT problem:

$$\max_{K \subseteq N} \sum_{ij \in \delta(K)} w_{ij}$$

Can formulate MAX-CUT as

$$\begin{aligned} \max \quad & \frac{1}{4} \sum_{i,j=1}^n w_{ij}(1 - x_i x_j) \\ \text{s.t.} \quad & x_i \in \{-1, 1\}, i \in N. \end{aligned}$$

**Proof.** Let  $X$  be feasible for the SDP relaxation. Then  $X = V^T V$  for some  $V = [v_1 \ \dots \ v_n] \in \mathbf{R}^{n \times n}$ , where each  $\|v_i\| = 1$ .

Construct a cut as follows: Pick  $v \in \mathbf{R}^n$ ,  $\|v\| = 1$  uniformly at random and put

$$K := \{i \in N : v^T v_i \geq 0\}.$$

It turns out that the expected value of this cut is

$$W[X] = \frac{1}{2} \sum_{i,j=1}^n \frac{w_{ij} \arccos X_{ij}}{\pi} \geq \frac{\alpha}{4} \sum_{i,j=1}^n w_{ij}(1 - X_{ij}).$$

It follows that  $\text{MAX-CUT} \geq \alpha \text{SDP}$ .

The inequality  $\text{MAX-CUT} \leq \text{SDP}$  is immediate.  $\square$

Putting  $X = xx^T$ , can reformulate the latter as

$$\begin{aligned} \max \quad & \frac{1}{4} \sum_{i,j=1}^n w_{ij}(1 - X_{ij}) \\ \text{s.t.} \quad & X_{ii} = 1, i \in N \\ & X \succeq 0 \\ & X \text{ rank-one.} \end{aligned}$$

SDP relaxation

$$\begin{aligned} \max \quad & \frac{1}{4} \sum_{i,j=1}^n w_{ij}(1 - X_{ij}) \\ \text{s.t.} \quad & X_{ii} = 1, i \in N \\ & X \succeq 0. \end{aligned}$$

**Thm (Goemans & Williamson):**  $0.87856 \leq \frac{\text{MAX-CUT}}{\text{SDP}} \leq 1$ .

$$\alpha = 0.87856 := \min_{t \in [-1,1]} \frac{2 \arccos(t)}{\pi(1-t)}.$$

**Example 6**

$$\begin{aligned} \max \quad & x^T Q x \\ \text{s.t.} \quad & x_i \in \{-1, 1\}, i = 1, \dots, n. \end{aligned}$$

SDP relaxation

$$\begin{aligned} \max \quad & Q \bullet X \\ \text{s.t.} \quad & X_{ii} = 1, i = 1, \dots, n \\ & X \succeq 0. \end{aligned}$$

**Thm (Nesterov).** If  $Q \succeq 0$  then

$$\frac{2}{\pi} \leq \frac{\text{OPT}}{\text{SDP}} \leq 1.$$

There are more schemes to get SDP-relaxations of combinatorial problems.

## Duality and complementarity

Recall LP duality: For conciseness put

$$A := [a_1 \ \cdots \ a_m]^T.$$

Primal-dual pair

$$\begin{array}{ll} \min & c^T x \\ \text{(P) s.t.} & Ax = b \\ & x \geq 0, \end{array} \quad \begin{array}{ll} \max & b^T y \\ \text{(D) s.t.} & A^T y + s = c \\ & s \geq 0. \end{array}$$

**Prop (weak duality).** If  $x$  is (P)-feas, and  $(y, s)$  is (D)-feasible then

$$b^T y \leq c^T x.$$

Given  $x, s \in \mathbf{R}^n$  define  $x \circ s \in \mathbf{R}^n$  as

$$(x \circ s)_i = x_i s_i, \quad i = 1, \dots, n.$$

Can recast (P) and (D) as

$$\begin{array}{l} A^T y + s = c \\ Ax = b \\ x \circ s = 0 \\ x, s \geq 0. \end{array}$$

Simplex method: maintain first three conditions; aim for the last one.

Interior-point methods: maintain first two and last one, aim for the third one.

**Thm (strong duality).** If either (P) or (D) is feasible and bounded, then both have optimal solutions. In that case  $x$  and  $(y, s)$  solve (P) and (D) respectively iff

$$b^T y = c^T x \Leftrightarrow x^T s = 0.$$

**Prop (complementarity).** Let  $x, s \in \mathbf{R}_+^n$ . Then

$$x^T s = 0 \Leftrightarrow x_i s_i = 0, \quad i = 1, \dots, n.$$

Similar duality results for SDP?

For conciseness let  $\mathcal{A} : \mathbf{S}^n \rightarrow \mathbf{R}^m$  be the mapping

$$X \mapsto [A_1 \bullet X \ \cdots \ A_m \bullet X]^T.$$

The adjoint is  $\mathcal{A}^* : \mathbf{R}^m \rightarrow \mathbf{S}^n$  is defined by

$$y \mapsto y_1 A_1 + \cdots + y_m A_m.$$

Consider the SDP primal-dual pair.

$$\begin{array}{ll} \min & C \bullet X \\ \text{(P) s.t.} & \mathcal{A}X = b \\ & X \succeq 0, \end{array} \quad \begin{array}{ll} \max & b^T y \\ \text{(D) s.t.} & \mathcal{A}^* y + S = C \\ & S \succeq 0. \end{array}$$

**Prop (weak duality).** If  $X$  is (P)-feas, and  $(y, S)$  is (D)-feasible then

$$b^T y \leq C \bullet X.$$

**Proof.**

$$C \bullet X - b^T y = (A^* y + S) \bullet X - (AX)^T y = S \bullet X.$$

Because  $S \in \mathbf{S}_+^n$ , can put  $S = LL^T$  for some  $L \in \mathbf{R}^{n \times n}$ .

Hence, since  $X \in \mathbf{S}_+^n$

$$S \bullet X = \text{trace}(LL^T X) = \text{trace}(L^T X L) \geq 0.$$

□

Other pathologies may occur: inf/sup may not be attained. One of the problems may be feasible and bounded while the other is infeasible.

**Example 8.** Consider the SDP

$$\begin{aligned} \min \quad & X_{12} \\ \text{s.t.} \quad & \begin{bmatrix} 0 & X_{12} \\ X_{12} & X_{22} \end{bmatrix} \succeq 0 \end{aligned}$$

and its dual

$$\begin{aligned} \max \quad & 0 \\ \text{s.t.} \quad & \begin{bmatrix} -y_1 & 1/2 \\ 1/2 & 0 \end{bmatrix} \succeq 0. \end{aligned}$$

Primal optimal value is 0; dual is infeasible.

**Example 9.**

$$\begin{aligned} \min \quad & X_{11} \\ \text{s.t.} \quad & \begin{bmatrix} X_{11} & 1 \\ 1 & X_{22} \end{bmatrix} \succeq 0. \end{aligned}$$

Optimal value is 0, but it is not attained.

Strong duality may not necessarily hold...

**Example 7.** Consider the SDP

$$\begin{aligned} \min \quad & X_{12} \\ \text{s.t.} \quad & \begin{bmatrix} 0 & X_{12} & 0 \\ X_{12} & X_{22} & 0 \\ 0 & 0 & 1 + X_{12} \end{bmatrix} \succeq 0 \end{aligned}$$

and its dual

$$\begin{aligned} \max \quad & y_1 \\ \text{s.t.} \quad & \begin{bmatrix} -y_2 & \frac{1+y_1}{2} & -y_3 \\ \frac{1+y_1}{2} & 0 & -y_4 \\ -y_3 & -y_4 & -y_1 \end{bmatrix} \succeq 0. \end{aligned}$$

Primal optimal value is 0;

dual optimal value is  $-1$ .

Crux of strong duality in LP:

**Farkas Lemma:** Assume  $A \in \mathbf{R}^{m \times n}$ ,  $b \in \mathbf{R}^m$ . Then either

$$\exists x \text{ s.t. } Ax = b, x \geq 0$$

or

$$\exists y \text{ s.t. } A^T y \geq 0, b^T y < 0$$

but not both.

For SDP:

**Asymptotic Farkas Lemma:** Assume  $\mathcal{A} \in L(\mathbf{S}^n, \mathbf{R}^m)$ ,  $b \in \mathbf{R}^m$ . Then either

$$b \in \overline{\{\mathcal{A}X : X \succeq 0\}}$$

or

$$\exists y \text{ s.t. } \mathcal{A}^* y \succeq 0, b^T y < 0$$

but not both.

Get strong duality under additional assumptions:

(P) strongly feasible if  $b \in \text{int} \{AX : X \succeq 0\}$ .

(D) strongly feasible if  $C \in \text{int} \{A^*y + S : S \succeq 0\}$ .

**Usual assumption:**  $A$  surjective, i.e.,  $A_1, \dots, A_m$  linearly independent.

Under such assumption (P) strongly feasible iff  $\exists X \succ 0$  s.t.  $AX = b$ .

**Strong Duality Thm.** Assume (P) and (D) are strongly feasible. Then both (P) and (D) have optimal solutions. In that case  $X$  and  $(y, S)$  are optimal sols to (P) and (D) respectively iff

$$b^T y = C \bullet X \Leftrightarrow X \bullet S = 0.$$

Hence under the strong feasibility assumptions can recast (P) and (D) as

$$\begin{aligned} A^*y + S &= C \\ AX &= b \\ XS &= 0 \\ X, S &\succeq 0. \end{aligned}$$

Strong Duality Thm follows from Asymptotic Farkas Lemma and the following lemma.

**Lemma.** If  $A^*z \in \mathbf{S}_{++}^n$  for some  $z \in \mathbf{R}^m$  then  $\mathcal{AS}_{+}^n := \{AX : X \succeq 0\}$  is closed.

### SDP Complementarity

**Prop (complementarity).** Let  $X, S \in \mathbf{S}_{+}^n$ . Then  $X \bullet S = 0$  iff  $XS = 0$  iff there exists  $Q \in \mathbf{O}^n$ ,  $\lambda, \omega \in \mathbf{R}_{+}^n$  such that

$$\begin{aligned} X &= Q \text{Diag}(\lambda) Q^T, \quad S = Q \text{Diag}(\omega) Q^T, \\ \lambda_i \omega_i &= 0, \quad i = 1, \dots, n. \end{aligned}$$

### References for today's material

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