



Review from last lecture











(Russell and Norvig Chapter 20.6)



Back to standard machine learning problem. 2 dimensions (2 attributes, x1 and x2). 2 classes (red and blue). A classifier would classify each point as red or blue.

The points are clearly linearly separable (blue can be separated from red with a line)









This is how the perceptron with the initial weights will classify points. Points above the line are classified as 1.

Not very surprising that this isn't very good, as we randomly set the weights



The algorithm we showed you last time needs to take the derivative of g. Here, g does not have a derivative. For now, we will just ignore that.



So here's what's happening in a perceptron with those weights.

Picked a mislabeled point, and update the weights



Pick another mislabeled point, update weights again



And again...



Note that each time we pick a blue point essentially nothing happens.



Note: w0 could only ever change by alpha. If alpha is too small, it will move too slow. If alpha is too big, you might not have the resolution to find the answer.

How does α affect the learning?

 $W_j \leftarrow W_j + \alpha(y - out)x_j$



All these lines separate red from blue. But is one better than the other?









Pick the direction with the largest margin, and then put the separator in the middle of the margin. There is a pretty efficient algorithm to find this separator (but the algorithm is a bit mathy to present here)

When the data is not linearly separable then there's a thing called "soft margin" you can look at.

The points on the dotted line are considered the "support vectors"

Given all the examples, the margin can be maximized efficiently



Running a perceptron on this data





The data isn't linearly separable. Boo.

How can we make this data linearly separable?



But you can make it linearly separable by using a transformation . For example, you can make points $(x1, x1^2)$.

By mapping the one dimensional examples to higher dimensions you can make them linearly separable!





Oh hey check this out mapping to higher dimensions is actually a pretty good idea. The trick is just choosing how to map it.



This is very pretty, watch it!

Demo:

http://svm.dcs.rhbnc.ac.uk/pagesnew/GPat.shtml