

Artificial Intelligence Methods for Social Good

MI-3 [Optimization]:

Combinatorial Optimization and Robust Optimization

08-537 (9-unit) and 08-737 (12-unit)

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Learning Objectives

- ▶ Understand the concept of
 - ▶ Maximin model
 - ▶ Minimax regret
- ▶ Briefly describe
 - ▶ Branch and bound algorithm
- ▶ Optional
 - ▶ Dual problem of a linear program

Robust Optimization

- ▶ How do we deal with uncertainty?
- ▶ Exp I: Choose location for a party
- ▶ When you know the probability of raining (whether forecast): Compute expected utility
- ▶ When you don't know: robust optimization
 - ▶ Maximin: Maximize the worst case utility (Conservative)
 - ▶ Minimax regret (Less conservative)
 - ▶ Minimize maximum regret
 - ▶ Regret: Gap between my current utility and the best possible utility given the whether condition

Robust Optimization

- ▶ Solve Minimax Regret when there are many actions and possibilities
 - ▶ Constraint sampling/constraint generation
 - ▶ Sample a subset of actions and possibilities
 - ▶ Solve the restricted problem
 - ▶ Find most “critical” combination of action and possibilities
 - ▶ Resolve the restricted problem
 - ▶ Repeat until some stopping criteria

Quiz I

Difficulty of Exam

Effort Spend

	Low	Medium	High
Easy	$9-0=9$	$9-1=8$	$10-3=7$
Medium	$5-0=5$	$7.5-1=6.5$	$9-3=6$
Hard	$2-0=2$	$5-1=4$	$8-3=5$

- ▶ What is the value of minimax regret?
 - ▶ 1
 - ▶ 2
 - ▶ 0.5
 - ▶ 3

Branch and Bound

- ▶ Binary Program with linear objective and constraints
- ▶ Key idea:
 - ▶ Incrementally build a binary search tree
 - ▶ Prune the tree using lower bound and upper bound
 - ▶ Expand the most promising leaf node

Branch and Bound

▶ Exp 2: Knapsack ($W=10$)

Items	1	2	3	4	5
Weight	5	4	2	6	7
Value	4	3	6	9	5

- ▶ Upper bound: LP relaxation (poly-time computable)
- ▶ Lower bound: Any feasible integer solution

Solving (Mixed) Integer Program with Branch and Bound

- ▶ Recall MILP: An optimization problem whose optimization objective is a linear function and feasible region is defined by linear constraints and integer constraints
- ▶ Key Ideas of Branch and Bound for MILP
 - ▶ If value of all integer variables are determined, then become an LP (can be efficiently solved using e.g., Simplex algorithm!)
 - ▶ Substitute the integer variables with binary variables
 - ▶ Build a binary search tree for the binary variables
 - ▶ Prune the tree using lower bound and upper bound

Recall: Linear Program

- ▶ An optimization problem whose optimization objective is a linear function and feasible region is defined by linear constraints
- ▶ Dual problem of an LP: also a linear program
- ▶ Strong duality theorem: LP and its dual have the same value

Write the Dual of an LP

► Exp 3: Maximize Profit

	Price	Labor	Machine
Product 1	\$30	0.2 hour	4 hour
Product 2	\$30	0.5 hour	2 hour
Total		≤ 90	≤ 800

Write the Dual of an LP (Non-Standard form)

Maximize	Minimize
ith constraint \leq	ith variable ≥ 0
ith constraint \geq	ith variable ≤ 0
ith constraint =	ith variable unrestricted
jth variable ≥ 0	jth constraint \geq
jth variable ≤ 0	jth constraint \leq
jth variable unrestricted	jth constraint =

Other properties of LP Duality

- ▶ Complementary slackness
 - ▶ Primal constraint is not tight \rightarrow dual variable=0
 - ▶ Primal variable is not zero \rightarrow dual constraint is tight
 - ▶ Dual constraint is not tight \rightarrow primal variable=0
 - ▶ Dual variable is not zero \rightarrow primal constraint is tight
- ▶ Optimality Conditions: If x, y are feasible solutions to the primal and dual problems, respectively, then they are optimal solutions to these problems if, and only if, the complementary-slackness conditions hold for both the primal and the dual problems

Reference and Related Work

- ▶ [Combinatorial Optimization: Algorithms and Complexity, Chapters 3](#)
 - ▶ Christos H. Papadimitriou, Kenneth Steiglitz
- ▶ [Branch-and-price: Column generation for solving huge integer programs](#)
 - ▶ Cynthia Barnhart, Ellis L. Johnson, George L. Nemhauser, Martin W. P. Savelsbergh, Pamela H. Vance
- ▶ [Robust protection of fisheries with COMPASS](#)
 - ▶ William Haskell, Debarun Kar, Fei Fang, Milind Tambe, Sam Cheung, Elizabeth Denicola

Paper Discussion

- ▶ (PRA5) [Keeping Pace with Criminals: An Extended Study of Designing Patrol Allocation against Adaptive Opportunistic Criminals](#)
 - ▶ Chao Zhang, Shahrzad Gholami, Debarun Kar, Arunesh Sinha, Manish Jain, Ripple Goyal, Milind Tambe
- ▶ Summary
 - ▶ Societal challenge
 - ▶ AI method
 - ▶ Contributions
- ▶ Questions
- ▶ Brainstorming Ideas
 - ▶ Improvement / future direction / other valid discussions
 - ▶ Societal challenge and AI method that can potentially be used to tackle it (not necessarily relevant to the paper)