

Catering to the Bias

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July 7, 2023

Personalized Recommender Systems _____

- Ubiquitous nowadays
 - eCommerce recommendations: Amazon, Google Shopping, NYT Wirecutter
 - Social Media: Facebook, TikTok, Instagram, Youtube, Twitter
 - News Aggregators: Feedly, Google News, Panda, Techmeme, Flipboard, Youtube, Twitter
- The incentives of the recommender system (principal) and users (agents) are not aligned
 - Principal: Maximize engagement
 - Agent: Acquire information, time cost

Overview of Results

There are two major cases

- Principal and agent share the same prior beliefs,
 - The relative curvature of agent payoff function to that of principal determines optimal information structure
 - Convex in time: Poisson revelation with an intensity determined by the agent's payoff function
 - Concave in time: A period of no information followed by an immediate revelation
- When the agent has a biased prior
 - Principal always caters to the biased prior
 - Initially revealing information on the state towards which the agent is biased
 - Gradual revelation is necessary (conjecture).

Simple Example

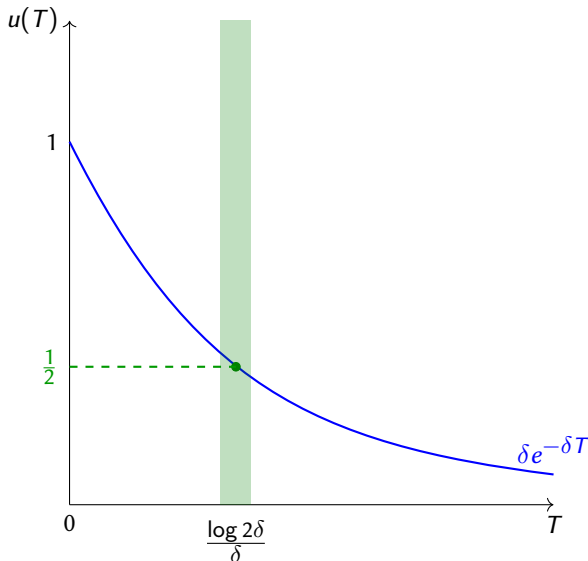
- Game between an informed principal (committed) and an uninformed agent (uncommitted)
- Payoffs:
 - P: T , i.e., he values engagement
 - A: $u(T) = \delta e^{-\delta T} v(\text{Info})$

$$v(\text{Info}) = \begin{cases} 1 & \text{Info} = \text{State} \\ 1/2 & \text{Info} = \text{Prior} \end{cases}$$

- Actions:
 - P: reveal the state at $T \in \mathbb{R}_+ \cup \{0\}$
 - A: when to stop listening

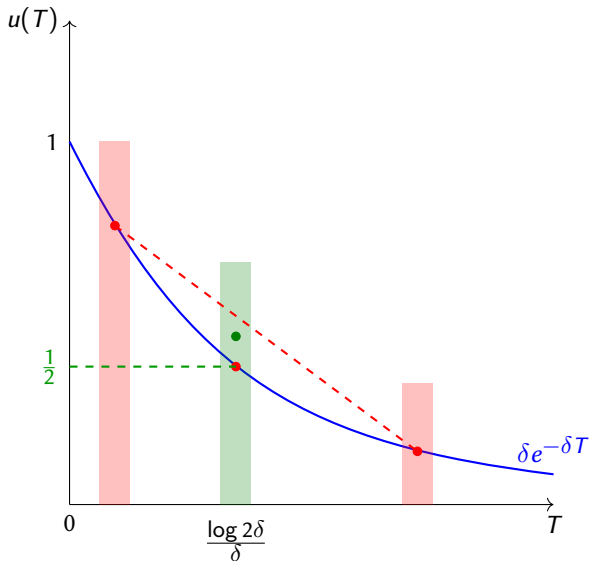
Simple Example

- Revelation strategy: reveal at $\delta e^{-\delta T^*} = 1/2$



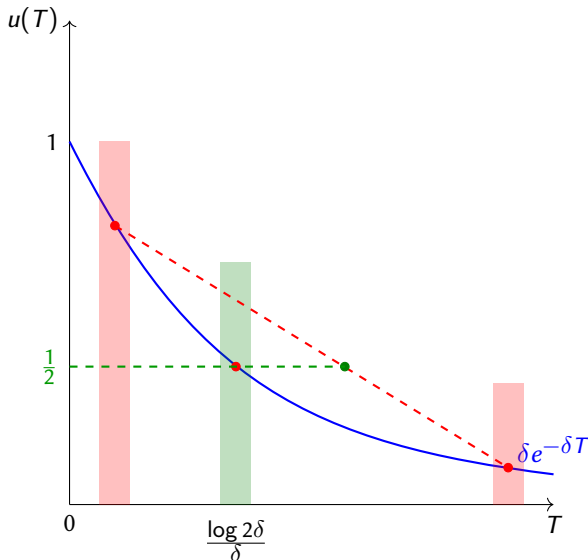
Simple Example

- Spread revelation time around T^*



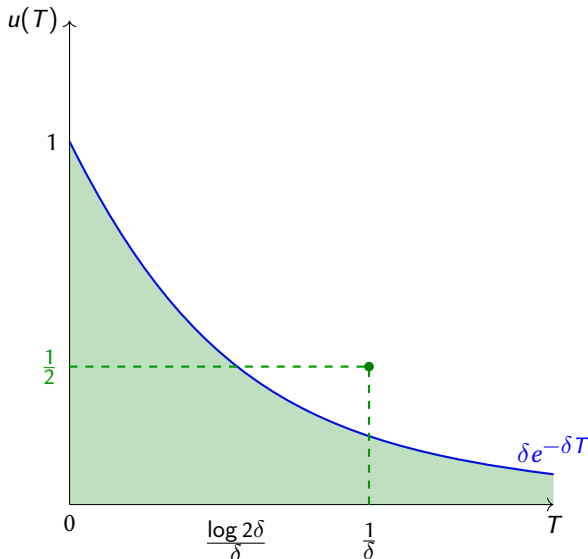
Simple Example

- Spread revelation time around T^* and increase its mean



Simple Example

- Distribution: exponential at rate δ ; Poisson revelation



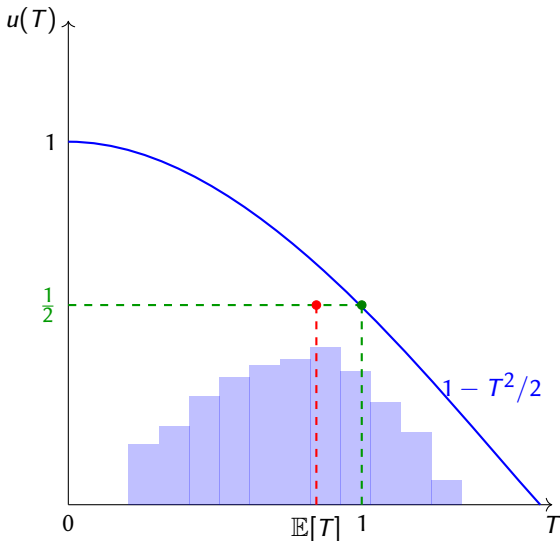
Simple Example

- Alternative: $u(T) = (1 - T^2/2) v(\text{info})$
- In this case, a mean preserving contraction of any distribution of T benefits A
 - \Rightarrow its mean can be pushed up!
- Optimal revelation strategy is T^*

$$1 - (T^*)^2 / 2 = 1/2 \rightarrow T^* = 1$$

Simple Example

- Concave payoff: Jensen's inequality: $\mathbb{E}[T] < 1$



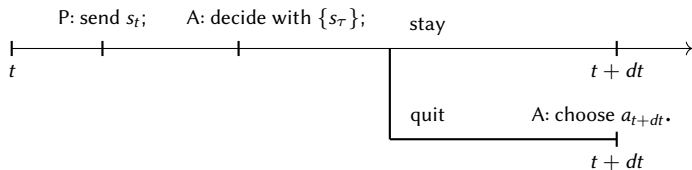
Model

- Agent utility function

$$u_A(T, \omega, a) = D(T) \hat{u}(\omega, a)$$

- Underlying state: $\omega \in \Omega = \{0, 1\}$ – more would not make much of a difference
- Action: $a \in A$
- Time spent acquiring information: T
- $D(T)$ is strictly decreasing in T and $\hat{u}(\omega, a) \geq 0$
- Principal payoff : T
- Possibly uncommon priors
 $\mu_0^A = \mathbb{P}^A(\omega = 1), \mu_0^P = \mathbb{P}^P(\omega = 1) \in (0, 1)$. Common knowledge

Timing



The Model

- P chooses an information structure.
- A mapping from the space of history realizations to probability distributions over signals at t .

$$\left(S_\infty \times \Omega, \mathcal{F}, \mathbb{P}^P, \{\mathcal{F}_t\}_{t \in \mathbb{R}_+} \right)$$

- S_∞ : the set of history of signal realizations,
- Each member is of the form s^∞ , \mathcal{F} is a σ -algebra over $S_\infty \times \Omega$,
- \mathbb{P}^P : probability measure from the principal's perspective
- $\mathcal{F}_t \subset \mathcal{F}_{t'} \subset \mathcal{F}, \forall t < t'$ is a filtration.

The Model

- A's information is similar except that it does not include Ω and

$$\mathbb{P}^A(S) = \mu_0^A \cdot \mathbb{P}^P(S \times \Omega | \omega = 1) + (1 - \mu_0^A) \cdot \mathbb{P}^P(S \times \Omega | \omega = 0)$$

- \mathcal{F}_t^A is similarly calculated
- Equilibrium is standard:
 - A cannot commit to exit strategies
 - P can commit to information structure

Some Examples

- Key assumption:

$$u^P = T$$

$$u^A = D(T) \hat{u}(\omega, a)$$

- This can be mapped to several assumptions about the evolution of time cost for the agent

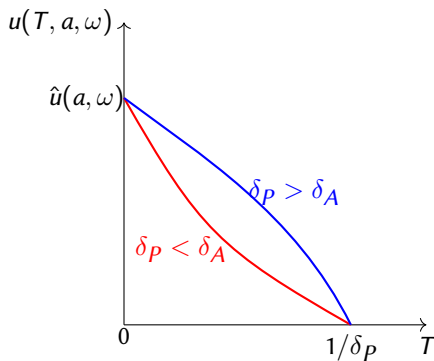
Some Examples

Example 1. Exponential discounting

$$u^P = \int_0^{\hat{T}} e^{-\delta_P t} dt$$

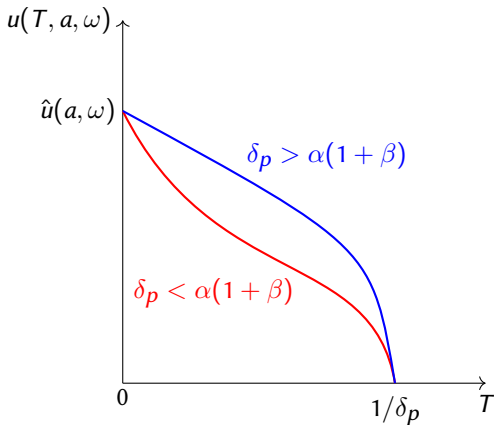
$$\rightarrow T = u^P \Rightarrow D(T) = (1 - \delta_P T)^{\frac{\delta_A}{\delta_P}}$$

$$u^A = \delta_A e^{-\delta_A \hat{T}} \hat{u}(\cdot)$$



Some Examples

- **Example 2.** Hyperbolic discounting of Loewenstein and Prelec (1992) $u^A = (1 + \alpha T)^{-\beta} \hat{u}(\cdot)$
 - Set $T = u^P \Rightarrow D(T) = \left(1 - \frac{\alpha}{\delta_p} \log(1 - \delta_p T)\right)^{-\beta}$

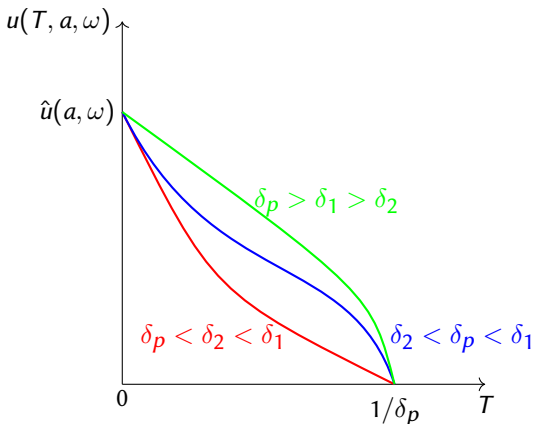


Some Examples

- **Example 3.** Quasi-Hyperbolic discounting of Harris and Laibson (2013) $u^A = \left[(1 - \beta) e^{-\delta_1 \hat{T}} + \beta e^{-\delta_2 \hat{T}} \right] \hat{u}(\cdot)$

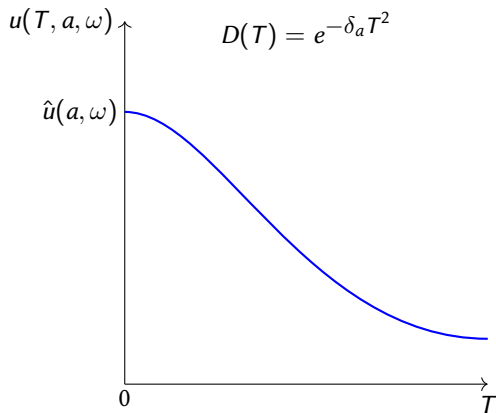
- Set $T = u^P \Rightarrow$

$$D(T) = (1 - \beta) (1 - \delta_p T)^{\delta_1/\delta_p} + \beta (1 - \delta_p T)^{\delta_2/\delta_p}$$



Some Examples

- **Example 4.** Habit Formation of Allcott, Gentzkow, and Song (2022) $u^A = e^{\int_0^T g(\tau) d\tau} \hat{u}(\cdot)$, $g' < 0$, $g'' > 0$



The Model – Characterization_____

Claim. If A exits after history s_t , then $\mu_t^A = \mathbb{E}^A[\omega|s_t] = 0, 1$ a.e.

- Idea of proof: If not, then split the signal into two fully revealing signals each with probability μ_t^A and $1 - \mu_t^A$. Increases the value of staying at all histories. Allows P to reduce the probability of exit and increase his payoff.

The Model

Assumption. The Payoff function $v(\mu) = \max_{a \in A} \mathbb{E}_{\mu} [\hat{u}(a, \omega)]$ is strictly convex, differentiable and symmetric around $\mu = 1/2$.

- Allows us to take derivatives
- An example is $\hat{u}(a, \omega) = a(\omega - 1/2) - a^2/2, A = [-1, 1]$
- Does include $|A| < \infty$, since $v(\mu)$ is piecewise linear
 - can approximate with smooth convex functions

The Model

- Can apply Caratheodory theorem
 - 3 signals in each period is sufficient: $\Omega \cup \{\text{No News}\}$
- Choice of information structure is equivalent to choice of two D.D.F functions (decumulative distribution functions)

$$G_1(t) = \mathbb{P}^A(\text{exit} \geq t, \omega = 1)$$

$$G_0(t) = \mathbb{P}^A(\text{exit} \geq t, \omega = 0)$$

$$\hat{\mu}^A(t) = \mathbb{P}^A(\omega | \text{stay until } t)$$

$$= \frac{G_1(t)}{G_1(t) + G_0(t)} = \frac{G_1(t)}{G(t)}$$

- D.D.F's are decreasing and $G_1(0) = \mu_0^A = 1 - G_0(0)$

Optimal Information Provision

$$\max_{G_0, G_1} \int_0^{\infty} \left(\hat{\mu}^A(t) + (1 - \hat{\mu}^A(t)) \ell \right) [G_0(t) + G_1(t)] dt$$

subject to

$$v(1) D(t) G(t) + v(1) \int_t^{\infty} G(s) D'(s) ds \geq G(t) D(t) v(\hat{\mu}^A(t)), \forall t$$

$G_{\omega}(t)$: non-increasing

$$G_1(0) = 1 - G_0(0) = \mu_0^A$$

- $\ell = \frac{\mu_0^A}{1 - \mu_0^A} / \frac{\mu_0^P}{1 - \mu_0^P}$: likelihood ratio; adjustment needed for difference in prior

Solution Method

- Objective is linear in $G_\omega(t)$
- Constraint set is convex and has a non-empty interior.
We can use standard Lagrangian techniques
 - Guess a Lagrangian
 - Use first order condition
 - Use ironing when necessary
- Somewhat similar to Kleiner, Moldovanu, and Strack (2021) and Saeedi and Shourideh (2023)
 - key difference: it is not a linear program

The Agreement Case

- Suppose that $\mu_0^A = \mu_0^P \rightarrow \ell = 1$.
- First the easy one!

Proposition. Concave Discounting. When $D(T)$ is concave, optimal solution is

$$\begin{aligned}G_1(t) &= \mu_0 \mathbf{1}[t < t^*] \\G_0(t) &= (1 - \mu_0) \mathbf{1}[t < t^*] \\v(1) D(t^*) &= v(\mu_0) D(0)\end{aligned}$$

- Silence until t^* is optimal!
- Agent is only indifferent at time 0 \rightarrow Time inconsistency

The Agreement Case

Proposition. Convex Discounting. When $D(T)$ is convex, optimal solution two phases (if $\mu_0 > 1/2$)

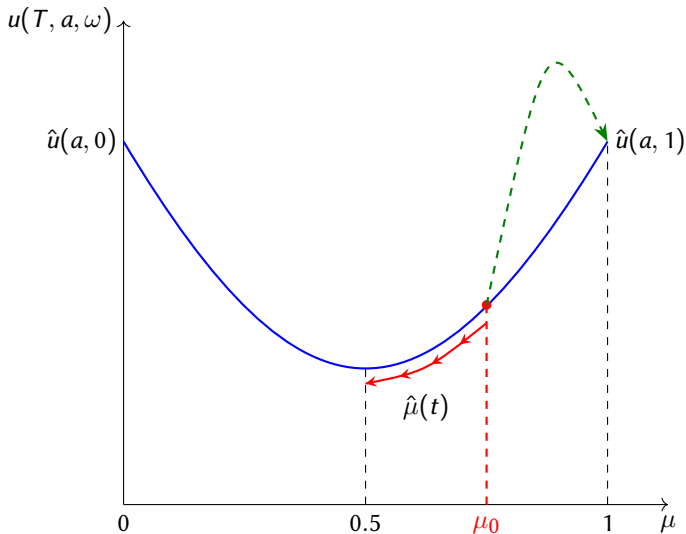
$$t \leq t^* : G_1'(t) < 0, \hat{\mu}'(t) < 0, G_0(t) = 1 - \mu_0$$

$$t \geq t^* : \hat{\mu}(t) = 1/2, \frac{G_0'(t)}{G_0(t)} = \frac{G_1'(t)}{G_1(t)} = \frac{D'(t)}{D(t)}$$

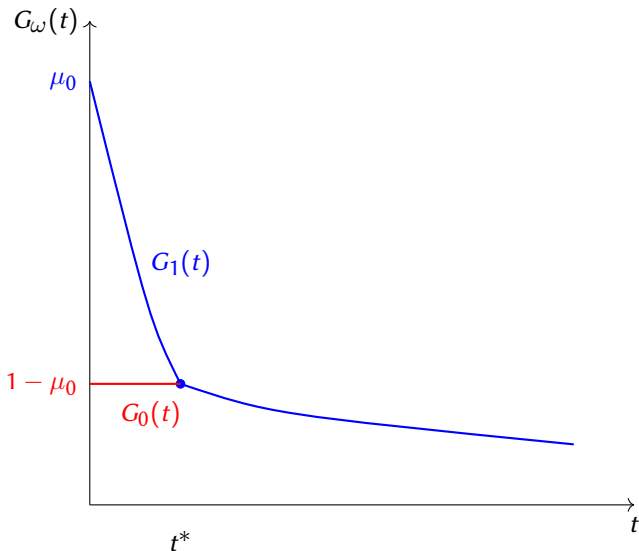
The case with $\mu_0 < 1/2$ is symmetric.

- *Belief-Smoothing*
 - A's value function $v(\mu)$, i.e., cost of delay, is strictly convex

Agreement: Convex Discounting



Agreement: Convex Discounting



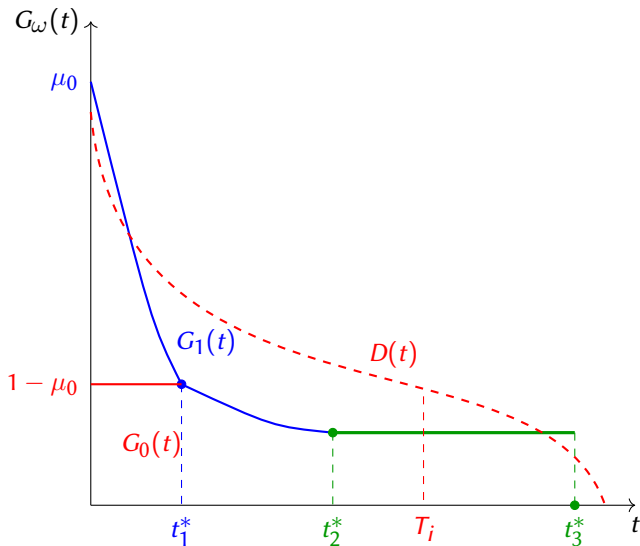
Agreement: Convex Discounting

- Two phases with time-varying Poisson revelation of information
 - Phase 1: Arrival of news about the more likely state at rate $> -\frac{D'(t)}{D(t)}$
 - Phase 2: Arrival of news about both state at rate $-\frac{D'(t)}{D(t)}$
- Phase 1 depends on the curvature of $v(\mu)$
 - The more convex it is, the longer is Phase 1
 - Belief-smoothing: Agent really hates variation in beliefs

Agreement: Convex-Concave _____

- Suppose there exists an inflection point T_i where $D(T)$ is convex below T_i and concave above T_i .
 - Possible under (Quasi-)Hyperbolic discounting:
- **Result.** Optimal information structure has (at most) three phases:
 - Phase 1: More likely state is revealed according to poisson
 - Phase 2: Both states are revealed at rate $-D'(t)/D(t)$
 - Phase 3: silence followed by revelation of both states
- Phase 3 often starts before T_i

Agreement: Convex-Concave



Disagreement

- Payoff of P

$$\int_0^{\infty} \left(\hat{\mu}^A(t) + (1 - \hat{\mu}^A(t)) \ell \right) [G_0(t) + G_1(t)] dt$$

where $\ell = \frac{\mu_0^A}{1-\mu_0^A} / \frac{\mu_0^P}{1-\mu_0^P}$ is the relative likelihood ratios.

- We are writing everyone's payoff as a function of beliefs of the agent.
- WLOG, let's say $\ell < 1$ so A is more optimistic about $\omega = 0$.
- Given that P prefers μ closer to 1, wants A to spend the most time strictly above $\hat{\mu} = 1/2$.

Disagreement: Convex Discounting _____

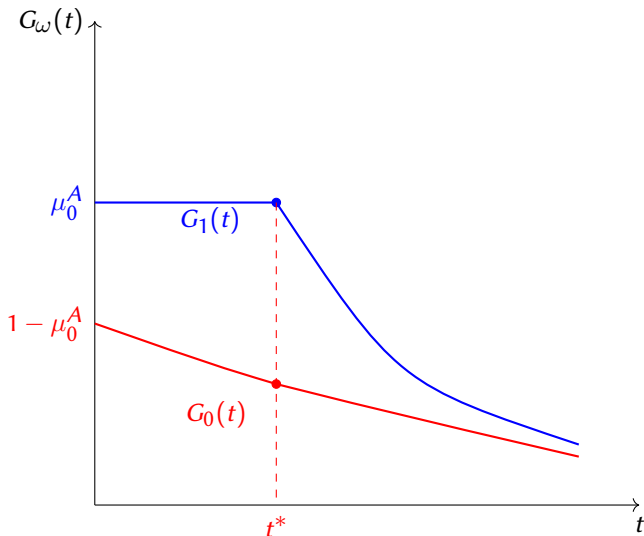
Proposition. Convex Discounting and Disagreement. Suppose $D(T) = e^{-\delta T}$ and $\mu_0^A < \mu_0^P$, then optimal solution two phase

$$t \leq t^* : G_0'(t) < 0, \hat{\mu}'(t) > 0, G_1(t) = \mu_0^A$$

$$t \geq t^* : \hat{\mu}(t) = \mu^*(t) > \mu_0^A, \frac{G_0'(t)}{G_0(t)} = \frac{G_1'(t)}{G_1(t)} = -\delta$$

- Again two phase:
 - *Cater to the bias phase*: reveal the A-optimistic state
 - Settle on higher belief

Catering to the Bias



Disagreement: Concave Discounting _____

- Very Preliminary:
 - Cannot have full revelation in both states at the same time
- Conjecture:
 - Three Phases:
 - A silent phase
 - A cater-to-the-bias phase
 - Full revelation

THANK YOU