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A Logical Characterization of Small 2NFAs

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Let $2N$ be the class of families of problems solvable by families of *two-way nondeterministic finite automata* of polynomial size. We characterize $2N$ in terms of families of formulas of *transitive-closure logic*. These formulas apply the transitive-closure operator on a quantifier-free disjunctive normal form of *first-order logic with successor and constants*, where (i) apart from two special variables, all others are equated to constants in every clause, and (ii) no clause simultaneously relates these two special variables and refers to fixed input cells. We prove that automata with polynomially many states are as powerful as formulas with polynomially many clauses and polynomially large constants. This can be seen as a refinement of Immerman's theorem that nondeterministic logarithmic space matches positive transitive-closure logic ($NL = FO + pos TC$).

1. Introduction

A formal machine M and a logical formula φ are equivalent if they determine the same language: a string w is accepted by M iff it satisfies φ . Such comparisons between machines and formulas are the topic of Descriptive Complexity Theory [4]. Its inaugural result was Fagin's Theorem, which says that polynomial-time nondeterministic Turing machines (NTMs) are equivalent to formulas of *existential second-order logic* ($NP = \exists SO$) [2]. An analogous result for space complexity is Immerman's theorem that logarithmic-space NTMs are equivalent to formulas of *positive transitive-closure logic* ($NL = FO + pos TC$) [3]. Today we know many such 'logical characterizations' of various computational complexity classes [4].

When it comes to finite automata (on finite strings), an old result of this kind is Büchi's Theorem, that *one-way nondeterministic finite automata* (1NFAs) are equivalent to formulas of *monadic second-order logic with successor* ($MSO[S]$) [1] —and thus so are, too, all automata recognizing the regular languages, including the deterministic and/or two-way variants (1DFAs, 2DFAs, 2NFAs). But this is a 'computability result', in the sense that the equivalence involves no restriction on the

automata resources —as opposed to Fagin’s and Immerman’s ‘complexity results’, where the NTMs are restricted to use only polynomial time or logarithmic space, respectively. What if we focus on automata where the main resource, the number of states, is restricted to be polynomial (in a given parameter)?

We first asked this in [6], in the context of building a size-complexity theory of two-way finite automata, or ‘Minicomplexity Theory’ [5]. Specifically, we asked: What is an analog of Fagin’s Theorem when we replace NTMs and time with 2NFAS and size? Unfortunately, however, we failed to answer in full generality. Instead, we proved such analogs only for the one-way, rotating, and sweeping restrictions of 2NFAS (where the input head can, respectively, only move forward; or only move forward and jump to the start; or turn only on the end-markers).

The present paper contains the full answer to that question of [6]. In what can be seen as a refinement of Immerman’s theorem from above, we prove that polynomial-size 2NFAS are equivalent to a certain class of formulas of FO+pos TC. Specifically, we focus on formulas consisting of a single, positive application of the transitive-closure operator on a quantifier-free disjunctive normal form of first-order logic with successor and constants, where (i) each of the conjunctive clauses equates every variable, except for two special ones, to some constant, and (ii) none of these clauses can *both* relate the two special variables *and* refer to a fixed input cell. We call such formulas *weak one-dimensional graph-accessibility disjunctive-normal-forms* (weak GA/DNF_{1S}) and prove that they are equivalent to polynomial-size 2NFAS, if their clauses are polynomially many and their constants polynomially large. This completes our first step into what one could call ‘Descriptive Minicomplexity Theory’.

2. Preparation

Let \mathbb{Z} be all integers and $\mathbb{Z}^\pm := \mathbb{Z} - \{0\}$. If $n \geq 0$, then we let $[n] := \{0, \dots, n-1\}$, $\mathbb{Z}_n^+ := \{1, \dots, n\}$, and $\mathbb{Z}_n^- := \{-n, \dots, -1\}$. If $w \in \Sigma^*$ is a finite string over some alphabet Σ , then $|w|$ and w_x are its length and x -th symbol (if $1 \leq x \leq |w|$).

2.1. Finite automata

A *two-way nondeterministic finite automaton* is a tuple $N = (S, \Sigma, \delta, q_s, q_a)$ of a set of *states* S , an *alphabet* Σ , a *start state* $q_s \in S$, an *accept state* $q_a \in S$, and a set of *transitions* $\delta \subseteq S \times (\Sigma \cup \{\vdash, \dashv\}) \times S \times \{L, R\}$, where $\vdash, \dashv \notin \Sigma$ are the two *end-markers* and L,R are the two directions of motion for the input head.

A word $w \in \Sigma^*$ is presented to N between the end-markers, as $\vdash w \dashv$. The computation starts at q_s on \vdash . At each step, the next state and head motion may be any of those derived from δ and the current state and symbol. End-markers are never violated, except for \dashv if the next state is q_a . So, each branch of N ’s computation can *hang* inside the input; or *loop*; or fall off \dashv into q_a , in which case we call it *accepting*. If at least one branch is accepting, we say N *accepts* w .

Let $n = |w|$. A *configuration* of N on w is a pair $(p, x) \in S \times [n+3]$; it means N is at state p reading w_x , if $x \leq n+1$ (we let $w_0 := \vdash$ and $w_{n+1} := \dashv$); or has fallen off \dashv

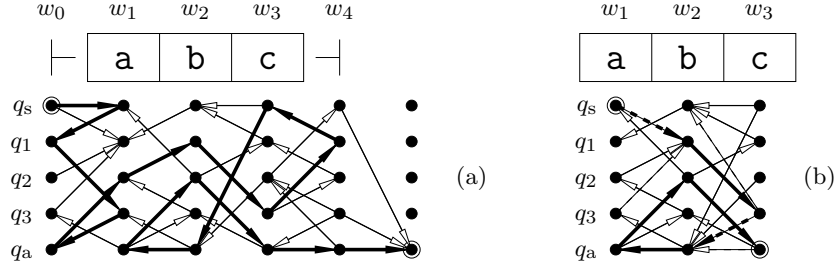


Figure 1. (a) The configuration graph of a 5-state 2NFA N on $w = abc$. An accepting branch in bold arrows. (b) The *inner* configuration graph of N on w . Dashed arrows are caused by computations on $\vdash w_1$ or $w_3 \dashv$. E.g., $(q_3, 1) \rightarrow (q_1, 2)$ is caused by $(q_3, 1) \rightarrow (q_a, 0) \rightarrow (q_2, 1) \rightarrow (q_1, 2)$ in (a).

into p , if $x = n+2$. The *configuration graph* $G_{N,w}$ of N on w (Fig. 1a) is the directed graph where vertices are configurations of N on w and an edge $(p, x) \rightarrow (q, y)$ exists iff N can switch from (p, x) to (q, y) in a single step, i.e., iff

$$y = x+1 \ \& \ (p, w_x, q, R) \in \delta \quad \text{or} \quad y = x-1 \ \& \ (p, w_x, q, L) \in \delta. \quad (1)$$

Clearly, N accepts w iff $G_{N,w}$ has a path $(q_s, 0) \rightsquigarrow (q_a, n+2)$.

When $n \geq 2$, a denser representation is the *inner configuration graph* $G'_{N,w}$ (Fig. 1b), where now the vertices are only the *inner configurations* $S \times \mathbb{Z}_n^+$ and an edge, or *inner step*, $(p, x) \rightarrow (q, y)$ exists iff any of the following holds:

- N can switch from (p, x) to (q, y) in a single step, as in (1);
- $x = 1, y = 2$, and the switch can happen by a U-turn computation on $\vdash w_1$;
- $x = n, y = n-1$, and the switch can happen by a U-turn on $w_n \dashv$.

We will need to say that N accepts w iff $G'_{N,w}$ has a path $(q_s, 1) \rightsquigarrow (q_a, n)$. But, in general, this is false; it becomes true, if N is in the form of Def. 1 (Fact 2ii). Conveniently, with two more states, every 2NFA can be put in this form (Fact 2i).

Definition 1. A 2NFA $N = (\cdot, \Sigma, \delta, q_s, q_a)$ is in inner normal form (INF) if

- i. δ contains (q_s, \vdash, q_s, R) , but no other tuple $(q_s, \vdash, \cdot, \cdot)$; and
- ii. δ contains every (q_a, a, q_a, R) for $a \in \Sigma \cup \{\dashv\}$, but no other tuple (\cdot, \cdot, q_a, R) .

Fact 2. i. Every s -state 2NFA is equivalent to a $(s+2)$ -state 2NFA in INF.
 ii. If N is in INF, then N accepts w iff $G'_{N,w}$ has a path $(q_s, 1) \rightsquigarrow (q_a, n)$.

Proof. (i) Pick any 2NFA $N = (S, \Sigma, \delta, q_s, q_a)$. For two states $p_s, p_a \notin S$, consider the 2NFA $N' = (S \cup \{p_s, p_a\}, \Sigma, \delta', p_s, p_a)$, where δ' augments δ with the transitions:

- (p_s, \vdash, p_s, R) and (p_s, a, q_s, L) for all $a \in \Sigma \cup \{\dashv\}$;
- (q, \dashv, p_a, L) for all $q \in S$ such that $(q, \dashv, q_a, R) \in \delta$; and
- (p_a, a, p_a, R) for all $a \in \Sigma \cup \{\dashv\}$.

Easily, N' starts with steps $(p_s, 0) \rightarrow (p_s, 1) \rightarrow (q_s, 0)$ and continues exactly as N , except that its final step $(q, n+1) \rightarrow (q_a, n+2)$ is replaced by $(q, n+1) \rightarrow (p_a, n) \rightarrow (p_a, n+1) \rightarrow (p_a, n+2)$. This creates a correspondence between the accepting computations of N and N' , making the two 2NFAs equivalent. Clearly, N' is in INF.

(ii) For the forward direction, suppose N accepts w . Then $G_{N,w}$ has a path $(q_s, 0) \rightsquigarrow (q_a, n+2)$, call it π . By Def. 1i, π starts with the step $(q_s, 0) \rightarrow (q_s, 1)$; by Def. 1ii, it ends with the steps $(q_a, n) \rightarrow (q_a, n+1) \rightarrow (q_a, n+2)$. So, $G_{N,w}$ has a path $(q_s, 1) \rightsquigarrow (q_a, n)$, call it $\hat{\pi}$. Scan $\hat{\pi}$ and replace every subpath of the form $(p, 1) \rightsquigarrow (q, 2)$ over $\vdash w_1$ or of the form $(p, n) \rightsquigarrow (q, n-1)$ over $w_n \dashv$ with the corresponding edge $(p, 1) \rightarrow (q, 2)$ or $(p, n) \rightarrow (q, n-1)$, respectively, given by the definition of $G'_{N,w}$. Clearly, the resulting path π' is a path $(q_s, 1) \rightsquigarrow (q_a, n)$ in $G'_{N,w}$.

Conversely, suppose $G'_{N,w}$ has a path $(q_s, 1) \rightsquigarrow (q_a, n)$, call it π' . Scan π' and replace every edge $(p, 1) \rightarrow (q, 2)$ or $(p, n) \rightarrow (q, n-1)$ which is not also in $G_{N,w}$ with the corresponding subpath $(p, 1) \rightsquigarrow (q, 2)$ over $\vdash w_1$ or $(p, n) \rightsquigarrow (q, n-1)$ over $w_n \dashv$, respectively, which justifies its presence in $G'_{N,w}$. Clearly, the result is a path $(q_s, 1) \rightsquigarrow (q_a, n)$ in $G_{N,w}$, call it $\hat{\pi}$. Now, prepend to $\hat{\pi}$ the step $(q_s, 0) \rightarrow (q_s, 1)$ and append the steps $(q_a, n) \rightarrow (q_a, n+1) \rightarrow (q_a, n+2)$, given by Def. 1. The resulting path π is a path $(q_s, 0) \rightsquigarrow (q_a, n+2)$ in $G_{N,w}$. Hence, N accepts w . \square

2.2. Logical formulas

In *quantifier-free first-order logic with successor and constants* over alphabet Σ ($\text{Q-FO}_{\Sigma}^{\pm}[\text{S}, \mathbb{Z}^*]$), formulas are built out of first-order *variables* x_0, x_1, \dots , *constants* $\pm 1, \pm 2, \dots \in \mathbb{Z}^{\pm}$, one *cell* predicate $\alpha(\cdot)$ for each $\alpha \subseteq \Sigma$, the *equality* predicate $\cdot = \cdot$, the *successor* predicate $\text{S}(\cdot, \cdot)$, and the connectives \neg, \wedge, \vee . A formula φ is either an *atom*, of the form $\alpha(t)$, $t = t'$, or $\text{S}(t, t')$, where each of the *terms* t, t' is either a variable or a constant; or *compound*, of the form $\neg\phi$, $\phi \wedge \psi$, or $\phi \vee \psi$, where ϕ, ψ are simpler formulas. An atom is either *local*, of the form $\alpha(t)$; or *relational*, of the form $t = t'$ or $\text{S}(t, t')$. An atom or negation of atom is a *literal*. A conjunction (resp., disjunction) of literals is an \wedge -*clause* (resp., an \vee -*clause*); a disjunction (resp., conjunction) of $\leq m$ such clauses is an m -*clause disjunctive normal form*, or m -DNF (resp., an m -*clause conjunctive normal form*, or m -CNF). A formula is *non-trivial* if it is not identically true or identically false.

The *length* $|\varphi|$ of a formula φ is the number of occurrences of symbols in it, ignoring punctuation and counting each variable, constant, and cell predicate as a single symbol. More carefully, we define $|\varphi|$ by structural induction on φ :

- for all α, t, t' : $|\alpha(t)| = 2$ and $|t = t'| = |\text{S}(t, t')| = 3$;
- for all ϕ, ψ : $|\neg\phi| = 1 + |\phi|$ and $|\phi \wedge \psi| = |\phi \vee \psi| = |\phi| + 1 + |\psi|$.

The *margin* of φ is the maximum absolute value of a constant in it; or 0, if φ has no constants. We write $\varphi(x_2, x_5, \dots)$ to indicate that all variables appearing in φ are among x_2, x_5, \dots (note that all variables are free, as there are no quantifiers).

Remark 3. Note that $|\varphi|$ may be smaller than the length of a *binary encoding* of φ , or '*bit-length*' of φ ', where each variable x_i counts for $\lceil \log \iota \rceil$, where ι the greatest index of a variable in φ ; each constant c counts for $\lceil \lg(2\tau) \rceil$, where τ the largest absolute value of a constant in φ ; and each cell predicate α counts for $\sigma := |\Sigma|$.

We opt for 'length', over 'bit-length', for three reasons. First, measuring variables and constants as in bit-length can increase our measurements only by a logarithmic

\perp	a
x_1	1
x_2	0

(a)

	1	2	3	4	5
\perp	a	a	b	a	b
x_1	1	0	0	0	0
x_2	0	0	1	0	0

(b)

	1	2	3	4	5
\perp	a	a	b	a	b
x_1	1	0	0	0	0
x_2	0	0	1	0	0
x_5	0	1	0	0	0

(c)

Figure 2. (a) A column from $\Sigma|V$, for $\Sigma = \{a,b\}$, $V = \{x_1, x_2\}$. (b) A well-formed \hat{w} over $\Sigma|V$; here, $\hat{w}(\perp) = \mathbf{a a b a b}$, $\hat{w}(x_2) = 3$, $\hat{w}(+1) = 1$, $\hat{w}(-1) = 5$. (c) The word $\hat{w}[x_5/2]$.

factor, which is insignificant in our context —so, in this respect, length is preferable just for simplicity. Second, our theorem takes constants into account explicitly —so, again, simplicity makes length preferable. Finally, measuring each cell predicate as 1 is in line with our measuring automata size by number of states (as opposed to bits in a binary encoding), which again ignores the contribution of alphabet size —so, in this respect, length is necessary for consistency in comparing with automata.

2.2.1. Semantics.

For a set of variables V , let $\Sigma|V$ be the alphabet of all functions $u : \{\perp\} \cup V \rightarrow \Sigma \cup \{0,1\}$ which map \perp into Σ and variables into $\{0,1\}$ (namely, $u(\perp) \in \Sigma$ and $u(x_i) \in \{0,1\}$ for all $x_i \in V$). Intuitively, every such u is a column of $1+|V|$ cells, labelled by the elements of $\{\perp\} \cup V$ and filled by the respective values of u (Fig. 2a). Likewise, each word $\hat{w} = \hat{w}_1 \cdots \hat{w}_n \in (\Sigma|V)^*$ is a table of n columns and $1+|V|$ rows: one row is labelled by \perp and hosts an n -long word over Σ ; the rest are labelled by variables and host n -long bitstrings (Fig. 2b).

We say \hat{w} is *well-formed* if $n \geq 2$ and the row of each variable hosts exactly one 1 (Fig. 2b). Then, $\hat{w}(\perp)$ is the word $\hat{w}_1(\perp) \cdots \hat{w}_n(\perp) \in \Sigma^*$ hosted in the \perp -row; $\hat{w}(x_i)$ is the index x of the one column \hat{w}_x which has a 1 in the x_i -row; and, for $c \in \mathbb{Z}^\pm$, $\hat{w}(c)$ is the index c of the c -th leftmost column, if $c > 0$, or the index $n-|c|+1$ of the $|c|$ -th rightmost column, if $c < 0$. Moreover, for any $x_i \notin V$ and index $x \in \mathbb{Z}_n^+$, $\hat{w}[x_i/x]$ is the well-formed word over $\Sigma|(V \cup \{x_i\})$ derived from \hat{w} by adding a row labelled x_i with its x -th bit 1 and all others 0 (Fig. 2c).

Now, given a n -long well-formed \hat{w} over $\Sigma|V$ and a formula φ whose variables are all in V , we say \hat{w} *satisfies* φ and write $\hat{w} \models \varphi$, if what φ ‘says’ about $\hat{w}(\perp)$ is true when each variable x_i is interpreted as in the x_i -row, namely iff:

$$\begin{array}{ll}
 \text{for } \varphi \equiv \alpha(t) : & \hat{w}(\perp)_{\hat{w}(t)} \in \alpha & \text{for } \varphi \equiv \neg\phi : & \hat{w} \not\models \phi \\
 \text{for } \varphi \equiv t=t' : & \hat{w}(t) = \hat{w}(t') & \text{for } \varphi \equiv \phi \wedge \psi : & \hat{w} \models \phi \text{ and } \hat{w} \models \psi \\
 \text{for } \varphi \equiv S(t, t') : & \hat{w}(t) + 1 = \hat{w}(t') & \text{for } \varphi \equiv \phi \vee \psi : & \hat{w} \models \phi \text{ or } \hat{w} \models \psi.
 \end{array}$$

2.2.2. Transitive closure.

Let $\varphi(\bar{x}, \bar{y})$ be a $\text{Q-FO}_{\Sigma}^+[\mathbb{S}, \mathbb{Z}^*]$ formula over $2k+2$ variables $\bar{x} = x_0, \dots, x_k$ and $\bar{y} = y_0, \dots, y_k$. Given an n -long $w \in \Sigma^*$, this defines a binary relation R_φ on

$k+1$ -tuples of indices in \mathbb{Z}_n^+ . As usual, the *transitive closure* of R_φ is the binary relation R_φ^* which contains a pair (\bar{u}, \bar{v}) iff there is a sequence of tuples $\bar{r}_0, \bar{r}_1, \dots, \bar{r}_\ell$ such that $\bar{u} = \bar{r}_0$; every $(\bar{r}_i, \bar{r}_{i+1})$ is in R_φ ; and $\bar{r}_\ell = \bar{v}$.

We augment our logic with the *transitive closure* operator ‘TC’, which checks if two tuples of indices are in the relation R_φ^* defined by some $\varphi(\bar{x}, \bar{y})$: given φ and two tuples of terms \bar{t}, \bar{t}' , the formula $\text{TC}_\varphi(\bar{t}, \bar{t}')$ (or, more legibly, $\text{TC}[\varphi(\bar{x}, \bar{y})](\bar{t}, \bar{t}')$) has length $1+|\varphi|+2k+2$ and the following semantics, for all well-formed \hat{w} :

$$\hat{w} \models \text{TC}_\varphi(\bar{t}, \bar{t}') \quad \text{iff} \quad ((\hat{w}(t_0), \dots, \hat{w}(t_k)), (\hat{w}(t'_0), \dots, \hat{w}(t'_k))) \in R_\varphi^*.$$

Intuitively, let $G_{\varphi, \hat{w}}$ be the directed graph with vertex set $(\mathbb{Z}_n^+)^{k+1}$ and all edges (\bar{u}, \bar{v}) such that $\hat{w}[\bar{x}/\bar{u}, \bar{y}/\bar{v}] \models \varphi(\bar{x}, \bar{y})$; then $\hat{w} \models \text{TC}_\varphi(\bar{t}, \bar{t}')$ iff $G_{\varphi, \hat{w}}$ has a path $(\hat{w}(t_0), \dots, \hat{w}(t_k)) \rightsquigarrow (\hat{w}(t'_0), \dots, \hat{w}(t'_k))$. We call this new logic $\text{Q}\cdot\text{FO}_\Sigma^+[\mathbb{S}, \mathbb{Z}^*]+\text{TC}$.

2.3. Finite automata versus logical formulas

A (*promise*) *problem* over alphabet Σ is any pair $\mathfrak{L} = (L, \tilde{L})$ of disjoint subsets of Σ^* .^a An automaton N *solves* \mathfrak{L} if it accepts all $w \in L$ but no $w \in \tilde{L}$. A formula φ *solves* \mathfrak{L} if it is satisfied by all $w \in L$ but no $w \in \tilde{L}$.

A family of automata $\mathcal{N} = (N_h)_{h \geq 1}$ (resp., of formulas $\mathcal{F} = (\varphi_h)_{h \geq 1}$) *solves* a family of problems $(\mathfrak{L}_h)_{h \geq 1}$ if every N_h (resp., φ_h) solves the respective \mathfrak{L}_h . The automata of \mathcal{N} (resp., the formulas of \mathcal{F}) are *small* if every N_h has $\leq p(h)$ states (resp., every φ_h has length $\leq p(h)$), for some polynomial p . Therefore, the set

$$2\text{N} := \left\{ (\mathfrak{L}_h)_{h \geq 1} \mid \begin{array}{l} \text{there exist 2NFAS } (N_h)_{h \geq 1} \text{ and a polynomial } p \\ \text{such that every } N_h \text{ solves } \mathfrak{L}_h \text{ with } \leq p(h) \text{ states} \end{array} \right\}$$

is the class of problem families which are solvable by families of small 2NFAS.^b

A formula $\varphi(\bar{x})$ of $\text{Q}\cdot\text{FO}_\Sigma^+[\mathbb{S}, \mathbb{Z}^*]+\text{TC}$ is *equivalent* to a 2NFA N over $\Sigma|\bar{x}$ if for all well-formed $\hat{w} \in (\Sigma|\bar{x})^*$: \hat{w} satisfies φ iff N accepts \hat{w} (note that $|\hat{w}| \geq 2$).

3. Graph-Accessibility Sentences and Our Theorem

A formula of $\text{Q}\cdot\text{FO}_\Sigma^+[\mathbb{S}, \mathbb{Z}^*]$ is *local*, if all its atoms are local (i.e., it talks only about the contents of certain cells); *quasi-local*, if every relational atom in it uses at least one constant (i.e., it talks only about certain cells’ contents and distance from the end-markers); and *relational*, if all its atoms are relational (i.e., it talks only about the order of certain cells). Orthogonally, the formula is *floating*, if all its terms are variables; *quasi-floating*, if every atom uses at least one variable; and *anchored*, if all its terms are constants. Finally, inside an \wedge -clause, a variable x is *anchored* if it appears in at least one literal of the form $x = c$ or $c = x$ (without negation), for some constant c ; otherwise, it is *floating*.

^aIf $\tilde{L} = \bar{L}$, then \mathfrak{L} is a *language*.

^bElsewhere, this is defined as a class of families of *languages*, as opposed to promise problems. For our purposes, this difference is not important.

Given a $\text{Q-FO}_{\Sigma}^+[\text{S}, \mathbb{Z}^*]$ formula $\varphi(\bar{x}, \bar{y})$ with $\bar{x} = x_0, \dots, x_k$ and $\bar{y} = y_0, \dots, y_k$, a *graph-accessibility sentence* (GAS) with *core* φ and *arity* $k+1$ is any formula

$$\text{TC}[\varphi(\bar{x}, \bar{y})](\bar{s}, \bar{t}) \quad (2)$$

where $\bar{s} = s_0, \dots, s_k$ and $\bar{t} = t_0, \dots, t_k$ are constants. If φ is a DNF, namely $\varphi(\bar{x}, \bar{y}) \equiv \bigvee_{i=1}^m \varphi_i(\bar{x}, \bar{y})$ where each φ_i is an \wedge -clause and the *degree* m is ≥ 1 , we say (2) is a GA/DNF. If x_1, \dots, x_k and y_1, \dots, y_k are all anchored in every φ_i (so that only x_0, y_0 may be floating), we say (2) is *one-dimensional* (GA/DNF₁). Finally, we say (2) is *weak* if no φ_i contains both anchored local atoms and floating relational ones.

Our theorem states that 2NFAs of polynomial size are as powerful as weak GA/DNF₁s of polynomial degree and margin; and that this holds already when the margin is 1 and we also require polynomial length and logarithmic arity.

Theorem 4. *The following are equivalent, for every family of problems \mathcal{L} :*

1. \mathcal{L} has small 2NFAs.
2. \mathcal{L} has small weak GA/DNF₁s of small degree, margin 1, logarithmic arity.
3. \mathcal{L} has weak GA/DNF₁s of small degree, small margin.

Proof. The implication [(2) \Rightarrow (3)] is trivial. For the other two, let $\mathcal{L} = (\mathfrak{L}_h)_{h \geq 1}$.

[(1) \Rightarrow (2)] Suppose some family $(N_h)_{h \geq 1}$ of 2NFAs and a polynomial p are such that every N_h solves \mathfrak{L}_h with $s_h \leq p(h)$ states. By Lemma 5, N_h is equivalent to a weak GA/DNF₁ φ_h of margin 1, arity $O(\log s_h) = O(\log p(h)) = O(\log h)$, degree $O(s_h^2) = O(p(h)^2) \leq q(h)$, and length $O(s_h^2 \log s_h) = O(p(h)^2 \log p(h)) \leq q(h)$, where q any large enough polynomial. So, $(\varphi_h)_{h \geq 1}$ is a family of small weak GA/DNF₁s of polynomial degree, margin 1, and logarithmic arity that solves \mathcal{L} .

[(3) \Rightarrow (1)] Suppose a family $(\varphi_h)_{h \geq 1}$ of weak GA/DNF₁s and a polynomial p are such that every φ_h solves \mathfrak{L}_h with degree $m_h \leq p(h)$ and margin $\tau_h \leq p(h)$. By Lemma 13, φ_h is equivalent to a 2NFA N_h with $O(m_h \tau_h) = O(p(h)^2) \leq q(h)$ states, where q any large enough polynomial. So, the small 2NFAs $(N_h)_{h \geq 1}$ solve \mathcal{L} . \square

4. From Automata to Formulas

The simpler conversion, from automata to formulas, is treated in the next lemma.

Lemma 5. *Every s -state 2NFA is equivalent to a weak GA/DNF₁ of degree $O(s^2)$, margin 1, arity $O(\log s)$ and length $O(s^2 \log s)$.*

Proof. Pick any s -state 2NFA N . We first switch to an equivalent 2NFA \tilde{N} which is in INF (Def. 1) and its number of states \tilde{s} is a power of 2 not exceeding $2s+2$, i.e., $\tilde{s} = 2^r \leq 2s+2$ for some r . For this, we first apply Fact 2i to derive a 2NFA N' in INF which is equivalent to N and has $s' = s+2$ states. If s' is a power of 2, then we are done: we let $\tilde{N} := N'$ and have $\tilde{s} = s' = s+2 \leq 2s+2$. If not, then there exists r such that $2^{r-1} < s' < 2^r$; so, we let \tilde{N} be the 2NFA derived from N' when we add $2^r - s'$ dummy states. Easily, \tilde{N} is also equivalent to N and has size $\tilde{s} = s' + (2^r - s') = 2^r = 2 \cdot 2^{r-1} \leq 2(s'-1) \leq 2(s+2-1) = 2(s+1)$, so again $\tilde{s} \leq 2s+2$.

Now, for simplicity, we rename the states of \tilde{N} so that $\tilde{N} = ([\tilde{s}], \Sigma, \tilde{\delta}, 0, \tilde{s}-1)$.

We need a weak GA/DNF₁ TC $[\varphi(\bar{x}, \bar{y})](\bar{s}, \bar{t})$ such that, for all w of length $n \geq 2$:

$$\tilde{N} \text{ accepts } w \iff w \models \text{TC}[\varphi(\bar{x}, \bar{y})](\bar{s}, \bar{t}). \quad (3)$$

By definition, the right-hand side holds iff the graph $G_{\varphi, w}$ induced by φ (cf. p. 6) has a path $(s_0, s_1, \dots, s_k) \rightsquigarrow (t_0, t_1, \dots, t_k)$, where $k+1$ the arity of φ . By Fact 2ii, the left-hand side holds iff the inner configuration graph $G'_{\tilde{N}, w}$ induced by \tilde{N} has a path $(0, 1) \rightsquigarrow (\tilde{s}-1, n)$. So, we simply need to pick φ so that $G_{\varphi, w}$ is actually $G'_{\tilde{N}, w}$, and then pick \bar{s}, \bar{t} so that they are actually $(0, 1)$ and $(\tilde{s}-1, n)$.

First, we must represent each vertex of $G'_{\tilde{N}, w}$, namely each inner configuration $(p, x) \in [\tilde{s}] \times \mathbb{Z}_n^+$, as a vertex of $G_{\varphi, w}$, namely a tuple $\bar{u} = (u_0, u_1, \dots, u_k)$ of indices from \mathbb{Z}_n^+ . Of course, x can be represented by any component of \bar{u} , say u_0 . As for p , we represent it in ‘binary’ using the other components u_1, \dots, u_k : we pick $k := r = \lg \tilde{s}$ (to ensure we have enough ‘bits’) and use indices 1 and n (which are distinct, as $n \geq 2$) as 0 and 1, respectively. E.g., if $\tilde{s} = 16$ (so, $k = 4$) and $n = 50$, then the configuration $(p, x) = (2, 22)$ maps to $\bar{u} = (22, 1, 1, 50, 1)$. Note that $(0, 1)$ and $(\tilde{s}-1, n)$ map to $(1, 1, \dots, 1)$ and (n, n, \dots, n) , i.e., to the interpretations of the tuples of constants $(+1, +1, \dots, +1)$ and $(-1, -1, \dots, -1)$.

Given this representation, we now need a $\varphi(\bar{x}, \bar{y})$ which states that the edge (\bar{x}, \bar{y}) exists in $G'_{\tilde{N}, w}$, namely that \tilde{N} can switch in a single inner step from the inner configuration (x_0, x_1, \dots, x_k) to the inner configuration (y_0, y_1, \dots, y_k) .

As a start, for every state $p \in [\tilde{s}]$ we need a formula $\xi_p(\bar{u})$ which says that the state of the inner configuration (u_0, u_1, \dots, u_k) is p . E.g., if $n = 50$ and $p = 2$ as above, then $w \models \xi_p(\bar{u})$ should hold iff \bar{u} is of the form $(\cdot, 1, 1, 50, 1)$, and thus $\xi_p(\bar{u})$ should be $u_1 = +1 \wedge u_2 = +1 \wedge u_3 = -1 \wedge u_4 = +1$. In general, we let

$$\xi_p(\bar{u}) := \bigwedge_{i=1}^k (u_i = p_i), \quad (4)$$

where each p_i is either $+1$ or -1 depending on whether the i -th most significant bit in the k -bit binary representation of p is 0 or 1.

Additionally, for every two states $p, q \in [\tilde{s}]$ and each direction of head motion, we need the set of symbols which allow the corresponding transition:

$$\alpha_{p,q}^L := \{a \in \Sigma \mid (p, a, q, L) \in \tilde{\delta}\}, \quad \alpha_{p,q}^R := \{a \in \Sigma \mid (p, a, q, R) \in \tilde{\delta}\}. \quad (5)$$

Similarly, for every two states $p, q \in [\tilde{s}]$ and each end-marker, we need the set of symbols which, together with the end-marker, allow the corresponding U-turn:

$$\begin{aligned} \alpha_{p,q}^+ &:= \{a \in \Sigma \mid \text{computing on } \vdash a \text{ from } p \text{ on } a, \tilde{N} \text{ can exit right into } q\}, \\ \alpha_{p,q}^- &:= \{a \in \Sigma \mid \text{computing on } a \dashv \text{ from } p \text{ on } a, \tilde{N} \text{ can exit left into } q\}. \end{aligned} \quad (6)$$

Using the \wedge -clauses of (4) and the cell predicates for the sets of (5) and (6), we now build a formula $\varphi(\bar{x}, \bar{y})$ which says that, in a single inner step, \tilde{N} can switch

from cell x_0 and ‘state’ (x_1, \dots, x_k) to cell y_0 and ‘state’ (y_1, \dots, y_k) :

$$\varphi(\bar{x}, \bar{y}) := \bigvee_{p, q \in [\bar{s}]} \left\{ \begin{array}{l} [\xi_p(\bar{x}) \wedge \xi_q(\bar{y}) \wedge \mathbf{S}(x_0, y_0) \wedge \alpha_{p,q}^R(x_0)] \quad (7) \\ \vee [\xi_p(\bar{x}) \wedge \xi_q(\bar{y}) \wedge \mathbf{S}(y_0, x_0) \wedge \alpha_{p,q}^L(x_0)] \quad (8) \\ \vee [\xi_p(\bar{x}) \wedge \xi_q(\bar{y}) \wedge x_0 = +1 \wedge \mathbf{S}(x_0, y_0) \wedge \alpha_{p,q}^+(x_0)] \quad (9) \\ \vee [\xi_p(\bar{x}) \wedge \xi_q(\bar{y}) \wedge x_0 = -1 \wedge \mathbf{S}(y_0, x_0) \wedge \alpha_{p,q}^-(x_0)] \quad (10) \end{array} \right\}$$

Intuitively, φ says that there exist states p, q such that the state of inner configuration \bar{x} is p , the state of inner configuration \bar{y} is q , and: \bar{y} is exactly to the right of \bar{x} , and the symbol read in \bar{x} allows a right-moving transition $p \rightarrow q$ (line (7)); or \bar{y} is exactly to the left of \bar{x} , and the symbol read in \bar{x} allows a left-moving transition $p \rightarrow q$ (line (8)); or \bar{x}, \bar{y} are on cells 1, 2 and the symbol read in \bar{x} together with \vdash allows a left U-turn from p to q (line (9)); or \bar{y}, \bar{x} are on cells $n-1, n$ and the symbol read in \bar{x} together with \dashv allows a right U-turn from p to q (line (10)).

Overall, our GAS is that of (3) with φ as in (7)–(10) and $\bar{s} = (+1, \dots, +1)$ and $\bar{t} = (-1, \dots, -1)$. As promised, the *margin* is 1 (all constants are ± 1) and the *arity* is $k+1 = O(\log s)$. Also, each bracket in (7)–(10) is an \wedge -clause of length $O(\log s)$, as the conjunction of two \wedge -clauses of length $O(k) = O(\log s)$ and two or three atoms of length $O(1)$; hence, φ is a disjunction of $4\bar{s}^2 = O(s^2)$ \wedge -clauses, of total length $O(s^2 \log s)$; and thus our GAS in (3) is a GA/DNF of *degree* $O(s^2)$ and *length* $O(s^2 \log s)$, too. Finally, each bracket in (7)–(10) anchors each one of x_1, \dots, x_k and y_1, \dots, y_k (inside ξ_p and ξ_q) and contains no anchored local atoms, making our GAS in (3) both *one-dimensional* and *weak*, as promised. \square

5. From Formulas to Automata

We now show how to convert a weak GA/DNF₁ to a 2NFA. Facts 6–11 analyze the structure of the given sentence and its sub-formulas; their proofs are straightforward and mostly syntactic. Lemmas 8–12 build two-way automata which simulate those sub-formulas. The final 2NFA for the given sentence is built in Lemma 13.

Fact 6. *Let $\varphi(\bar{x}, \bar{y}) = \bigvee_{i=1}^m \varphi_i(\bar{x}, \bar{y})$ be the core of a GA/DNF₁ of arity $k+1$. Then every \wedge -clause $\varphi_i(\bar{x}, \bar{y})$ is equivalent to an \wedge -clause of the form*

$$(x_1 = c_1) \wedge \dots \wedge (x_k = c_k) \wedge (y_1 = d_1) \wedge \dots \wedge (y_k = d_k) \wedge \hat{\varphi}(x_0, y_0),$$

for some constants $c_1, \dots, c_k, d_1, \dots, d_k$ and some \wedge -clause $\hat{\varphi}(x_0, y_0)$.

Proof. Pick any φ_i . By one-dimensionality, x_1 is anchored in φ_i , so at least one literal is of the form $x_1 = c_1$ or $c_1 = x_1$, for some constant c_1 . Consider the following modifications: (1) if the literal is $c_1 = x_1$, change it to $x_1 = c_1$; (2) bring the literal upfront; (3) replace any other occurrence of x_1 with c_1 . Easily, this brings φ_i into the equivalent form $(x_1 = c_1) \wedge \vartheta_1(x_0, x_2, x_3, \dots, x_k, \bar{y})$. Similarly, x_2 is also anchored in φ_i , so by repeating modifications (1)–(3) for it, we bring φ_i to the equivalent form

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$(x_1 = c_1) \wedge (x_2 = c_2) \wedge \vartheta_2(x_0, x_3, x_4, \dots, x_k, \bar{y})$. Continuing like this for all anchored variables, we eventually get the desired equivalent form $(x_1 = c_1) \wedge \dots \wedge (x_k = c_k) \wedge (y_1 = d_1) \wedge \dots \wedge (y_k = d_k) \wedge \vartheta_{2k}(x_0, y_0)$. \square

Fact 7. *Every non-trivial \wedge -clause $\varphi(x, y)$ is equivalent to a formula of the form $\phi \wedge \chi(x) \wedge \psi(y) \wedge \omega(x, y)$, where each of ϕ, χ, ψ, ω is an \wedge -clause; ϕ is anchored local; χ, ψ are quasi-floating quasi-local; and ω is floating relational.*

Proof. We simply rearrange the literals of φ based on which variables they use:

If they use both variables, we push them back into a sub-clause $\omega(x, y)$. Clearly, every such literal is relational and floating, so ω is also floating relational.

If they use neither variable, then we pull them forward into a sub-clause ϕ . Clearly, ϕ is anchored. But we may also assume that it is local: Indeed, any non-local literal in ϕ is of the form $c = c', \mathbf{S}(c, c'), \neg(c = c')$, or $\neg\mathbf{S}(c, c')$, for some constants c, c' , and thus trivial, namely always true or always false. We know it cannot be the latter, because then the entire φ would be false, and thus trivial, which is a contradiction. So, every non-local literal in ϕ is necessarily always true, and thus can be dropped from the conjunction altogether.

If they use only x , then we group them into a sub-clause $\chi(x)$. Clearly, χ is quasi-floating. But we may also assume that it is quasi-local: Indeed, the only way for χ not to be so is to contain one of $x = x, \mathbf{S}(x, x), \neg(x = x)$, or $\neg\mathbf{S}(x, x)$. But each of these literals is trivial and thus, as before, either impossible (if always false, since it would make φ trivial, which is a contradiction) or redundant (if always true).

If they use only y , then we collect them into a sub-clause $\psi(y)$ which is again quasi-floating quasi-local (by the same analysis as for χ). \square

Lemma 8. *Suppose φ is an anchored local \wedge -clause of margin τ . Then there exists a $O(\tau)$ -state 2DFA which, whenever run on a string w from the cell of \vdash , returns on that same cell and accepts iff $w \models \varphi$.*

Proof. Formula φ is a conjunction of literals of the form $\alpha(c)$ and $\neg\alpha(c)$, where $\alpha \subseteq \Sigma$ and $c \in \mathbb{Z}_\tau^+ \cup \mathbb{Z}_\tau^-$. We may assume that every such c appears in exactly one literal of the form $\alpha(c)$: Indeed, if it appears in none, then we add the true literal $\Sigma(c)$; if it appears in exactly one, but of the form $\neg\gamma(c)$, then we replace this with the equivalent $\bar{\gamma}(c)$; if it appears in more than one, then we replace the conjunction $\beta_1(c) \wedge \dots \wedge \beta_r(c) \wedge \neg\gamma_1(c) \wedge \dots \wedge \neg\gamma_s(c)$ of these literals with the equivalent single literal $\alpha(c)$ where $\alpha := \beta_1 \cap \dots \cap \beta_r \cap \bar{\gamma}_1 \cap \dots \cap \bar{\gamma}_s$.

So, φ is essentially a list of 2τ conditions, one for each of the τ leftmost and the τ rightmost cells of w , and $w \models \varphi$ iff all are true. To test this, a 2DFA M starting from \vdash scans the leftmost cells, counting up to τ and confirming all respective conditions; then sweeps to \dashv ; then scans the rightmost cells backwards, again counting up to τ and confirming all respective conditions; then sweeps to \vdash and accepts—if any condition fails or any cell does not exist (because w is too short), then M rejects. Easily, this can be implemented with $O(\tau)$ states. \square

Fact 9. *Every quasi-local formula is equivalent to a formula in which every atom is of the form $\alpha(\cdot)$ or $x = c$, where $\alpha \subseteq \Sigma$, x is a variable, and c is a constant.*

Proof. Suppose φ is quasi-local. We just need to prove that every relational atom in it can be either replaced by an equivalent atom of the form $x = c$ or removed altogether. So, pick any such atom, $t = t'$ or $S(t, t')$. Since φ is quasi-local, at least one of t, t' is a constant, and thus the following list of cases is exhaustive:

- $x = c$: This is of a desired form, so we keep it.
- $c = x$: This we replace by the equivalent $x = c$.
- $S(x, c)$ for $c \neq +1$: This we replace by the equivalent $x = c - 1$.
- $S(c, x)$ for $c \neq -1$: This we replace by the equivalent $x = c + 1$.
- $c = c'$ or $S(c, c')$ or $S(x, +1)$ or $S(-1, x)$: Each of these is either always true or always false, so we remove it altogether and then simplify φ appropriately.

After all replacements, every atom is indeed of the form $\alpha(\cdot)$ or $x = c$. \square

Lemma 10. *Suppose $\varphi(x)$ is a quasi-floating quasi-local \wedge -clause of margin τ . Then there exists a $O(\tau)$ -state 2DFA which, whenever run on a string w from a cell $1 \leq x^* \leq |w|$, returns on that same cell and accepts iff $w[x/x^*] \models \varphi(x)$.*

Proof. By Fact 9, by the margin τ , and since φ is quasi-floating with x as the only variable, we may assume that every atom is of the form $\alpha(x)$ or $x = c$, where $\alpha \subseteq \Sigma$ and $c \in \mathbb{Z}_\tau^+ \cup \mathbb{Z}_\tau^-$.

So, each literal has the form $\alpha(x)$, $\neg\alpha(x)$, $x = c$, or $\neg(x = c)$, for some α and c . As in the proof of Lemma 8, we may assume the first two forms contribute exactly one literal: the literal $\alpha(x)$, for α the intersection of Σ , of all β from occurring literals $\beta(x)$, and of all $\bar{\gamma}$ from occurring literals $\neg\gamma(x)$. We may also assume that the third form contributes at most one literal for collectively all $c > 0$ and at most one literal for collectively all $c < 0$: if there are two literals $x = c_1, x = c_2$ for distinct $c_1, c_2 > 0$, then φ is always false, and thus the 2DFA is just the trivial one which simply halts and rejects —similarly for $c_1, c_2 < 0$.

Overall, without loss of generality, we may assume that $\varphi(x)$ consists of: exactly one $\alpha(x)$ for $\alpha \subseteq \Sigma$; an optional $x = c$ for $c \in \mathbb{Z}_\tau^+$; an optional $x = c$ for $c \in \mathbb{Z}_\tau^-$; and zero or more $\neg(x = c)$ for $c \in \mathbb{Z}_\tau^+ \cup \mathbb{Z}_\tau^-$.

To test $w[x/x^*] \models \varphi$, a 2DFA run on w from cell x^* first verifies $\alpha(x)$ by testing that $w_{x^*} \in \alpha$. It then scans left counting down from τ , until its counter is 0 or it sees \vdash (whichever happens first), and then returns to cell x^* ; during this trip, it tests the optional $x = c$ and the zero or more $\neg(x = c)$ for $c > 0$. It then performs a symmetric trip of $\leq \tau$ steps to the right of cell x^* and back, during which it tests the optional $x = c$ and the zero or more $\neg(x = c)$ for $c < 0$. Finally, it accepts if all tests succeeded. Easily, $O(\tau)$ states are enough. \square

Fact 11. *Every not-identically-false floating relational \wedge -clause $\varphi(x, y)$ is equivalent to $S(x, y)$, $x = y$, $S(y, x)$, or a conjunction of $\neg S(x, y)$, $\neg(x = y)$, $\neg S(y, x)$.*

Proof. We know φ is an \wedge -clause where no constants occur (‘floating’); x, y are the only variables (notation ‘ $\varphi(x, y)$ ’); and every atom is of type $. = .$ or $\mathsf{S}(. , .)$ (‘relational’). Hence, φ is simply some conjunction of $x = x$, $y = y$, $x = y$, $y = x$, $\mathsf{S}(x, x)$, $\mathsf{S}(y, y)$, $\mathsf{S}(x, y)$, $\mathsf{S}(y, x)$, and their negations. However:

- If an atom is $y = x$: Then it can be replaced by the equivalent $x = y$.
- If an atom is $x = x$ or $y = y$: Then it is always true. So, the respective literal is either always true (if positive) or always false (if negative). But the latter is impossible, as then φ would be identically false — a contradiction. So, the literal is always true, and thus can be dropped from φ altogether.
- If an atom is $\mathsf{S}(x, x)$ or $\mathsf{S}(y, y)$: Then it is always false. So, as before, the respective literal is negative and always true (it cannot be positive and always false, because then φ would be identically false — a contradiction), and thus can be dropped from φ altogether.

Hence, without loss of generality, we can assume that φ is some conjunction of $\mathsf{S}(x, y)$, $x = y$, $\mathsf{S}(y, x)$, and their negations. Now:

- If the literal $\mathsf{S}(x, y)$ is present: Then the literals $\neg\mathsf{S}(x, y)$, $x = y$, $\mathsf{S}(y, x)$ cannot be present, as then φ would be identically false — a contradiction. Moreover, the literals $\neg(x = y)$ and $\neg\mathsf{S}(y, x)$ can be dropped, since they are always true in the presence of $\mathsf{S}(x, y)$.
- If the literal $x = y$ is present: Then, similarly, the literals $\mathsf{S}(x, y)$, $\neg(x = y)$, $\mathsf{S}(y, x)$ cannot be present (as then φ would be identically false — a contradiction) and the literals $\neg\mathsf{S}(x, y)$ and $\neg\mathsf{S}(y, x)$ can be dropped (as always true in the presence of $x = y$).
- If the literal $\mathsf{S}(y, x)$ is present: Then, as above, each of the other five literals is again either absent (as φ is not identically false) or redundant (as true).
- Otherwise: Then the only present literals are $\neg\mathsf{S}(x, y)$, $\neg(x = y)$, $\neg\mathsf{S}(y, x)$.

Overall, we see that φ is indeed equivalent to either a single positive literal from $\mathsf{S}(x, y)$, $x = y$, and $\mathsf{S}(y, x)$, or a conjunction of their negations. \square

Lemma 12. *Suppose $\varphi(x, y)$ is an \wedge -clause of margin τ which does not contain both anchored local and floating relational atoms. Then there exists a $O(\tau)$ -state 2NFA which, whenever run on a string w from a cell $1 \leq x^* \leq |w|$, computes so that, for all $1 \leq y^* \leq |w|$:*

$$\begin{array}{l} \text{a computation path which} \\ \text{halts } \& \text{ accepts on cell } y^* \text{ exists} \end{array} \iff w[x/x^*, y/y^*] \models \varphi(x, y). \quad (11)$$

Proof. If φ is trivial, then the 2NFA is also trivial: If $\varphi(x, y)$ is identically false, then our 2NFA is simply the one which immediately halts and rejects. If $\varphi(x, y)$ is identically true, then our 2NFA is the one which first resets its head to \vdash , then sweeps the entire input and, on each cell, spawns a new branch which simply halts and accepts. Easily, in both cases, the 2NFA can be implemented with $O(1)$ states.

Now assume φ is non-trivial. Let $\phi, \chi(x), \psi(y), \omega(x, y)$ be the \wedge -clauses by Fact 7. Then ϕ or ω is empty, as anchored local and floating relational atoms do not co-exist.

Case 1. Suppose ω is empty. Then, when run on w from cell x^* , our 2NFA N must create nondeterministic branches which collectively accept on every cell y^* such that $\phi \wedge \chi(x) \wedge \psi(y)$ holds if $x = x^*$ and $y = y^*$. For this, N first checks χ on cell x^* ; then resets its head (forgetting x^*) and reads the ends of w to check ϕ ; then sweeps w and, on every cell y^* , guesses and verifies that ψ is true on y^* .

Specifically, let Φ, X, Ψ be the $O(\tau)$ -state 2DFAs given by Lemma 8 for ϕ and by Lemma 10 for χ and ψ , respectively. Starting on cell x^* , N first simulates X . This brings it back to x^* having checked χ on x^* . Then N goes to \vdash and starts simulating Φ . This brings it back to \vdash having checked ϕ . Then N scans w and, on every cell y^* , spawns a new branch which simulates Ψ , eventually returning to y^* having checked ψ on y^* . Finally, N accepts (in that branch) iff all checks succeeded. Easily, N satisfies (11) and has size $O(|\Phi|+|X|+|\Psi|) = O(\tau)$.

Case 2. Suppose ϕ is empty. Then φ is equivalent to $\chi(x) \wedge \psi(y) \wedge \omega(x, y)$, where ω is not identically false (since φ is non-trivial), and thus is equivalent to one of $S(x, y)$, $x = y$, $S(y, x)$, or to a conjunction of their negations (Fact 11).

2a. If ω is equivalent to $S(x, y)$: Then the branches of N must collectively accept on every cell y^* such that $\chi(x) \wedge \psi(y) \wedge S(x, y)$ holds when $x = x^*$ and $y = y^*$. Because of $S(x, y)$, the only possible y^* of this kind is x^*+1 . So, N should just accept on cell x^*+1 iff $\chi(x) \wedge \psi(y)$ holds when $x = x^*$ and $y = x^*+1$. Hence, N starts on x^* by simulating X . This brings it back to x^* having checked χ on x^* . Then it moves one cell to the right, checks that it is not \neg , and starts simulating Ψ , eventually returning to the cell, having checked ψ on x^*+1 . In the end, N accepts iff all checks succeeded. Note that N is, in fact, deterministic.

2b. If ω is equivalent to $x = y$: Then φ is equivalent to $\chi(x) \wedge \psi(y) \wedge x = y$, so the only possible y^* is x^* . Hence, N works as in Case 2a, but without the one step to the right between the simulations of X and of Ψ .

2c. If ω is equivalent to $S(y, x)$: Then φ is equivalent to $\chi(x) \wedge \psi(y) \wedge S(y, x)$, so the only possible y^* is x^*-1 . So, N works as in Case 2a, except that, between the simulations of X and of Ψ , it moves left and checks that it does not read \vdash .

2d. If ω is equivalent to a conjunction of $\neg S(x, y)$, $\neg(x = y)$, $\neg S(y, x)$: Then ω excludes a certain set of cells $Y_\omega \subseteq \{x^*-1, x^*, x^*+1\}$ from being accepted. So, N must accept on cell y^* iff $\chi(x) \wedge \psi(y)$ holds for $x = x^*$, $y = y^*$ and $y^* \notin Y_\omega$. As above, N starts on x^* by simulating X , and returns on it after checking χ on x^* . Then it spawns five branches, one for each of the five cases as to where cell y^* is with respect to cell x^* : before x^*-1 , on x^*-1 , on x^* , on x^*+1 , or after x^*+1 .

- In the first branch: N moves left by two cells, checking that neither is \vdash . It then sweeps up to \vdash and, on each cell y^* , spawns a branch which simulates Ψ and eventually returns on y^* having checked ψ on it.
- In the second branch: If $x^*-1 \in Y_\omega$ (i.e., ω contains $\neg S(y, x)$), then N just rejects. Otherwise, it moves left once, checks that it is not on \vdash , then simulates Ψ . This brings it back to the same cell x^*-1 , having checked ψ on it.
- In the third and fourth branches: N works similarly to the second one.

It just rejects, if $x^* \in Y_\omega$ (i.e., ω contains $\neg(x=y)$) or if $x^*+1 \in Y_\omega$ (i.e., ω contains $\neg S(x,y)$), respectively. Otherwise, it simulates Ψ after, respectively, not moving at all or moving once to the right.

- In the last branch: N works symmetrically to the first one. It moves right by two cells checking against \neg , and then simulates Ψ on each cell before \neg .

In all cases, N accepts in a given branch iff all checks along it have succeeded.

Easily, in all four cases, N satisfies (11) and contains one copy of each of X and Ψ , plus $O(1)$ more states, for a total size of $O(|X|+|Y|) = O(\tau)$. \square

Lemma 13. *Every weak GA/DNF₁ of degree m and margin τ is equivalent to a 2NFA with $O(m\tau)$ states.*

Proof. Let $\psi = \text{TC}[\varphi(\bar{x}, \bar{y})](\bar{s}, \bar{t})$ be as in the statement. Let the arity be $k+1$. Then $s_0, \dots, s_k, t_0, \dots, t_k \in \mathbb{Z}_\tau^+ \cup \mathbb{Z}_\tau^-$ and the core φ has the form $\bigvee_{i=1}^m \varphi_i(\bar{x}, \bar{y})$, where (Fact 6) each φ_i is equivalent to:

$$(x_1 = c_1^i) \wedge \dots \wedge (x_k = c_k^i) \wedge (y_1 = d_1^i) \wedge \dots \wedge (y_k = d_k^i) \wedge \hat{\varphi}_i(x_0, y_0), \quad (12)$$

for some constants $c_1^i, \dots, c_k^i, d_1^i, \dots, d_k^i \in \mathbb{Z}_\tau^+ \cup \mathbb{Z}_\tau^-$ and an \wedge -clause $\hat{\varphi}_i$ of margin τ where anchored local and floating relational atoms do not co-exist (as ψ is weak).

We build a 2NFA N which accepts an input $w \in \Sigma^*$ of length $n \geq 2$ iff $w \models \psi$, i.e., iff the graph $G_{\varphi, w}$ (see p. 6) has a path from \bar{s} to \bar{t} . To check this, N nondeterministically guesses such a path *in stages*, in the standard way: starting each stage, it remembers only the last vertex \bar{u} of the path guessed so far (originally, $\bar{u} := \bar{s}$); then it checks whether $\bar{u} = \bar{t}$ and, if so, accepts; otherwise, it nondeterministically selects a neighbor \bar{v} of \bar{u} and updates its memory to $\bar{u} := \bar{v}$, completing the stage.

To implement this algorithm, N needs a way of remembering \bar{u} . Clearly, \bar{u} will always be a vertex reachable from \bar{s} , so the following fact becomes important:

Claim 1. *If \bar{u} is reachable from \bar{s} , then $(u_1, \dots, u_k) = (s_1, \dots, s_k)$ or there is $i = 1, \dots, m$ such that $(u_1, \dots, u_k) = (d_1^i, \dots, d_k^i)$; either way, $u_1, \dots, u_k \in \mathbb{Z}_\tau^+ \cup \mathbb{Z}_\tau^-$.*

Proof. If $\bar{u} = \bar{s}$, the claim is trivial. Suppose $\bar{u} \neq \bar{s}$. Then the path $\bar{s} \rightsquigarrow \bar{u}$ has ≥ 1 step. Let $\bar{v} \rightarrow \bar{u}$ be the last one. Then (\bar{v}, \bar{u}) is an edge in $G_{\varphi, w}$, so $w[\bar{x}/\bar{v}, \bar{y}/\bar{u}]$ satisfies $\varphi(\bar{x}, \bar{y})$; hence, it satisfies some $\varphi_i(\bar{x}, \bar{y})$; so, it satisfies the corresponding $(y_1 = d_1^i) \wedge \dots \wedge (y_k = d_k^i)$; which implies that $(u_1, \dots, u_k) = (d_1^i, \dots, d_k^i)$. \square

So, N separates \bar{u} into (1) its ‘bounded components’ $u_1, \dots, u_k \in \mathbb{Z}_\tau^+ \cup \mathbb{Z}_\tau^-$; and (2) its ‘unbounded component’ $u_0 \in \mathbb{Z}_\tau^+$. To remember (1), it keeps in its state an index $0 \leq i \leq m$ such that $(u_1, \dots, u_k) = (d_1^i, \dots, d_k^i)$ —for convenience, let $(d_1^0, \dots, d_k^0) := (s_1, \dots, s_k)$. To remember (2), it places its head on cell u_0 of w .

Overall, each state of N is of the form (i, σ) , where i identifies (as described) the list u_1, \dots, u_k and σ shows the status of the current stage. As a special case, $\sigma = \text{B}$ means the stage has just begun. So, if N is in state (i, B) on cell u^* , then it has reached vertex $\bar{u} = (u^*, d_1^i, \dots, d_k^i)$ and is now beginning the next stage.

With this representation, the search for a path $\bar{s} \rightsquigarrow \bar{t}$ takes N through configurations $((i_0, \mathbf{B}), u_0^*), ((i_1, \mathbf{B}), u_1^*), \dots, ((i_l, \mathbf{B}), u_l^*)$, where $u_0^* = s_0, i_0 = 0$; and the search succeeds iff $u_l^* = t_0$ and $(d_1^{i_l}, \dots, d_k^{i_l}) = (t_1, \dots, t_k)$. To complete the description of N , we must explain how N navigates through these configurations.

In a special first stage, N alters its configuration from $(q_s, 0)$ to $((i_0, \mathbf{B}), u_0^*) = ((0, \mathbf{B}), s_0)$. For this, it moves its head to cell s_0 (by counting s_0 steps from \vdash , if $s_0 > 0$; or by moving to \dashv and counting s_0 steps backwards, if $s_0 < 0$) and switches to state $(0, \mathbf{B})$. Easily, this can be done with $O(s_0) = O(\tau)$ states.

From then on, whenever at a configuration $((i, \mathbf{B}), u^*)$, our N works as follows.

First, it checks if $\bar{u} = \bar{t}$, i.e., if (1) $u^* = t_0$ and (2) $(d_1^i, \dots, d_k^i) = (t_1, \dots, t_k)$. Check 2 is hardwired, so it needs no extra states. Check 1 involves a trip to the left (if $t_0 > 0$) or right (if $t_0 < 0$) for t_0 steps or up to the end-marker, and back to cell u^* . There, if both checks succeeded, N accepts; otherwise, it switches to a special state (i, \mathbf{C}) . Overall, this uses $O(t_0) = O(\tau)$ states of the form (i, \cdot) .

State (i, \mathbf{C}) means that N is about to choose the next vertex \bar{v} among the out-neighbors of \bar{u} , so as to switch to the appropriate next configuration $((\cdot, \mathbf{B}), \cdot)$. Note that \bar{v} is an out-neighbor of \bar{u} iff (\bar{u}, \bar{v}) is an edge of $G_{\varphi, w}$; i.e., iff $w[\bar{x}/\bar{u}, \bar{y}/\bar{v}]$ satisfies some \wedge -clause $\varphi_j(\bar{x}, \bar{y})$ as in (12); i.e., iff there exists j such that

- the bounded components v_1, \dots, v_k of \bar{v} are equal to the second tuple of constants d_1^j, \dots, d_k^j in one of the φ_j whose first tuple of constants c_1^j, \dots, c_k^j are the bounded components d_1^i, \dots, d_k^i of \bar{u} , namely:

$$(d_1^i = c_1^j) \wedge \dots \wedge (d_k^i = c_k^j) \wedge (v_1 = d_1^j) \wedge \dots \wedge (v_k = d_k^j); \quad \text{and}$$

- the unbounded component v_0 of \bar{v} together with the unbounded component u^* of \bar{u} satisfy the respective $\hat{\varphi}_j$: $w[x_0/u^*, y_0/v_0] \models \hat{\varphi}_j(x_0, y_0)$.

So, to nondeterministically choose such a \bar{v} , our N works in two sub-stages:

- First, it chooses v_1, \dots, v_k , by simply choosing the index j of some \wedge -clause (if any) whose first tuple of constants is exactly d_1^i, \dots, d_k^i . This selection is hardwired and takes N to a special state (j, \mathbf{D}) still on cell u^* .
- Then, it chooses v_0 , by simulating the $O(\tau)$ -state 2NFA given by Lemma 12 for $\hat{\varphi}_j$, from cell u^* up to all cells v^* such that $w[x_0/u^*, y_0/v^*] \models \hat{\varphi}_j(x_0, y_0)$.

This needs $O(\tau)$ states of the form (j, \cdot) and ends at a state (j, \mathbf{B}) .

Overall, the result is a nondeterministic computation whose accepting branches take N to all configurations $((j, \mathbf{B}), v^*)$ such that $\bar{v} = (v^*, d_1^j, \dots, d_k^j)$ is an out-neighbor of $\bar{u} = (u^*, d_1^i, \dots, d_k^i)$. This concludes our description of a full stage.

In total, N uses $O(\tau)$ states for the special first stage and, for each i , another $O(\tau) + O(1) + O(\tau) = O(\tau)$ states for every stage that starts after state (i, \mathbf{B}) . So, the total number of states is $O(\tau) + (1+m) \cdot O(\tau) = O(m\tau)$, as promised.

6. Tightness

Having completed the proof of Theorem 4, we can now also show that it is ‘tight’, in two respects: first, its sentences are rightly one-dimensional, because two-dimensional sentences can solve non-regular problems; and second, its sentences are

rightly in DNF, because sentences in CNF can solve problems outside $2N$. Specifically, Theorem 14 below shows that a weak *two-dimensional* GA/DNF can solve the well-known non-regular problem of checking that a binary string is a palindrome; and Theorem 15 shows that a weak one-dimensional GAS *with core in CNF* can check that a string has length 2^h , which is well-known to require exponentially large $2NFAS$.

Theorem 14. $PALINDROME\ BINARY = \{w \in \{\mathbf{a}, \mathbf{b}\}^* \mid w \text{ is palindrome}\}$ is solved by a weak two-dimensional GA/DNF of arity 2, margin 1, degree 2, and length 27.

Proof. As a GAS of arity 2 and margin 1, our formula is of the form

$$TC[\varphi(x_0, x_1, y_0, y_1)](s_0, s_1, t_0, t_1), \quad (13)$$

where $s_0, s_1, t_0, t_1 \in \{+1, -1\}$. Therefore, for any $w \in \{\mathbf{a}, \mathbf{b}\}^*$ of length $n \geq 2$, the graph $G_{\varphi, w}$ has as vertex set the integer grid $(\mathbb{Z}_n^+)^2$, where every vertex corresponds to two cells of w . (Fig. 3R.) On this grid, we want an edge from vertex (x_0, x_1) to vertex (y_0, y_1) iff both of the following hold:

- The two vertices are successive along a forward-upward diagonal, i.e., $y_0 = x_0 + 1$ and $y_1 = x_1 - 1$; or, equivalently, $S(x_0, y_0) \wedge S(y_1, x_1)$.
- The cells x_0 and x_1 referred to by the first vertex contain the same symbol, i.e., $(\alpha(x_0) \wedge \alpha(x_1)) \vee (\beta(x_0) \wedge \beta(x_1))$, where $\alpha := \{\mathbf{a}\}$ and $\beta := \{\mathbf{b}\}$.

So, we let φ be the 2-clause DNF of length 27 which combines these two conditions, without using any anchored variables or anchored local atoms:

$$\begin{aligned} \varphi(x_0, x_1, y_0, y_1) := & (S(x_0, y_0) \wedge S(y_1, x_1) \wedge \alpha(x_0) \wedge \alpha(x_1)) \\ & \vee (S(x_0, y_0) \wedge S(y_1, x_1) \wedge \beta(x_0) \wedge \beta(x_1)). \end{aligned}$$

So, (13) is indeed a GA/DNF of degree 2, weak, and two-dimensional, as desired.

Now, clearly, a path $(1, n) \rightsquigarrow (n, 1)$ from bottom left to top right exists iff the main forward-upward diagonal contains all its edges $(i, n-i+1) \rightarrow (i+1, n-i)$; namely iff the cells i and $n-i+1$ contain the same symbols, for all $i = 1, \dots, n$; namely iff w is a palindrome. Therefore, (13) is exactly what we want, if we pick $(s_0, s_1) = (+1, -1)$ and $(t_0, t_1) = (-1, +1)$. \square

Theorem 15. For all $h \geq 1$, $LONG\ LENGTH_h = \{0^{2^h}\}$ is solved by a weak GA/CNF₁ of arity $h+1$, margin 1, degree $O(h^2)$, and length $O(h^2)$.

Proof. As a GA/CNF₁ of arity $h+1$ and margin 1, our formula is of the form

$$TC[\varphi(x_0, \dots, x_h, y_0, \dots, y_h)](s_0, \dots, s_h, t_0, \dots, t_h), \quad (14)$$

where $s_0, \dots, s_h, t_0, \dots, t_h \in \{+1, -1\}$ and each of $x_1, \dots, x_h, y_1, \dots, y_h$ is anchored to ± 1 in each of the \vee -clauses of the CNF φ .

Hence, for any $w \in \{0\}^*$ of length $n \geq 2$, the vertex set of the graph $G_{\varphi, w}$ is $(\mathbb{Z}_n^+)^{h+1}$. However, because of one-dimensionality, a vertex (x_0, x_1, \dots, x_h) is non-isolated only if $x_1, x_2, \dots, x_h \in \{1, n\}$. Viewing 1 as 0 and n as 1, we see every

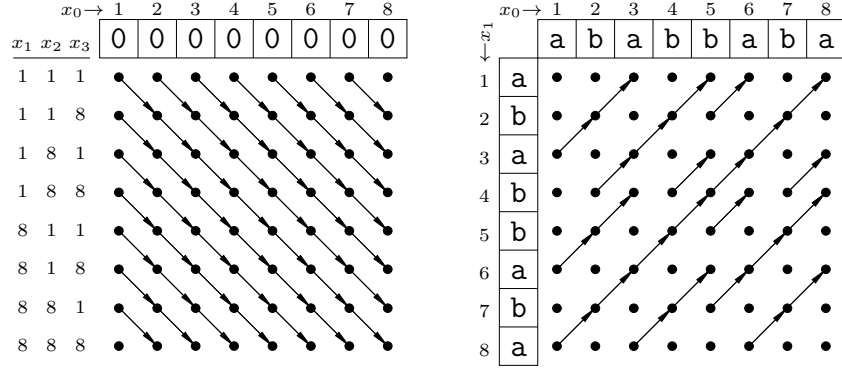


Figure 3. (L) The ‘active’ part of the graph $G_{\varphi,w}$ for φ the core of (14), $h = 3$, and $w = 0^8$: every edge is one step along a forward-downward diagonal. (R) The graph $G_{\varphi,w}$ for φ the core of (13) and $w = abaaba$: every edge is one step along a forward-upward diagonal and exists iff the two symbols at its origin are the same.

such ‘active’ vertex as an index $x_0 \in \mathbb{Z}_n^+$ in w together with a binary number $\tilde{x} := x_1 x_2 \cdots x_h \in [2^h]$. So, the corresponding ‘active’ part of $G_{\varphi,w}$ can be viewed as the integer grid $\mathbb{Z}_n^+ \times [2^h]$. (Fig. 3L.)

On this grid, we want an edge from vertex (x_0, \tilde{x}) to vertex (y_0, \tilde{y}) iff the two vertices are successive along a forward-downward diagonal, namely iff both (1) $y_0 = x_0 + 1$ and (2) $\tilde{y} = \tilde{x} + 1$. Clearly, Condition 1 can be written as $S(x_0, y_0)$.

Condition 2 says that the ‘bits’ $y_1 y_2 \cdots y_h$ are derived by a single increment from the ‘bits’ $x_1 x_2 \cdots x_h$. Recall that to increment a binary number is to complement (i) its rightmost 0 and (ii) all 1s to the right of that 0. In other words, a bit is complemented if all bits to its right are 1; otherwise, at least one bit to its right is 0 and the bit stays the same. So, every y_i is either $n+1-x_i$ (i.e., the ‘complement’ of x_i), if for all $j > i$ it is $x_j = n$ (i.e., the ‘bit’ x_j is 1); or equal to x_i , if for some $j > i$ it is $x_j = 1$ (i.e., the ‘bit’ x_j is 0). Thus, the formula

$$\left[\left(\bigwedge_{j=i+1}^h x_j = n \right) \longrightarrow y_i = \bar{x}_i \right] \wedge \left[\bigwedge_{j=i+1}^h (x_j = 1 \longrightarrow y_i = x_i) \right] \quad (15)$$

says that y_i has the correct value. Replacing 1 and n with ± 1 and taking cases as to the value of x_i , we can rewrite the two brackets of (15) respectively as:

$$\begin{aligned} & \left[\left(\bigwedge_{j=i+1}^h x_j = -1 \right) \wedge x_i = +1 \longrightarrow y_i = -1 \right] \wedge \left[\left(\bigwedge_{j=i+1}^h x_j = -1 \right) \wedge x_i = -1 \longrightarrow y_i = +1 \right], \\ & \bigwedge_{j=i+1}^h (x_j = +1 \wedge x_i = +1 \longrightarrow y_i = +1) \wedge \bigwedge_{j=i+1}^h (x_j = +1 \wedge x_i = -1 \longrightarrow y_i = -1). \end{aligned}$$

Now, by the identity $X \rightarrow Y \equiv \neg X \vee Y$, DeMorgan's Law, and since all variables here are either 1 or n (i.e., ± 1), we can further rewrite the brackets as:

$$\begin{aligned} & [(\bigvee_{j=i+1}^h x_j = +1) \vee x_i = -1 \vee y_i = -1] \wedge [(\bigvee_{j=i+1}^h x_j = +1) \vee x_i = +1 \vee y_i = +1], \\ & \bigwedge_{j=i+1}^h (x_j = -1 \vee x_i = -1 \vee y_i = +1) \wedge \bigwedge_{j=i+1}^h (x_j = -1 \vee x_i = +1 \vee y_i = -1). \end{aligned}$$

Calling them χ_i and ψ_i respectively, we see that χ_i is a 2-clause CNF of length $O(h-i)$, whereas ψ_i is a $2(h-i)$ -clause CNF of length $O(h-i)$. So, (15) is equivalent to the formula $\chi_i \wedge \psi_i$, which is a $O(h-i)$ -clause CNF of length $O(h-i)$. Thus,

$$\phi(x_1, \dots, x_h, y_1, \dots, y_h) := \bigwedge_{i=1}^h (\chi_i \wedge \psi_i)$$

is also a CNF, with $O(h^2)$ clauses and length $O(h^2)$, whose meaning is that every 'bit' y_j has the correct value, namely that $\tilde{y} = \tilde{x} + 1$, namely Condition 2.

Using the formulas for Conditions 1 and 2, we can now write the core of (14) as:

$$\varphi(x_0, x_1, \dots, x_h, y_0, y_1, \dots, y_h) := S(x_0, y_0) \wedge \phi(x_1, \dots, x_h, y_1, \dots, y_h).$$

So, φ is also a CNF, with just one more clause than ϕ ; hence, much like ϕ , it also has $O(h^2)$ clauses and length $O(h^2)$. Moreover, its only floating variables are x_0, y_0 and none of its atoms is local. Overall, (14) is indeed a weak GA/CNF₁, of margin 1, degree $O(h^2)$ and length $O(h^2)$, as promised.

Finally, it should be clear that a path $(1, 1, \dots, 1) \rightsquigarrow (n, n, \dots, n)$ from top left to bottom right exists iff the grid is square, namely iff $n = 2^h$. So, (14) is exactly what we want, so long as we pick $(s_0, s_1, \dots, s_h) = (+1, +1, \dots, +1)$ and $(t_0, t_1, \dots, t_h) = (-1, -1, \dots, -1)$. \square

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