18-847F: Special Topics in Computer Systems

Foundations of Cloud and Machine Learning Infrastructure



Lecture 9: Coding for Distributed Storage

Foundations of Cloud and Machine Learning Infrastructure



Outline

Coded Distributed Storage

Repair-efficiency

Service Capacity

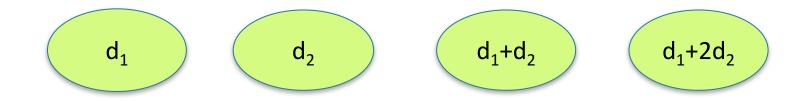
(n,k) Reed-Solomon Codes: 1960

- $\circ \quad \mathsf{Data:} \, \mathsf{d_{1\prime}} \mathsf{d_{2\prime}} \, \mathsf{d_{3\prime}} \dots \mathsf{d_{k}}$
- Polynomial: $d_1 + d_2 x + d_3 x^2 + ... d_k x^{k-1}$
- Parity bits: Evaluate at n-k points:

X=1:	$d_1 + d_2 + d_3 + d_4$
X=2:	$d_1 + 2 d_2 + 4 d_3 + 8 d_4$
x=3 :	
x=4:	
x=n:	

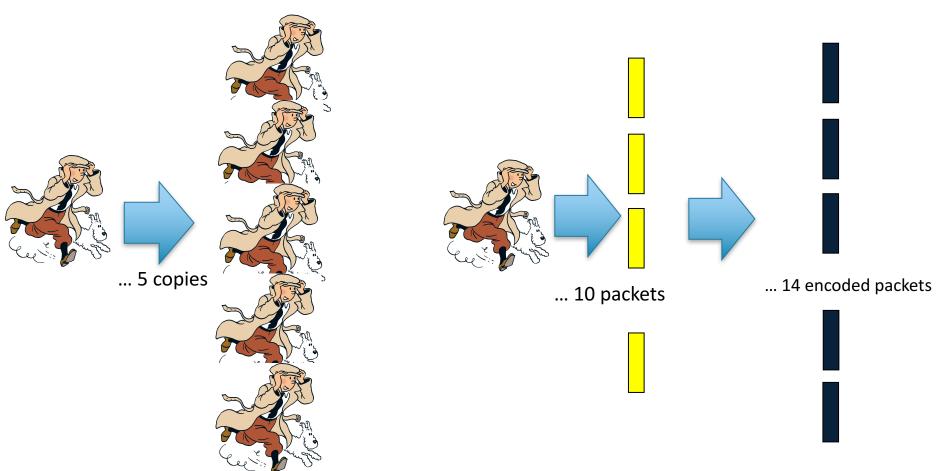
Can solve for the coefficients from any k coded symbols

Example: (4,2) Reed-Solomon Code

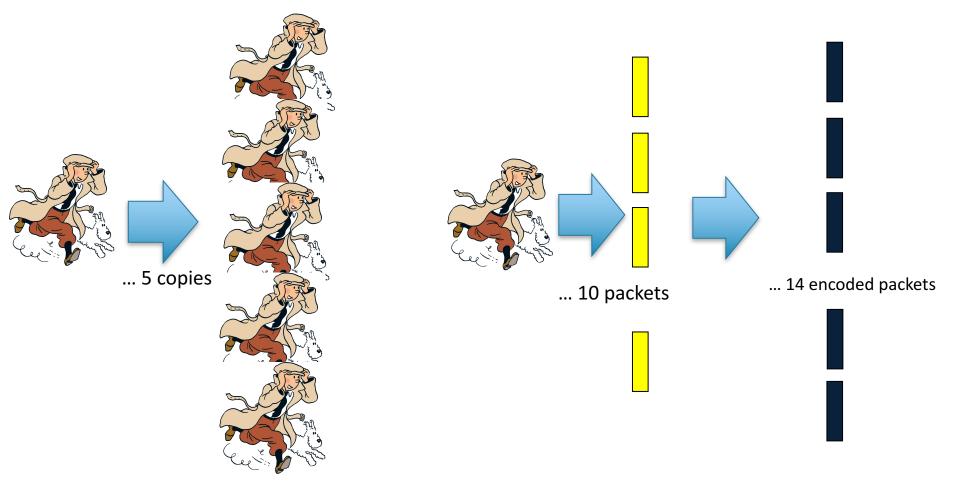


- Can solve for the coefficients from any k coded symbols
- Microsoft uses (7, 4) code
- Facebook uses (14,10) code

Coding vs Replication

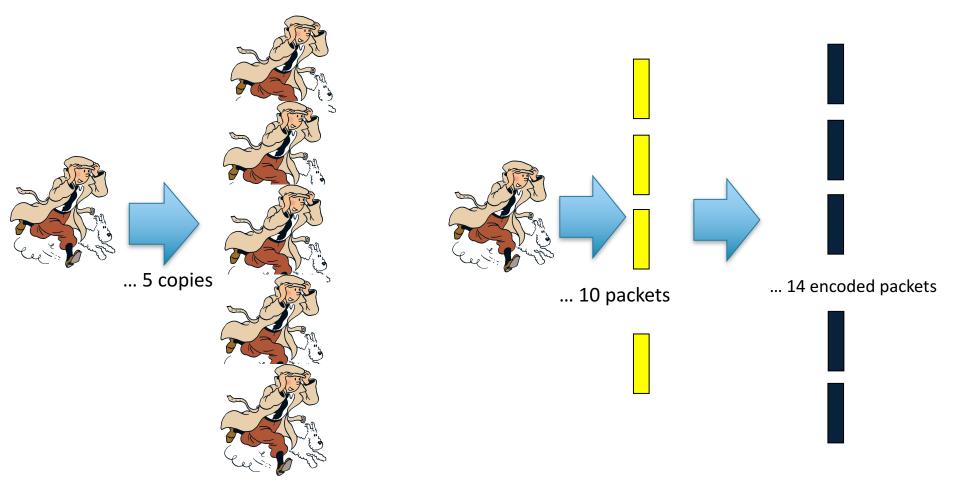


Concept Check: Coding vs Replication



- How many node-failures can each system tolerate?
- \circ $\,$ What is the code rate of each system?

Concept Check: Coding vs Replication



- How many node-failures can each system tolerate?: 4
- What is the code rate of each system? 1/5 and 10/14
- Replication uses 357% more storage for the same reliability!

Outline

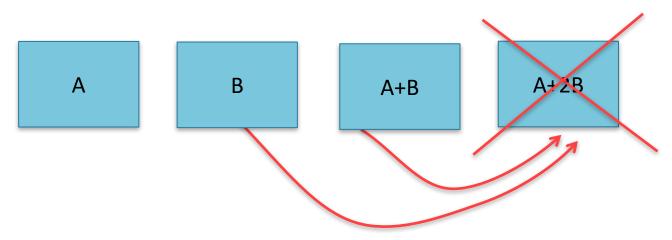
Coded Distributed Storage

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Locality and Repair Issues

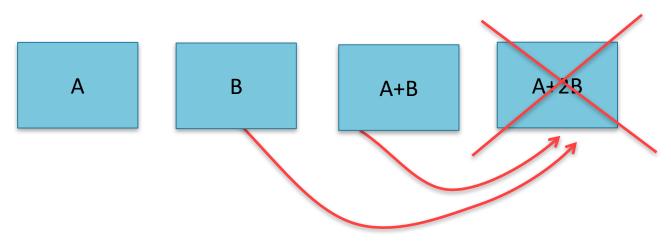
- Most distributed storage systems still use replication (21x in Gmail!)
- Repairing failed nodes is hard with Reed-Solomon Codes..



- If we lose 1 node :
 - Need to contact k other nodes
 - Need to download k times the lost data

Locality and Repair Issues

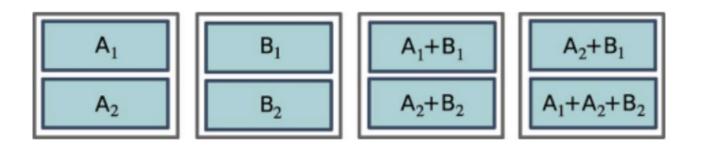
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Locality and Repair Issues

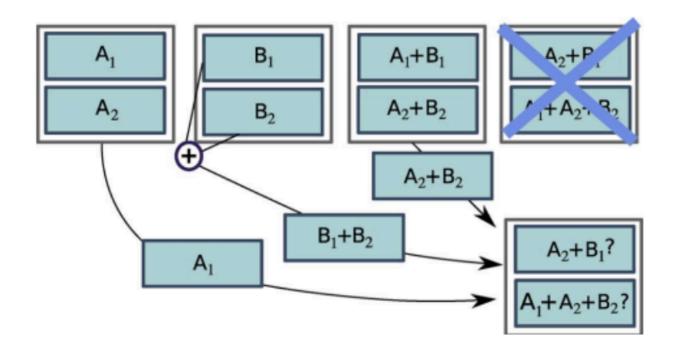
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- If we lose 1 node:
 - Need to contact k other nodes
 - Need to download k times the lost data

Solution: Regenerating Codes

- Codes designed to minimize:
 - o Repair Bandwidth
 - Number of nodes contacted



Exact vs Functional Repair

Exact repair

Repair the failed nodes exactly

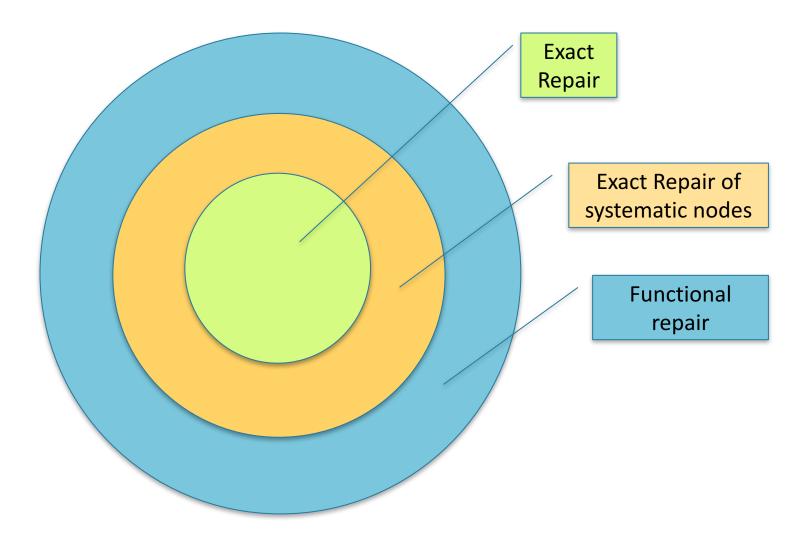
Functional repair

New data should be equivalent to the old for repair purposes, that is, k out of n nodes are still enough for repair

Exact repair of systematic nodes

Systematic nodes should be repaired exactly. Other notes may be repaired functionally

Exact vs Functional Repair

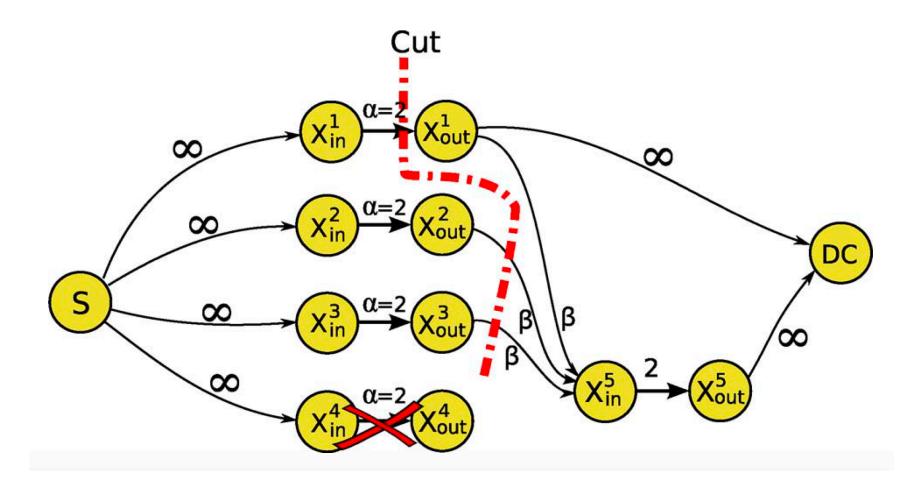


Model 1: Functional Repair

- \circ File of size M, stored on n nodes, with α bits per node
- A failed node can be repaired using any d surviving nodes
- \circ Each of the d nodes send β bits to repair it
- \circ Repair bandwidth = $\gamma = d\beta$

[Dimakis et al 2008] studies the fundamental trade-off b/w Storage per node: α and Repair bandwidth: γ

Information flow graph model



The min-cut needs to larger than M in order to recover the file

[Dimakis et al 2008]:

Theorem 1: For any $\alpha \geq \alpha^*(n, k, d, \gamma)$, the points $(n, k, d, \alpha, \gamma)$ are feasible, and linear network codes suffice to achieve them. It is information theoretically impossible to achieve points with $\alpha < \alpha^*(n, k, d, \gamma)$. The threshold function $\alpha^*(n, k, d, \gamma)$ is the following:

$$\alpha^*(n,k,d,\gamma) = \begin{cases} \frac{\mathcal{M}}{k}, & \gamma \in [f(0), +\infty) \\ \frac{\mathcal{M}-g(i)\gamma}{k-i}, & \gamma \in [f(i), f(i-1)), \end{cases}$$
(1)

where

$$f(i) \stackrel{\Delta}{=} \frac{2\mathcal{M}d}{(2k-i-1)i+2k(d-k+1)},$$

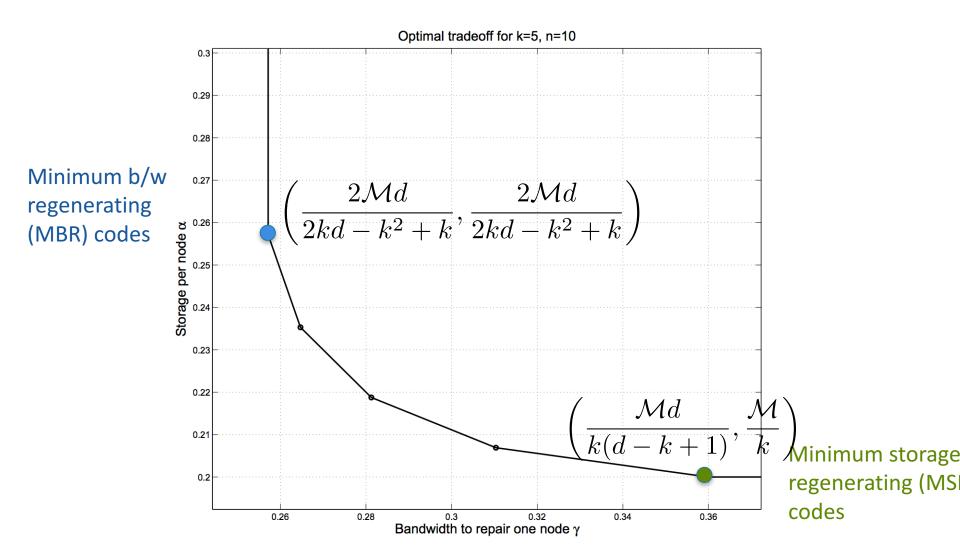
$$g(i) \stackrel{\Delta}{=} \frac{(2d-2k+i+1)i}{2d},$$
(2)
(3)

where $d \leq n-1$. For d, n, k given, the minimum repair bandwidth γ is

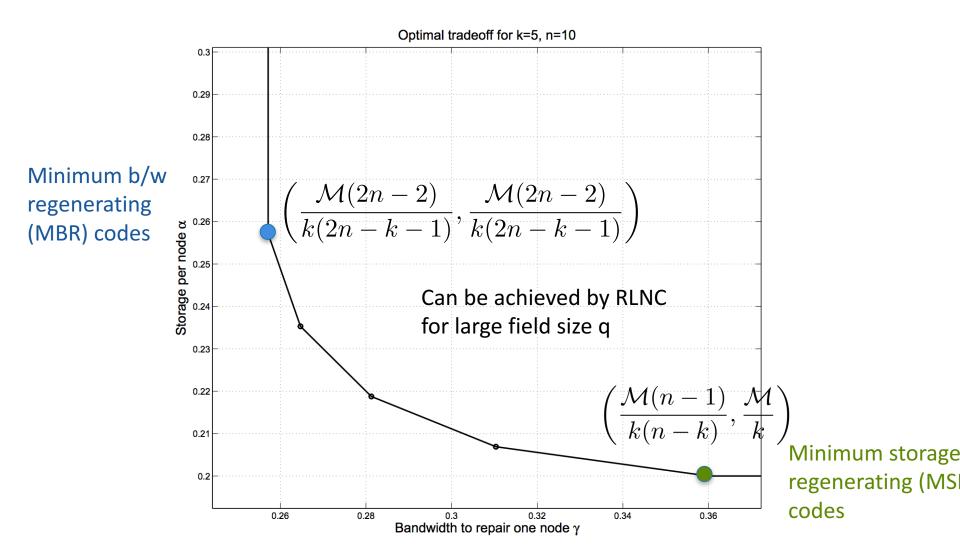
Decreases with d,
minimum at d = n-1
$$\gamma_{\min} = f(k-1) = \frac{2\mathcal{M}d}{2kd-k^2+k}$$
 (4)

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Storage-Bandwidth Trade-off



Storage-Bandwidth Trade-off

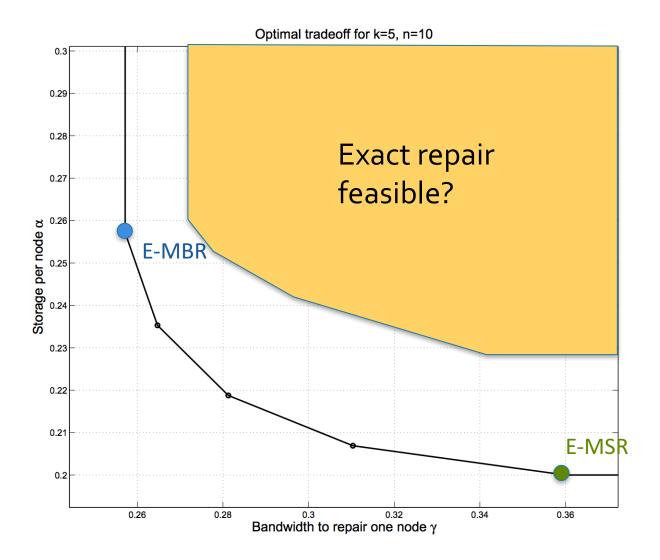


Concept Check: Min. Repair Bandwidth

Consider a file of size 1 Mb stored using an (7,4) code.

- 1. What is the repair-bandwidth of an (7,4) MDS code? How much data is stored at each node?
- 2. What is the min. possible repair bandwidth, for the same storage per node?

Model 2: Exact Repair

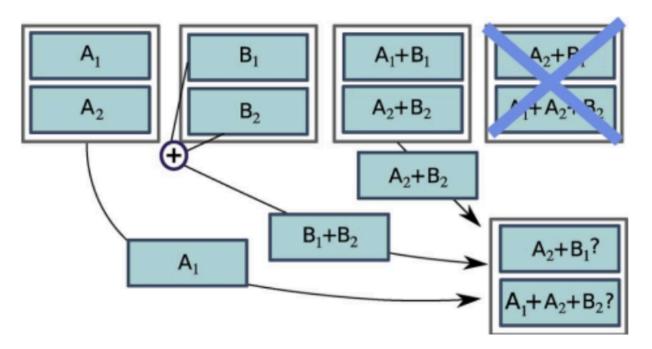


Exact Repair Code Constructions

- For (n,k=2) E-MSR repair can match cutset bound. [WD ISIT'09]
- (n=5,k=3) E-MSR systematic code exists [Cullina,Dimakis, Ho, Allerton'09]
- For k/n <=1/2 E-MSR repair can match cutset bound [Rashmi, Shah, Kumar, Ramchandran (2010)]
- [Cadambe, Jafar, Maleki] proposed codes to achieve the E-MSR point for all (k,n,d).
- E-MBR for all n,k, for d=n-1 matches cut-set bound [Suh, Ramchandran (2010)]

Locally Repairable Codes

- Codes designed to minimize:
 - o Repair Bandwidth
 - Number of nodes contacted [Gopalan 2012, Papailiopoulos 2014]



Locally Repairable Codes

o (n, r, d, M, α) LRC

- Repair a failed node from r other nodes
- Trade-off between the distance d and locality r

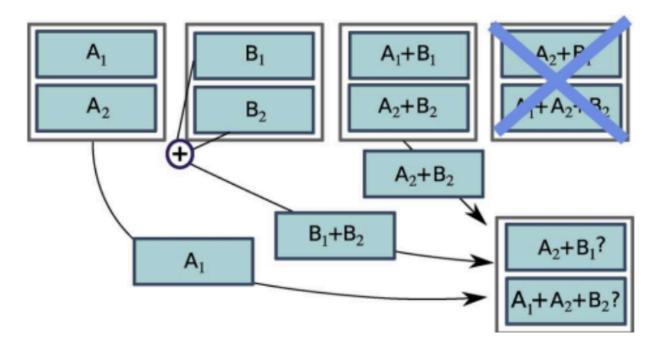
[Papailiopoulos et al 2014]:

Theorem 1. An (n, r, d, M, α) -LRC has minimum distance d that is bounded as

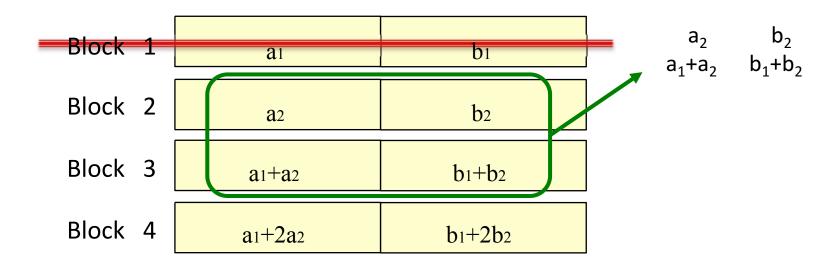
$$d \le n - \left\lceil \frac{M}{\alpha} \right\rceil - \left\lceil \frac{M}{r\alpha} \right\rceil + 2.$$

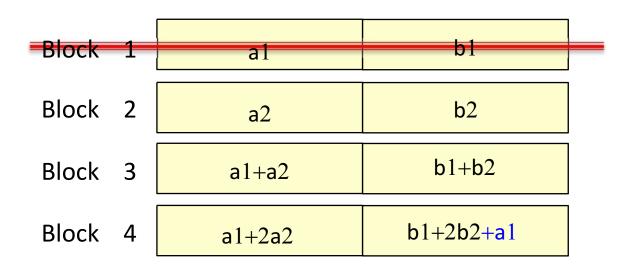
Data I/O considerations

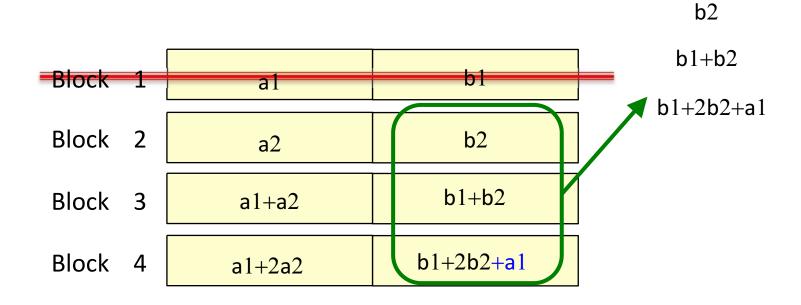
Piggybacking codes [Rashmi et al 2012, 13, 15]

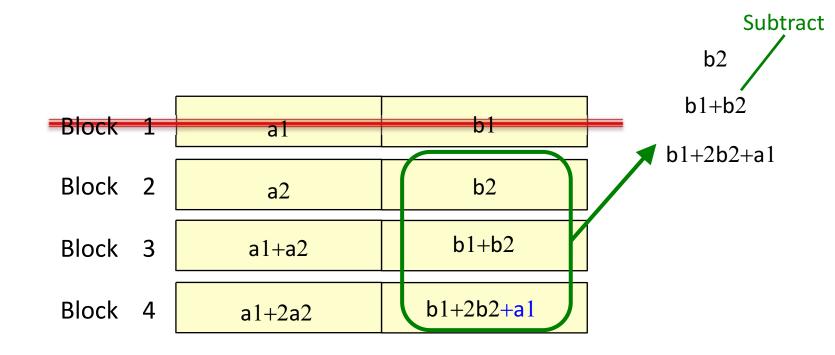


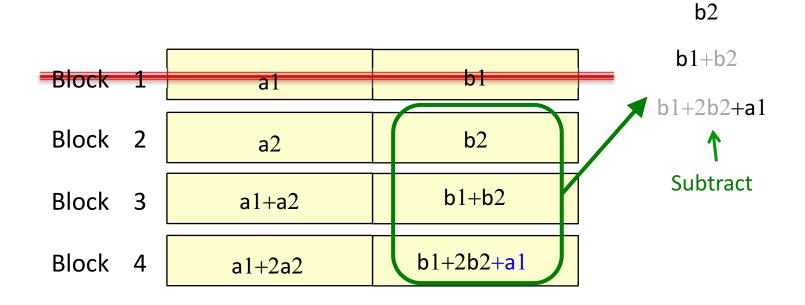
- Data I/O from disk = 4 blocks
- Repair Bandwidth = 3 blocks











Piggybacking Codes General Case

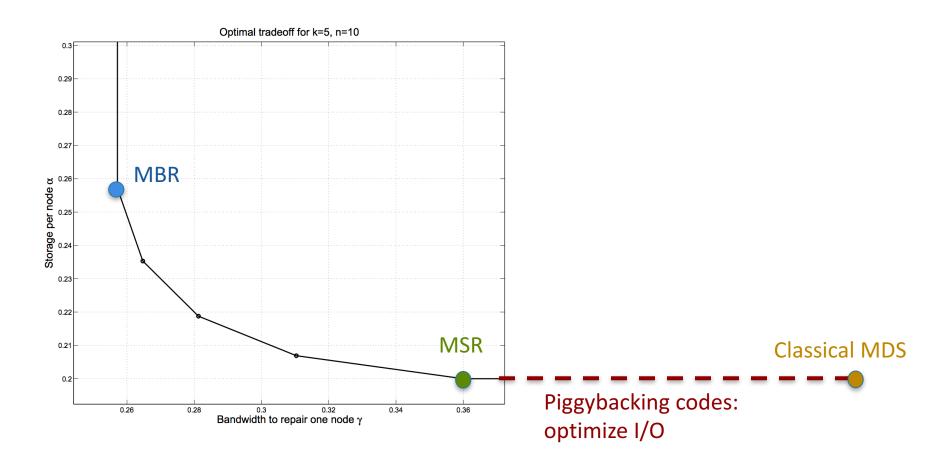
Node 1
$$f_1(\mathbf{a})$$
 $f_1(\mathbf{b})$ \cdots $f_1(\mathbf{z})$ \vdots \vdots \vdots \ddots \vdots Node n $f_n(\mathbf{a})$ $f_n(\mathbf{b})$ \cdots $f_n(\mathbf{z})$



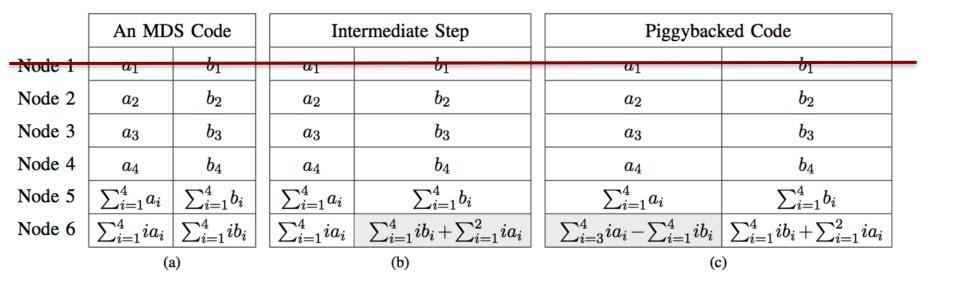
Node 1	$f_1(\mathbf{a})$	$f_1(\mathbf{b}) + g_{2,1}(\mathbf{a})$	$f_1(\mathbf{c})+g_{3,1}(\mathbf{a},\mathbf{b})$	••••	$f_1(\mathbf{z}) + g_{lpha,1}(\mathbf{a},\ldots,\mathbf{y})$
÷	:	:	:	•••	:
Node n	$f_n(\mathbf{a})$	$f_n(\mathbf{b}) + g_{2,n}(\mathbf{a})$	$f_1(\mathbf{c}) + g_{3,n}(\mathbf{a},\mathbf{b})$		$f_n(\mathbf{z}) + g_{lpha,n}(\mathbf{a},\dots,\mathbf{y})$

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Piggybacking Codes



Concept Check: Piggybacking Codes How many symbols need to be read to repair node 1?



Needs 8 symbols to repair

Needs 6 symbols to repair

Outline

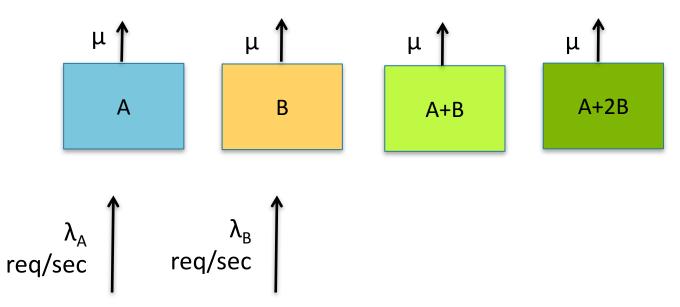
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Repair-efficiency

Service Capacity

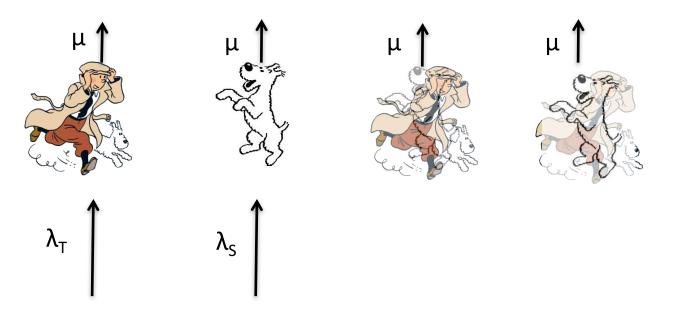
Problem Formulation

- Users may want to access only one of the two chunks
- Applications: Netflix or any content hosting system
- How many requests can we simultaneously support?



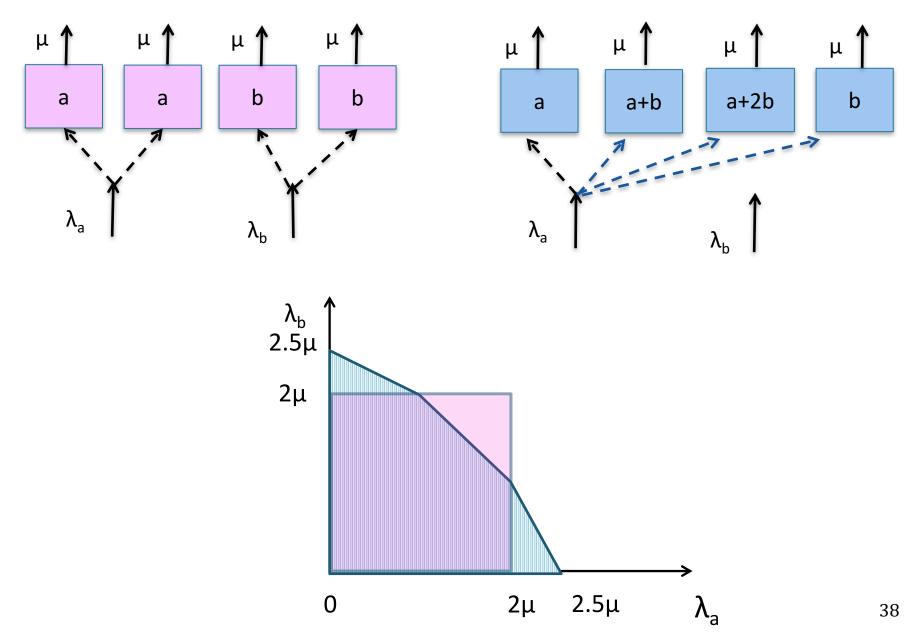
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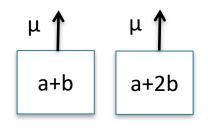


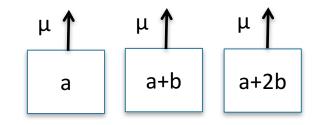
• What is the set of arrival rates (λ_T , λ_s) that we can support?

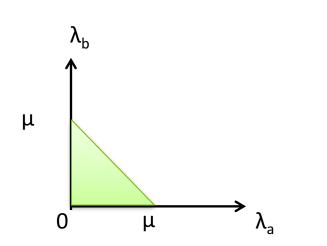
Replication Vs. Coding [Anderson et al 2017]

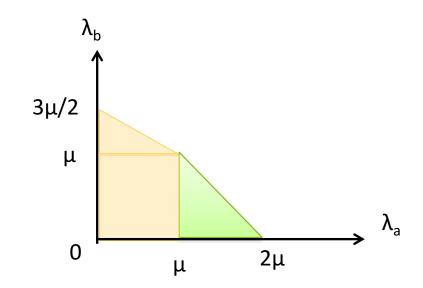


Adding Uncoded Nodes [Anderson et al 2017]

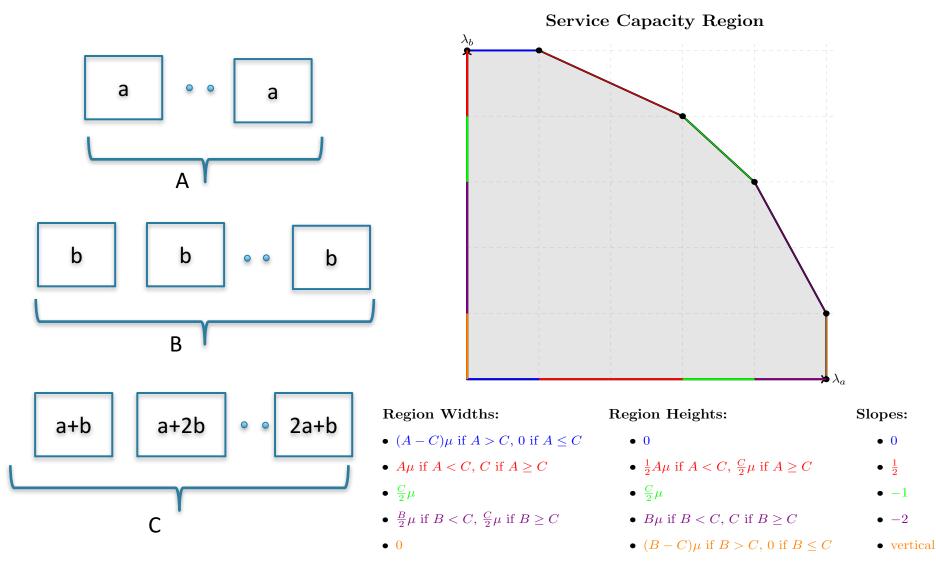




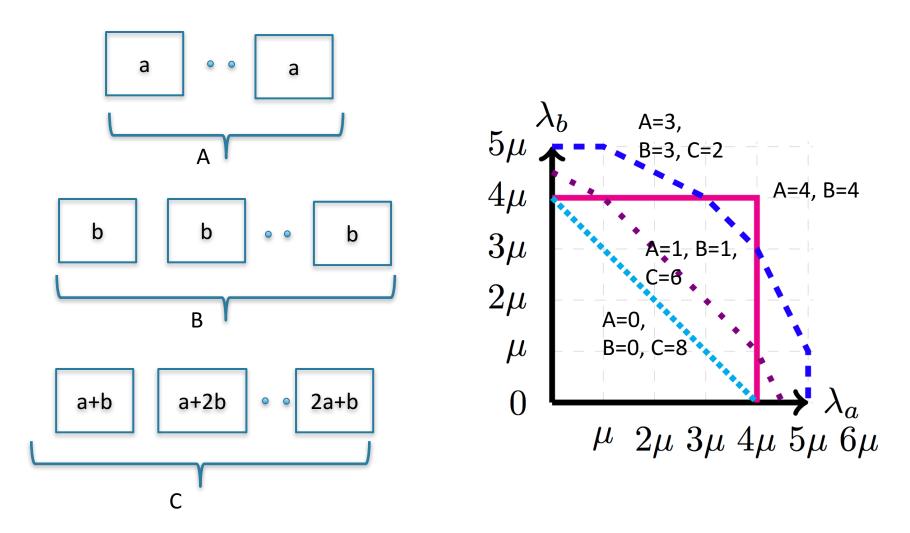




Service Capacity of Coded Storage [Anderson et al 2017]

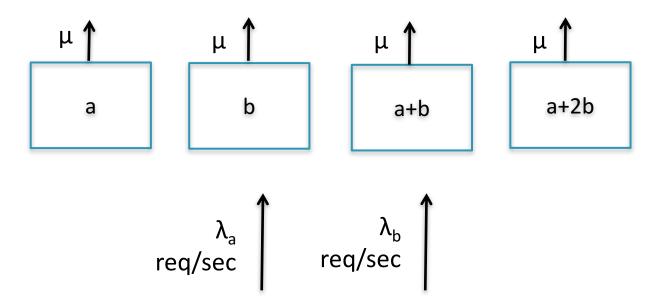


Service Capacity of Coded Storage [Anderson et al 2017]



Maximizing Service Capacity: k files, n nodes

- O1: Given a code, how to optimally split the requests?
- **Q2**: What is the best underlying erasure code?



Other considerations

Latency Security Update-efficiency

Next Lecture: Coded Computing

Approx. Computing Matrix-vector & matrix-matrix mult. Distributed Machine Learning