

Goals for today ...

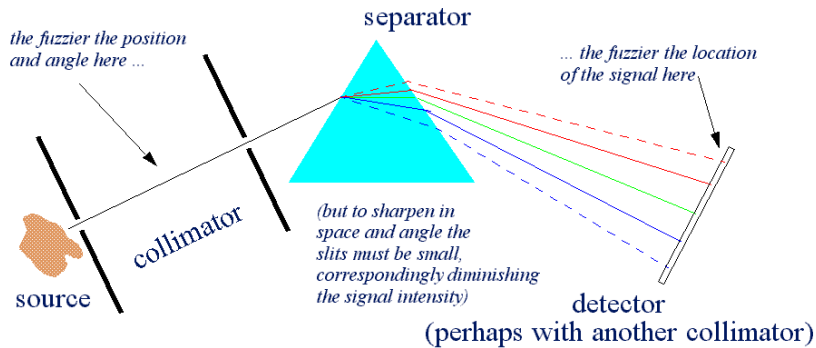
- Spectroscopic techniques and algorithms
- Instruments and algorithms for contraband detection
 - vapor detection techniques (mostly chemistry)
 - bulk detection techniques (mostly physics)

Spectroscopies

- Signal as a function of some dispersion parameter
 - retention time (chromatographies)
 - drift time (ion mobility spectroscopy)
 - wavelength (optical spectroscopy)
 - frequency (NMR, NQR, ESR)
 - photon energy (x-ray, γ -ray spectroscopies)
 - particle energy (photoelectron energy spectroscopy)
 - ion mass (mass spectroscopies)
- Always three functions, usually three modules:
 - source
 - dispersion element
 - detector

Principle of Conservation of Misery

- There is an inevitable tradeoff between your ability to separate spectral components (resolution) and your ability to detect small quantities (sensitivity)

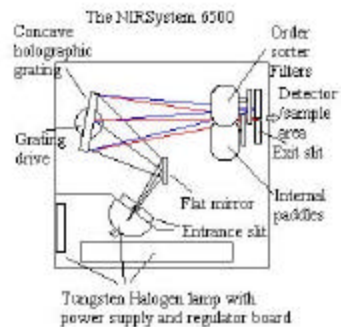
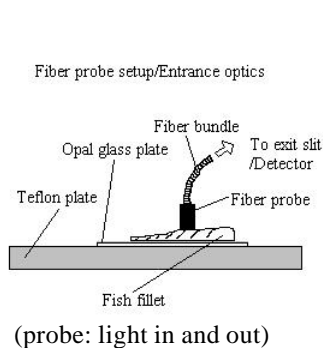


4/23/01 4:53 PM
for 2001-Apr-26

L2001-13-02

3 of 33

Example: VIS-NIR Diffuse Reflectance Spectrum to Measure Fish Freshness



(monochromator: specific color light out)

4/23/01 4:53 PM
for 2001-Apr-26

L2001-13-02

4 of 33

What's This GC Gizmo?

- Pipe coated (or packed with grains that are coated) with a “sticky” liquid ...
- Inert gas (e.g., He) flows through the pipe (“column”)
- Mixture (e.g., gasoline) squirted into “head”
- Gas (“mobile phase”) carries it over the liquid (“stationary phase”)

4/23/01 4:53 PM
for 2001-Apr-26

L2001-13-02

5 of 33

- Mixture components move at different velocities due to different equilibria between mobile and stationary phases
- Components emerge at column “tail”: detect with a “universal” detector, or use as inlet to mass spectrometer or other instrument
- MANY similar techniques: liquid chromatography, ion mobility chromatography, electrophoresis, and (the original) color-band based chromatography (hence the name)

4/23/01 4:53 PM
for 2001-Apr-26

L2001-13-02

6 of 33

What's this MS Gizmo?

- *Usually* a separation based on mass of positive ions; sometimes negative ions, rarely neutrals
- *Usually* all the ions are accelerated (and filtered) to the same energy
- Velocity thus depends on mass: $v = \text{Sqrt}(2 W/m)$
- Velocity can be measured by time-of-flight, by trajectory in a magnetic field, etc, in many different geometries

4/23/01 4:53 PM
for 2001-Apr-26

L2001-13-02

7 of 33

- Smaller lower cost alternative: quadrupole mass spectrometers
 - ions move under combined influence of DC and oscillating (RF) electric fields; most orbits are unbounded, but for any particular mass there is a small region in the DC/RF amplitude plane where they are bounded (analogous to the inverted pendulum)

4/23/01 4:53 PM
for 2001-Apr-26

L2001-13-02

8 of 33

Spectroscopies: Algorithms

4/23/01 4:53 PM
for 2001-Apr-26

L2001-13-02

9 of 33

Unraveling Overlapping Spectra

- Absent separation (like GC), given the spectrum of a mixture, how best to unravel its components when the component spectra all overlap?
 - $S_1 = \{s_{11}, s_{12}, s_{13}, \dots, s_{1n}\}$
1 = hexane, $\{1,2,3,\dots,n\}$ = peak IDs
 - $S_2 = \{s_{21}, s_{22}, s_{23}, \dots, s_{2n}\}$
2 = octane, $\{1,2,3,\dots,n\}$ = same peak IDs
 - ... etc
 - $S_m = \{s_{m1}, s_{m2}, s_{m3}, \dots, s_{mn}\}$
m = Xane, $\{1,2,3,\dots,n\}$ = same peak IDs

4/23/01 4:53 PM
for 2001-Apr-26

L2001-13-02

10 of 33

- Consider the inverse problem: given the concentrations, it is straightforward to predict what the combined spectrum will be:

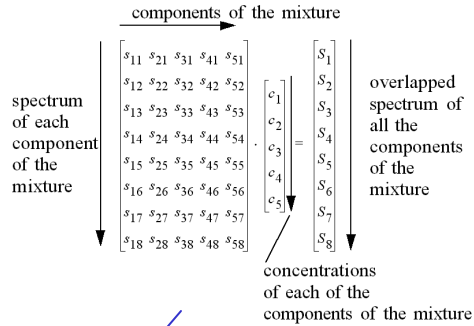
$$C = \{c_1, c_2, c_3, \dots, c_m\},$$

1 = hexane, 2 = octane,
 ..., m = Xane

$$S = c_1 S_1 + c_2 S_2 + c_3 S_3$$

$$+ \dots + c_m S_m$$

- Or in matrix notation:



- If we look at only as many peaks as there are components then the matrix is square, and it is easy: $c = S^{-1} S$
- If we have fewer peaks than components then we are up the creek.
- If we have more peaks than components then what to do?
- More peaks than components means we have “extra data” that we can use to improve the precision of our result.

Pseudo-Inverse Method

- The trick is to multiply both sides of the equation by s^T :

$$\begin{aligned}
 & - s \quad \quad \quad c \quad \quad \quad = S \\
 & \quad (n_{\text{peaks}} \times n_{\text{components}}) (n_{\text{components}} \times 1) = (n_{\text{peaks}} \times 1) \\
 & - s^T s c = s^T S \\
 & \quad (n_{\text{components}} \times n_{\text{peaks}}) (n_{\text{peaks}} \times n_{\text{components}}) (n_{\text{components}} \times 1) \\
 & \quad = (n_{\text{components}} \times n_{\text{peaks}}) (n_{\text{peaks}} \times 1) \\
 & - \text{note that } s^T s \text{ is square, hence it (generally) has an} \\
 & \quad \text{inverse}
 \end{aligned}$$

- $$\begin{aligned}
 & - c = (s^T s)^{-1} s^T S \\
 & \quad (n_{\text{components}} \times 1) = \\
 & \quad (n_{\text{components}} \times n_{\text{components}})^{-1} (n_{\text{components}} \times n_{\text{peaks}}) (n_{\text{peaks}} \times 1) \\
 & - \text{called the "pseudo-inverse method"}
 \end{aligned}$$
- Calculated component concentrations are optimal: equivalent to least squares fitting
 - i.e., algebraic least squares fit gives the same result as matrix solution using pseudo-inverse formalism
 - (Yes, of course, there are degenerate cases where $s^T s$ doesn't actually have an inverse, or calculating it is unstable; then you need to use better judgement in deciding which peaks to use!)

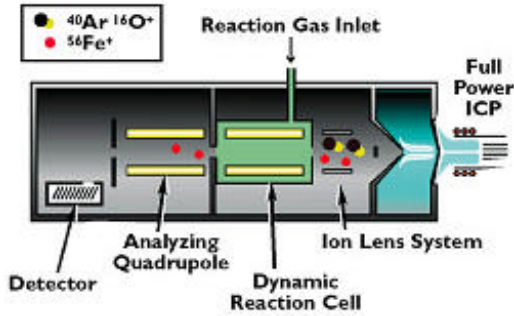
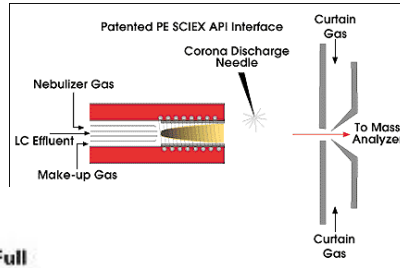
Caution ...

- $c = (s^T s)^{-1} s^T S$ is the same as the optimal result you would get if you minimized the sum of the squares of the differences between the components of the data set S and a “predicted” data set $S = s c$:
 - $\Sigma = \text{Sum}((s c - S)_i \text{ over all } n_{\text{peaks}} \text{ spectral peaks})$
 $d\Sigma / dc_j = 0$ gives $n_{\text{components}}$ simultaneous equations which when you solve them for $\{c\}$ gives the same result as the pseudo-inverse

- But (to keep the notation and discussion simple) *I've left something out*: as in our previous discussion about how to combine multiple measurements that have different associated uncertainties, you need to weight each datum by a reciprocal measure of its uncertainty, e.g., $1/\sigma_i^2$ (in both the least-squares and the pseudo-inverse formulations).

Tandem Technologies

*note analogy to image processing:
not one magic bullet, but a clever
chain of simple unit operations*



4/23/01 4:53 PM
for 2001-Apr-26

L2001-13-02

17 of 33

Miniaturization



Ocean Optics:
optical spectrometer
optics and electronics
on a PC card; separate
light source (below),
and fiber optic (blue)
light input path

4/23/01 4:53 PM
for 2001-Apr-26

L2001-13-02

18 of 33

Contraband Detection

System issues when you have to detect something that probably isn't there

4/23/01 4:53 PM
for 2001-Apr-26

L2001-13-02

19 of 33

Pod (Probability of Detection) FAR (False Alarm Rate)

- Illustrative problem: a town has 10 blue taxis, 90 black taxis; a man reports a hit-and-run accident involving a blue taxi; tests show he correctly identifies taxi color 80% of the time; what is the probability that the taxi he saw was actually blue?
- First thought: 80%.

4/23/01 4:53 PM
for 2001-Apr-26

L2001-13-02

20 of 33

- Second thought: you should ask how often he is correct when he says he saw a blue cab. If the cab really was blue, he reports 8 blue cabs out of 10 blue; if the cab really was black, he reports 18 blue cabs out of 80 that are actually black. So when he reports a blue cab he is correct only $(8/(8+18)) = 31\%$ of the time!
- (see <http://www.maa.org/devlin/devlinjune.html>)

Bayes Theorem

- We start with an *a priori* estimate from previous experience, etc.
Then we receive additional information from an observation.
How do we update our estimate?
- $P(\text{blue})=0.10$, $P(\text{black})=0.90$ [etc., total 1., for possibilities >2]
- $P(\text{say it is blue} \mid \text{if it is blue}) = 0.80$,
 $P(\text{say it is blue} \mid \text{if it is black}) = 0.20$,
 $P(\text{it is blue} \mid \text{if say it is blue}) = ?$

$$P(\text{itisblue}|\text{if say it is blue}) = \frac{P(\text{itisblue})P(\text{say it is blue}|\text{if it is blue})}{P(\text{itisblue})P(\text{say it is blue}|\text{if it is blue}) + P(\text{itisblack})P(\text{say it is blue}|\text{if it is black})}$$

Bayes Theorem

$$P(X|A) = \frac{P(X)P(A|X)}{P(X)P(A|X) + P(Y)P(A|Y) + P(Z)P(A|Z)}$$

4/23/01 4:53 PM
for 2001-Apr-26

L2001-13-02

23 of 33

Airport Explosives Sniffer

- $P(\text{alarm} | \text{if bomb}) = 0.80$ (PoD)
 $P(\text{alarm} | \text{if no_bomb}) = 0.01$ (PFA)
 $P(\text{bomb}) = 0.000001$
 $P(\text{no_bomb}) = 0.999999$
- An alarm goes off; what is the probability of a real bomb?
- $P(\text{bomb} | \text{if alarm}) = \frac{P(\text{bomb}) P(\text{alarm} | \text{if bomb})}{P(\text{bomb}) P(\text{alarm} | \text{if bomb}) + P(\text{no_bomb}) P(\text{alarm} | \text{if no_bomb})}$

4/23/01 4:53 PM
for 2001-Apr-26

L2001-13-02

24 of 33

- $P(\text{bomb} \mid \text{if alarm}) = 0.00007994 \approx 0.00008$
(false alarm rate is 99,992/100,000)
- $P(\text{bomb} \mid \text{if alarm}) = 0.5$ when $P(\text{alarm} \mid \text{if no_bomb}) = 0.8 \times 10^{-6}$

Try this one ...

- A commercial system reports NG, RDX, PETN, TNT, Semtex, HMX.
- Terrorists use $P(\text{NG})=0.15$, $P(\text{RDX})=0.10$, $P(\text{PETN})=0.20$, $P(\text{TNT})=0.05$, $P(\text{Semtex})=0.25$, $P(\text{HMX})=0.05$, $P(\text{OTHER})=0.20$.
- The instrument characteristics are $P(\text{NG_alarm} \mid \text{if NG})=0.80$, $P(\text{RDX_alarm} \mid \text{if RDX})=0.85$, $P(\text{PETN_alarm} \mid \text{if PETN})=0.60$, $P(\text{TNT_alarm} \mid \text{if TNT})=0.75$, $P(\text{Semtex_alarm} \mid \text{if Semtex})=0.90$, $P(\text{HMX_alarm} \mid \text{if HMX})=0.70$, $P(\text{some_alarm} \mid \text{if other})=0.30$, $P(\text{wrong_alarm} \mid \text{if any_of_the_six})=0.05$, $P(\text{some_alarm} \mid \text{if no_explosive})=0.01$

- One piece of luggage out of a million contains actual explosive.
- When an alarm goes off, what is the probability that some explosive is actually present in the luggage?