Major Changes:
Focus on neural network

What I Have Accomplished Since Last Meeting:
I have found a paper “Sensor-Driven Neural Control for Omnidirectional Locomotion and Versatile Reactive Behaviors of Walking Machines”, which was very close to the topic I was challenging. I thought about proposing a multi-end neural oscillator network, which could potentially produce a rotational pattern.

However, the mismatch of time had not allowed me to actually discuss the idea in person. I have sent the idea on email, and am waiting for the answer right now.

Looking Ahead:
I will narrow down the problem, and should start implementing as soon as possible.

Revisions to Your Future Milestones:
The milestone from now on would be to produce the prototype which can produce the oscillating and phase-shifted pattern by the end of this week, and apply it to generate the leg movement in some form.