

- * 13.3 Evaluate the transfer functions $T_1(s) = Y(s)/U(s)$ and $T_2(s) = Z(s)/U(s)$ as rational functions for the block diagram shown in Figure P13.3.

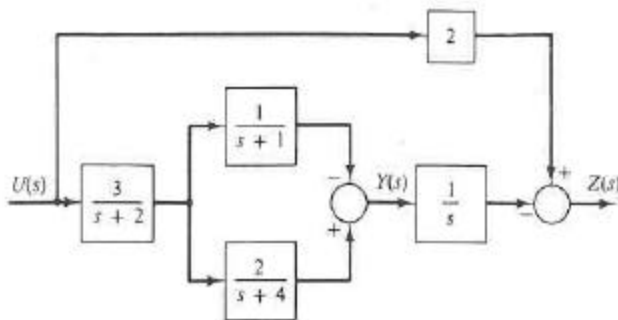


FIGURE P13.3

$$T_1(s) = Y(s)/U(s)$$

Blocks in parallel

$$\begin{aligned} Y(s) &= U(s) \cdot \frac{3}{s+2} \left[\frac{2}{s+4} - \frac{1}{s+1} \right] \\ &= U(s) \cdot \frac{3}{s+2} \left[\frac{2s+2 - s-4}{(s+4)(s+1)} \right] \\ &= U(s) \cdot \frac{3(s-2)}{(s+2)(s+4)(s+1)} \end{aligned}$$

$$\therefore T_1(s) = \frac{Y}{U} = \frac{3(s-2)}{(s+2)(s+4)(s+1)} = \frac{3s-6}{s^3+7s^2+14s+8}$$

Note to grader: either form acceptable

$$T_2 = Z(s)/U(s)$$

$$Z(s) = -\frac{1}{s} Y(s) + 2U(s) = \left(-\frac{1}{s} T_1(s) + 2 \right) U(s)$$

$$\Rightarrow T_2 = 2 - \frac{T_1(s)}{s} = \frac{2s^4 + 14s^3 + 28s^2 + 16s - 3s + 6}{s(s^3 + 7s^2 + 14s + 8)}$$

$$\therefore T_2(s) = \frac{2s^4 + 14s^3 + 28s^2 + 13s + 6}{s^4 + 7s^3 + 14s^2 + 8s}$$

or various alternatives

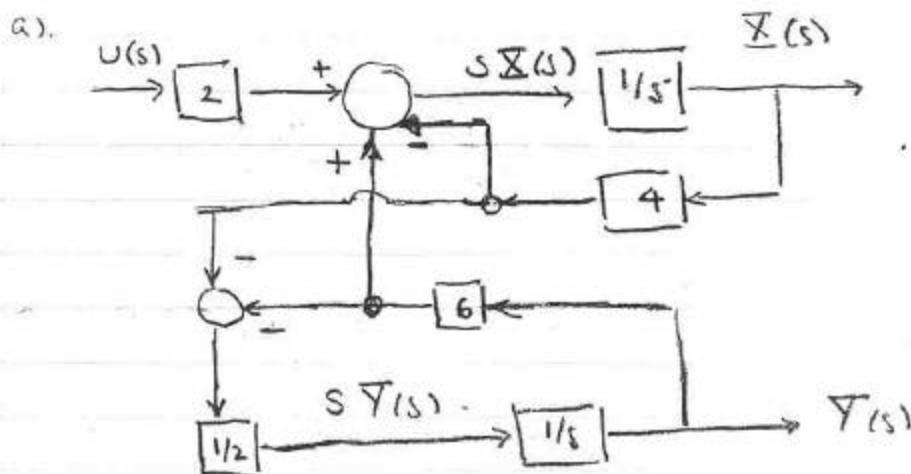
$$\text{e.g. } T_2 = 2 - \frac{3(s-2)}{s(s+2)(s+4)(s+1)}$$

13.4 Draw block diagrams for each of the following sets of state-variable equations.

a) $\dot{x} = -4x + 6y + 2u(t)$
 $\dot{y} = -2x - 3y$

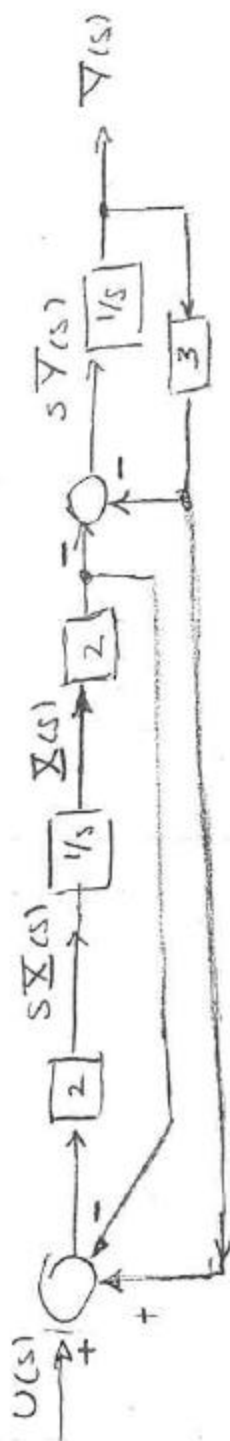
b) $\dot{x}_1 = -3x_1 + 5x_2 + 3u(t)$
 $\dot{x}_2 = 4x_1 - 6x_2 - u(t)$

c) $\dot{\theta} = \omega$
 $\dot{\omega} = -8\theta - 4\omega + 2x$
 $\dot{x} = v$
 $\dot{v} = 6\theta - 3x + u(t)$

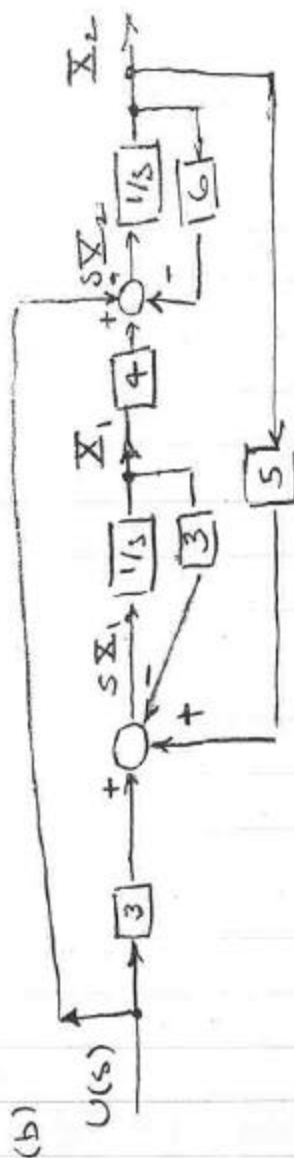


Lots of ways of doing these problems.

Alternative: need longer distance - use landscape.

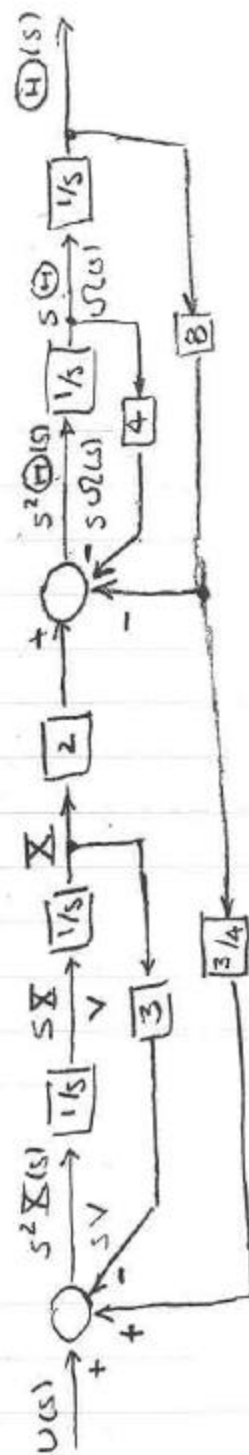


(a).



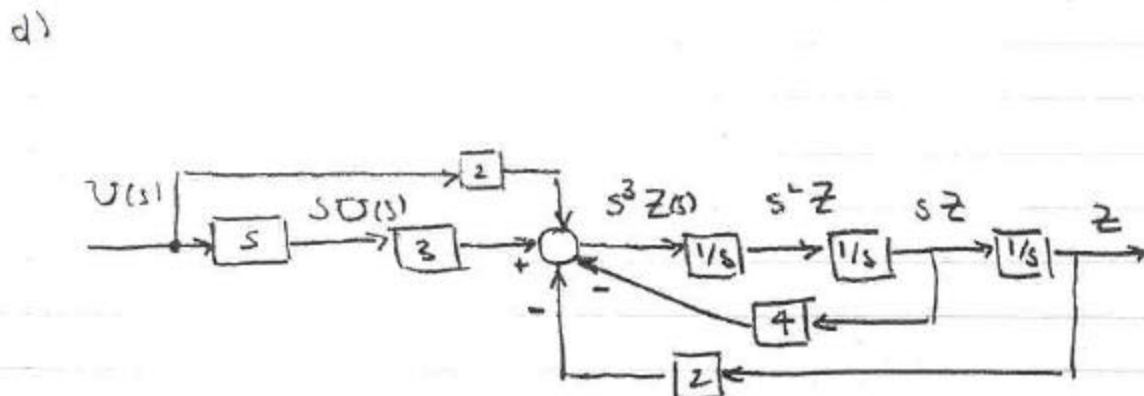
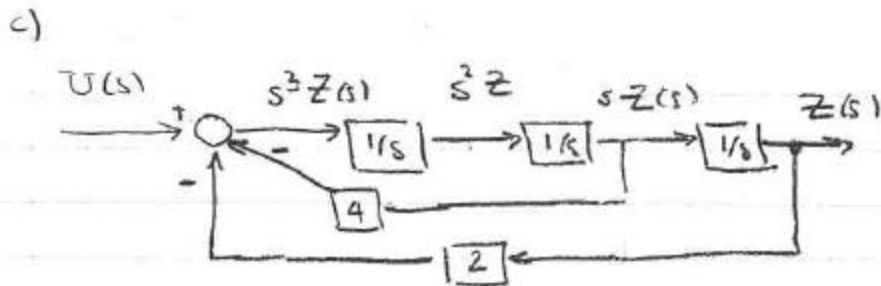
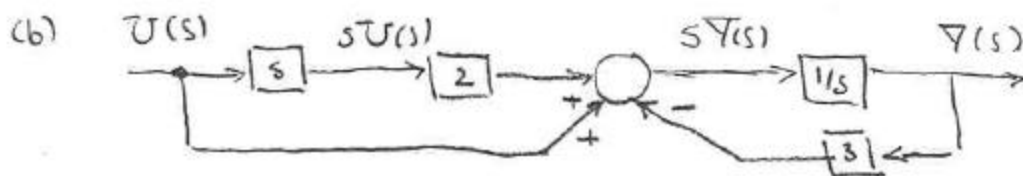
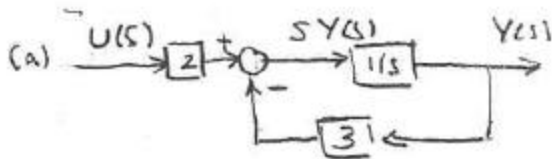
(b)

(c)



13.6 Draw block diagrams for each of the following input-output models.

- a) $\dot{y} + 3y = 2u(t)$
 b) $\dot{y} + 3y = 2\dot{u} + u(t)$
 c) $\ddot{z} + 4\dot{z} + 2z = u(t)$
 d) $\ddot{z} + 4\dot{z} + 2z = 3\dot{u} + 2u(t)$



In Problems 13.24 through 13.26, determine the closed-loop transfer function $Y(s)/U(s)$ as a rational function of s for the block diagram shown in the figure cited.

* 13.24 Figure P13.24.

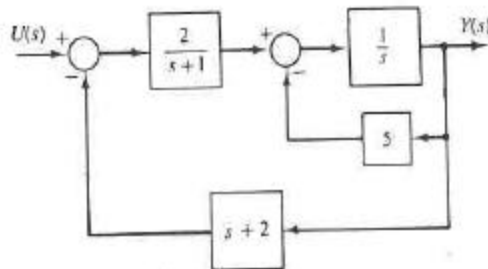


FIGURE P13.24

Inner loop with feed back

$$T_1 = \frac{1}{s} \cdot \frac{1}{1 + \frac{5}{s}} = \frac{1}{s+5}$$

Elements in series

$$T_2 = \frac{2}{s+1} \cdot \frac{1}{s+5} = \frac{2}{(s+1)(s+5)}$$

Outer Loop

$$T = \frac{T_2}{1 + T_2 \cdot (s+2)} = \frac{2}{(s+1)(s+5) \left(1 + \frac{(s+2)2}{(s+1)(s+5)} \right)}$$

$$T = \frac{2}{(s+1)(s+5) + 2(s+2)} = \frac{2}{s^2 + 6s + 5 + 2s + 4}$$

$$T = \frac{2}{s^2 + 8s + 9}$$

13.25 Figure P13.25.

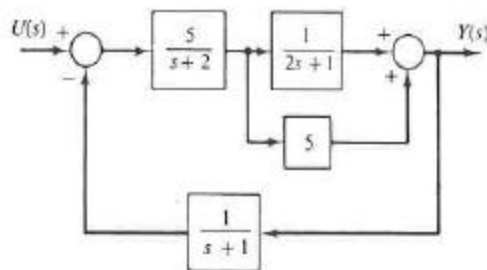
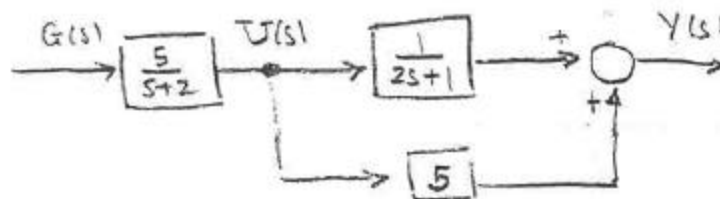


FIGURE P13.25

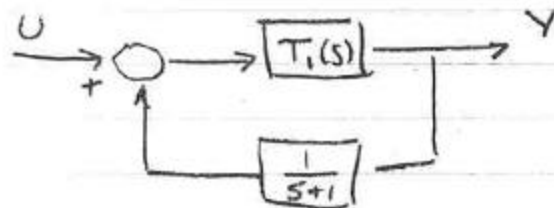
Equivalent transfer function for upper loop



$$Y(s) = U(s) \cdot \left(s + \frac{1}{2s+1} \right) = \frac{10s+5+1}{2s+1} = \frac{10s+6}{2s+1}$$

$$\frac{Y(s)}{G(s)} = \frac{5}{s+2} \cdot \frac{10s+6}{2s+1} = \frac{5(10s+6)}{(s+2)(2s+1)} = T_1(s)$$

Thus, block diagram look like



(use standard result
for closed loop)

$$\Rightarrow T = \frac{T_1}{1 + T_1 \cdot \frac{1}{s+1}} = \frac{5(10s+6)}{(s+2)(2s+1) \left(1 + \frac{5(10s+6)}{(s+2)(2s+1)(s+1)} \right)}$$

$$T = \frac{5(10s+6)(s+1)}{(s+2)(2s+1)(s+1) + 5(10s+6)} = \frac{50s^2 + 80s + 30}{2s^3 + 8s^2 + 57s + 32}$$

- 13.33 a) Find the closed-loop transfer function $T(s) = Y(s)/U(s)$ as a ratio of polynomials for the block diagram shown in Figure P13.33.
 b) Express the damping ratio ζ and the undamped natural frequency ω_n in terms of K . Show that both poles of $T(s)$ are on the negative real axis for $0 \leq K \leq 1/4$.

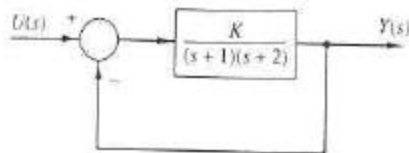


FIGURE P13.33

$$a). \quad T = \frac{G}{1+G} = \frac{K}{(s+1)(s+2) \left[1 + \frac{K}{(s+1)(s+2)} \right]}$$

$$T = \frac{K}{(s+1)(s+2)+K} = \frac{K}{s^2+3s+(2+K)}$$

By analogy with mass / spring system. For mass / spring system

$$T = \frac{1}{ms^2 + Bs + K_s}$$

K_s - spring stiffness

m - mass

B - damping.

Natural frequency = $\omega_n^2 = \frac{K_s}{m}$

Damping ratio = $\zeta = \frac{B}{2\sqrt{K_s m}}$

In this case: $m=1$, $B=3$, $K_s=2+K$

$$\therefore \omega_n = \sqrt{2+K}, \quad \zeta = \frac{3}{2\sqrt{2+K}}$$

Poles are on the negative real axis if $\zeta \geq 1$

$$\Rightarrow \frac{3}{2\sqrt{2+K}} \geq 1 \Rightarrow \sqrt{K+2} \leq \frac{3}{2}$$

$$\Rightarrow K+2 \leq \frac{9}{4} \Rightarrow K \leq \frac{1}{4}$$

Extra Credit, (25%).

a. From (32), page 406 of text

$$\ddot{w} + (1) \dot{w} + \frac{1}{1} w = \frac{1}{1} e_i(t)$$

or

$$\ddot{w} + \dot{w} + w = e_i(t)$$

Take Laplace T.

$$W(s) = \frac{E_i(s)}{s^2 + s + 1} = \frac{100}{s(s^2 + s + 1)}$$

$$W(s) = \frac{A}{s} + F(s)$$

$$A = \lim_{s \rightarrow 0} sW(s) = 100$$

$$F(s) = \frac{100 - 100s^2 - 100s - 100}{s(s^2 + s + 1)} = \frac{-100(s+1)}{s^2 + s + 1}$$

Complete square in denominator.

$$F(s) = -100 \cdot \frac{s+1}{(s+\frac{1}{2})^2 + 0.75}$$

Standard L.T. - see page 646 - has form

$$F(s) = -100 \cdot \frac{Bs + C}{(s+a)^2 + \omega^2}$$

$$\text{where } B=1, C=1, a=\frac{1}{2}, \omega=\sqrt{.75}$$

From Table:

$$w = 100 \left[1 - e^{-\frac{t}{2}} \left(\cos \omega t + \left(\frac{1/2}{\omega} \right) \sin \omega t \right) \right]$$

See MathCad Plot on next page.

$$b. 5\% \text{ os} \Rightarrow e^{-\frac{f\pi}{\sqrt{1-f^2}}} = 0.05$$

$$\text{Take natural log of both sides} \Rightarrow -\frac{f\pi}{\sqrt{1-f^2}} = -2.996$$

Divide by π & square both sides

$\Rightarrow$

$$\frac{f^2}{1-f^2} = 0.909 \Rightarrow f^2 = \frac{0.909}{1.909}$$

$$f = 0.69$$

From (32) if $R_A \neq 1$, we get. (page 406)

$$\ddot{w} + R_A \dot{w} + w = e_i(t)$$

$\therefore R_A$ is analogous to B for a mechanical system
 $K=1, m=1.$

$$\therefore f = \frac{B}{2\sqrt{Km}} = \frac{B}{2} = \frac{R_A}{2}$$

$$\Rightarrow R_A = 2 \cdot (0.69) = 1.38$$

c. From page 406, equation (32)

$$\ddot{\omega} + \dot{\omega} + \omega = e_i(t) - \dot{\tau}_L = \tau_L(t)$$

For steady state $\dot{\omega} = \ddot{\omega} = \dot{\tau}_L = 0$

$$\therefore \omega = 100 - 20 = 80 \text{ rad/sec.}$$