Formalizing o-minimality

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- I claim it is basically infeasible to formalize without some specialized automation.

Paths in classical algebraic topology

Let X be a topological space and a and b points of X.

Definition

A *path* in X from a to b is a continuous map $\gamma : [0,1] \rightarrow X$ such that $\gamma(0) = a$ and $\gamma(1) = b$.

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- Suppose X is the union of two closed subsets A and B. A continuous map γ : [0, 1] → X might "enter and leave" A and B infinitely many times. For example, take X = ℝ, A = (-∞, 0], B = [0, ∞), γ(t) = t sin(1/t).

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- Suppose X is the union of two closed subsets A and B. A continuous map γ : [0,1] → X might "enter and leave" A and B infinitely many times. For example, take X = ℝ, A = (-∞,0], B = [0,∞), γ(t) = t sin(1/t).

Furthermore, X itself might be "pathological" from the standpoint of homotopy theory. For example, $X = \mathbb{Z}_p$ (topologically a Cantor set) has no nonconstant paths and so might as well be discrete, but it has a nontrivial topology.

Grothendieck on topology

After some ten years. I would now say, with hindsight. that "general topology" was developed (during the thirties and forties) by analysts and in order to meet the needs of analysts, not for topology per se, i.e. the study of the topological properties of the various geometrical shapes. That the foundations of topology are inadequate is manifest from the very beginning, in the form of "false problems" (at least from the point of view of the topological intuition of shapes) such as the "invariance of domains". even if the solution to this problem by Brouwer led him to introduce new geometrical ideas.

> — Grothendieck, *Esquisse d'un Programme* (1984) (translated by Schneps and Lochak)

Tame topology

Objective: Develop a setting for the homotopy theory of spaces which is flexible enough to allow the usual sorts of constructions but also "tame" enough to rule out the pathologies we saw earlier.

Semialgebraic sets

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A semialgebraic set in \mathbb{R}^n is a finite union of sets of the form

$$\{x \in R^n \mid f_1(x) = 0, \dots, f_k(x) = 0, g_1(x) > 0, \dots, g_l(x) > 0\}$$

for polynomials $f_1, \ldots, f_k, g_1, \ldots, g_l$ in the coordinates of x.

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Definition

Let $X \subset R^m$ and $Y \subset R^n$ be semialgebraic sets. A function $f: X \to Y$ is *semialgebraic* if its graph

$$\Gamma(f) = \{ (x, y) \mid y = f(x) \} \subset X \times Y \subset R^{m+n}$$

is semialgebraic.

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Theorem

If $X = A \cup B$ is the union of two closed semialgebraic subsets then for any continuous semialgebraic function $\gamma : [0, 1] \rightarrow X$, the domain [0, 1] can be decomposed into finitely many closed intervals each of which is mapped by γ into either A or B. The homotopy theory of semialgebraic sets

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There is a more sophisticated notion of *weakly semialgebraic space*; these model all homotopy types.

The preceding theorems all follow from a few simple properties of the class of semialgebraic sets.

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More specifically, semialgebraic sets are an example of an *o-minimal structure* and the preceding theorems are valid for any "o-minimal expansion of a real closed field".

Structures

Fix any set R.

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A structure consists of, for each $n \ge 0$, a family of subsets of \mathbb{R}^n called the *definable* subsets such that:

- For each n ≥ 0, the definable subsets of Rⁿ form a boolean algebra of subsets (the empty set is definable, and the definable sets are closed under union and complementation).
- For each n ≥ 0, if A ⊂ Rⁿ is definable, then R × A ⊂ Rⁿ⁺¹ and A × R ⊂ Rⁿ⁺¹ are definable.
- For each $n \ge 2$, the set $\{(x_1, \ldots, x_n) \in \mathbb{R}^n \mid x_1 = x_n\}$ is definable.
- For each n ≥ 0, writing π : Rⁿ⁺¹ = Rⁿ × R → Rⁿ for the projection, if A ⊂ Rⁿ⁺¹ is definable, then π(A) ⊂ Rⁿ is definable.

O-minimal structures

Now suppose R is an ordered field.

Definition

An *o-minimal structure* (technically, "o-minimal expansion of $(R, <, +, \times)$ ") is a structure satisfying the following additional conditions:

• (Constants) The set $\{r\}$ is definable for every $r \in R$.

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- (Extension) The sets

$$\{ (x, y) \mid x < y \} \subset R^2,$$

 $\{ (x, y, z) \mid x + y = z \} \subset R^3,$
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 (Minimality) Any definable set in R is a finite union of singletons and open intervals. Examples of o-minimal structures

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Semialgebraic sets form an o-minimal structure R_{sa} (for any real closed field R).

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Example

Wilkie's theorem: The smallest structure containing \mathbb{R}_{sa} and the graph of exp : $\mathbb{R}\to\mathbb{R}$ is o-minimal.

Fix a set R and a structure on R.

Definition

Suppose $X \subset R^m$ and $Y \subset R^n$ are definable sets. A function $f: X \to Y$ is *definable* if its graph

$$\Gamma(f) = \{ (x, y) \mid y = f(x) \} \subset X \times Y \subset \mathbb{R}^{m+n}$$

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Proof.

For simplicity assume $f: R \to R$ and $g: R \to R$ are definable functions. Let $\pi: R \times R \times R \to R \times R$ project out the second coordinate. Then

$$\begin{split} \Gamma(g \circ f) &= \{ (x, z) \mid z = g(f(x)) \} \\ &= \pi(\{ (x, y, z) \mid y = f(x), z = g(y) \}) \\ &= \pi(\{ (x, y, z) \mid y = f(x) \} \cap \{ (x, y, z) \mid z = g(y) \}) \\ &= \pi((\Gamma(f) \times R) \cap (R \times \Gamma(g))) \end{split}$$

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This style of proof is not sustainable.

Suppose R is totally ordered by a definable relation <. Equip R with the order topology and R^n with the product topology.

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Proof.

We have $(x_1, \ldots, x_n) \in \text{int } A$ if and only if

$$\exists I_1, \ldots, I_n, u_1, \ldots, u_n, I_1 < x_1 < u_1 \land \cdots \land I_n < x_n < u_n \land$$
$$(\forall y_1, \ldots, y_n, I_1 < y_1 < u_1 \land \cdots \land I_n < y_n < u_n \Longrightarrow$$
$$(y_1, \ldots, y_n) \in A).$$

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Proof. We have $(x_1, \ldots, x_n) \in \text{int } A$ if and only if

$$\exists l_1, \ldots, l_n, u_1, \ldots, u_n, l_1 < x_1 < u_1 \land \cdots \land l_n < x_n < u_n \land$$
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$$(y_1, \ldots, y_n) \in A).$$

Therefore

int A = [some large expression involving A and <]

is definable.

Definability by formulas

Theorem

Let $\varphi(x_1, \ldots, x_n)$ be any formula of first-order logic using relation symbols r_i and function symbols f_j and suppose each relation and function symbol is given an interpretation in R which is a definable set. Then the interpretation of φ is a definable set in R^n .

This theorem completes the previous proof.

Automation?

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Wanted: Some kind of automated procedure, probably a tactic, to automatically apply instances of the previous theorem in order to solve goals of the form definable S,

But maybe automation is overkill—we just prove a few dozen lemmas about definable sets and definable functions, and we're done?

The beginning of tameness

Lemma

Let $f : (a, b) \rightarrow R$ be a definable function. Then there exists an open interval contained in (a, b) on which f is either injective or constant.

Proof.

Two cases.

- Suppose f⁻¹({y}) is infinite for some y ∈ R. Then it contains an interval, and so f is constant on this interval.
- Otherwise, $f^{-1}(\{y\})$ is finite for every $y \in R$. Define

$$\mathcal{K} = \{ x \in (a, b) \mid \forall x' \in (a, b), f(x) = f(x') \implies x \le x' \}.$$

Then f(K) = f((a, b)) and so K is infinite, and therefore contains an interval. By definition, f is injective on K.

In the constructive setting, the "minimality" axiom should take the form of a function which takes a definable set in R and outputs a description of that set as a finite union of singletons and open intervals. (For this to be possible, definable A should not be a Prop but should contain data.)

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Proposition

If $A \subset R^0$ is definable, then A is decidable.

Proof.

Look at whether $R \times A \subset R$ is empty or the whole line. In the previous proof, we need to decide the formula

$$\exists a', b', y, x, a' < x < b' \implies f(x) = y.$$