

Data Semantics, Sketches and Q-Trees

Category Theory Octoberfest

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Background and Perspective

● Project Experience

- Consultant: Senior Hadoop Analyst for PNC Financial Services. 2015
- Consultant: Statistical analysis and model development for Flexible Plan Investments, Bloomfield Hills, MI. 2014–2016
- Established Shepherd Laboratory for Big Data Analytics
- Co-Investigator with S. Bringsjord (RPI) and J. Hummel (UIUC): *Great Computational Intelligence*. AFOSR. 2011–14
- PI with N. Yanofsky (CUNY): *Quantum Kan Extensions*. IARPA. 2011–12
- Analyst. *Passive Sonar Algorithm Development*. ONR. 2010
- Technical Lead. *Exposing/Influencing Hidden Networks*. ONR. 2009–10
- PI: *Robust Decision Making*. AFOSR. 2008–2010
- Analyst: *TradeNet Integration into Global Trader*. ONI. 2009
- PI with S. Awodey (CMU): *Categorical Logic as a Foundation for Reasoning Under Uncertainty*. Phase I–II SBIR. MDA. 2005–8

Aspects of Knowledge Technologies

- Mathematical Logic (1879)
 - Availability of automated theorem provers (Prover9, Vampire, ...)
 - High computational complexity of some predicate calculus fragments
 - Complexity of the syntactic category used for knowledge alignment
 - Challenging to develop a human interface
- Databases + SQL (1968)
 - Excellent software infrastructure
 - Limited notion of context/view (a single table), static schema, ...
- Semantic Web OWL/RDF + Description Logic (1999)
 - Excellent software infrastructure (Apache Jena, Protégé, ...)
 - Lack of modularity: meta-data, instance data and uncertainty integrated into a monolithic ontology
 - Limited compositional algebra: (disjoint) unions of ontologies
 - Need for constraint-preserving maps
- Sketch Theory (1968/2000) + Q-Trees (1990)
 - Few software tools (however, see www.mta.ca/~rrosebru/project/Easik)
 - Mature mathematical framework including sketch and model maps
 - Visual/graphical modeling
 - Deduction system?

Sketches: Historical Timeline

- 1943: Eilenberg and Mac Lane introduce category theory
- 1958: Kan introduces the concept of adjoints
- 1963: Lawvere characterizes quantifiers and other logical operations as adjoints
- 1968: C. Ehresman introduces sketch theory
- 1985: KL-ONE — First implementation of a description logic system
- 1985: Barr and Wells publish *Toposes, Triples and Theories*
- 1989: J. W. Gray publishes *Category of Sketches as a Model for Algebraic Semantics*
- 1990: Barr and Wells publish *Categories for Computing Science*
- 1995: Carmody and Walters publish algorithm for computing left Kan extensions
- 1999: [RDF becomes a W3C recommendation](#)
- 2000: [Johnson and Rosebrugh apply sketch data model to database interoperability](#)
- 2000: DARPA begins development of DAML
- 2001: Dampney, Johnson and Rosebrugh apply sketches to view update problem
- 2001: W3C forms the Web-Ontology Working Group
- 2004: RDFS and OWL become W3C recommendations
- 2008: Johnson and Rosebrugh release Easik software
- 2009: OWL2 becomes a W3C recommendation
- 2012: Johnson, Rosebrugh and Wood use sketches to formulate lens concept of view updates

Sketch $(G, \mathcal{D}, \mathcal{L}, \mathcal{C})$

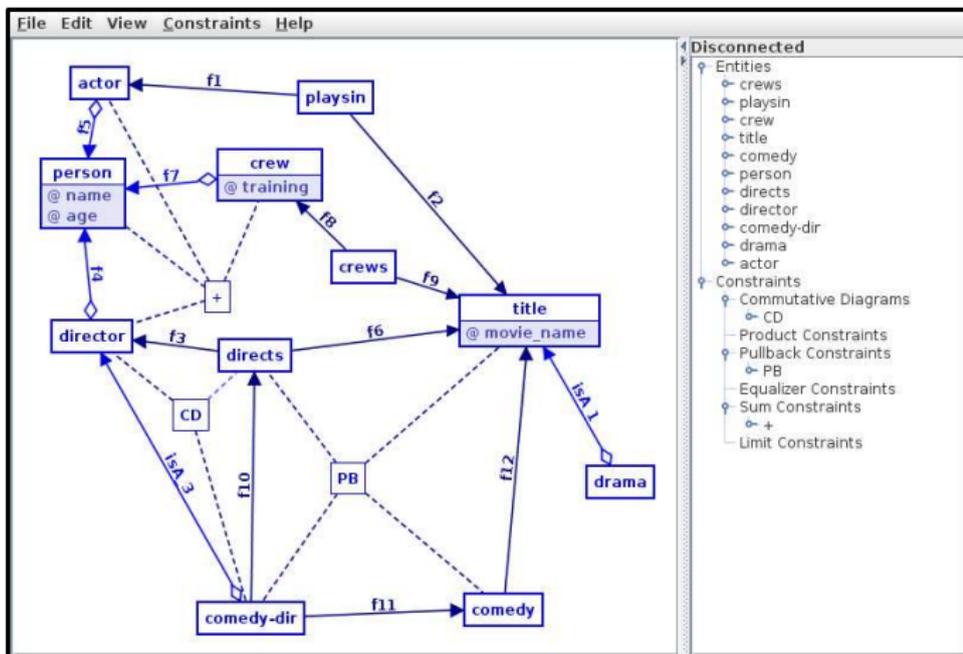
- All semantic constraints in a sketch are expressed using graph maps.
- A **sketch** $(G, \mathcal{D}, \mathcal{L}, \mathcal{C})$ consists of:

An underlying **graph** G and sets

\mathcal{D} of **diagrams** $B \rightarrow G$

\mathcal{L} of **cones** $L \rightarrow G$

\mathcal{C} of **cocones** $C \rightarrow G$



Categorical Semantics of Sketches

- **Vertices** are interpreted as objects
- **Edges** are interpreted as morphisms
- Classes of **constraints** (cones and cocones) are distinguished by the shapes of their base graphs.
- Classes of sketches are distinguished by their classes of constraints.
- Like logics and OWL species, these have different expressive powers.

Small sample of the sketch semantics landscape

Sketch Class	Set	Partial Func.	Stoch. Matrices	Čencov Cat.	Prob. 0 Refl.	Dempster Shafer	Fuzzy Sets	Convex Sets
linear	●	●	●	●	●	●	●	●
Finite Limit	●	●	×	×	×	×	●	●
Finite Coproduct	●	●	●	●	●	●	●	●
Entity-Attribute	●	●	×	×	×	×	●	●
Mixed	●	●	×	×	×	×	●	●

Questions

- EA sketch instance data (models) can be implemented using relational database features such as foreign keys and triggers.
- What features are required to store instance data for more expressive classes of sketches?
- What technologies support management of large, distributed models of sketches?
- How would relevant algorithms need to be reformulated in a distributed setting?

Presentations

- A sketch | first-order theory | ontology is a **presentation** of knowledge.
- Presentations **generate** additional knowledge needed for alignment (e.g., 'uncle = brother \circ parent')

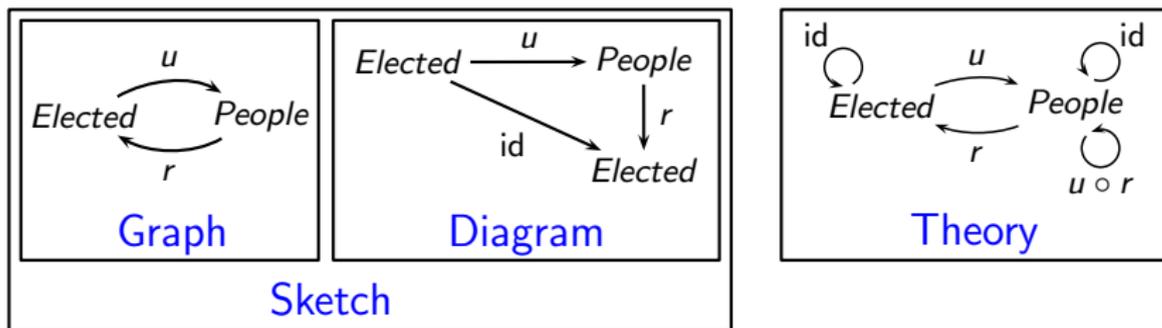
Framework	Alignment Tool
Ontology	rules
Sketch \mathbb{S}	theory of a sketch $\mathcal{T}(\mathbb{S})$
Logical theory \mathbb{T}	syntactic category $\mathcal{C}_{\mathbb{T}}$

- Different presentations may generate 'equivalent' structures.
- Theory of a (linear) sketch
 - Carmody-Walters algorithm for computing left Kan extensions: generalizes Todd-Coxeter procedure used in computational group theory
 - Complexity difficult to characterize: can depend on order of constraints

Civics Sketch \mathbb{S}_1

First formulation of a civics concept:

- Two classes: People and Elected officials
- People have Elected representatives via r .
- Elected officials are instances of people via u .
- Elected officials represent themselves via a diagram.



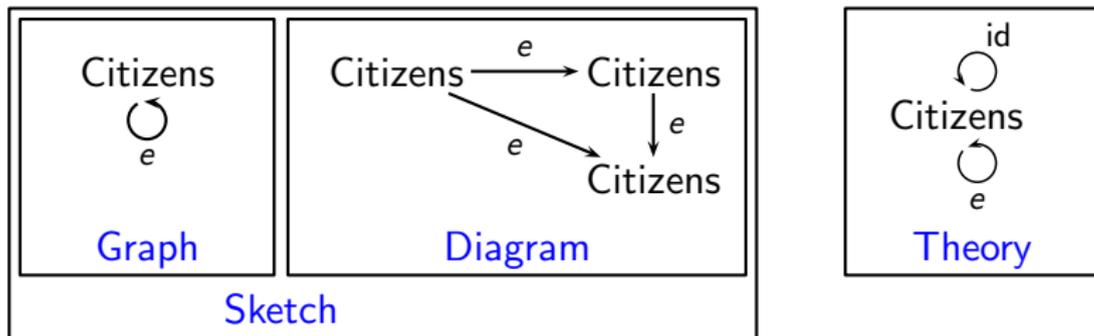
- The diagram truncates the infinite list of composites (property chains).

$$u \circ r \quad r \circ u \quad u \circ r \circ u \quad r \circ u \circ r \quad \dots$$

Civics Sketch \mathbb{S}_2

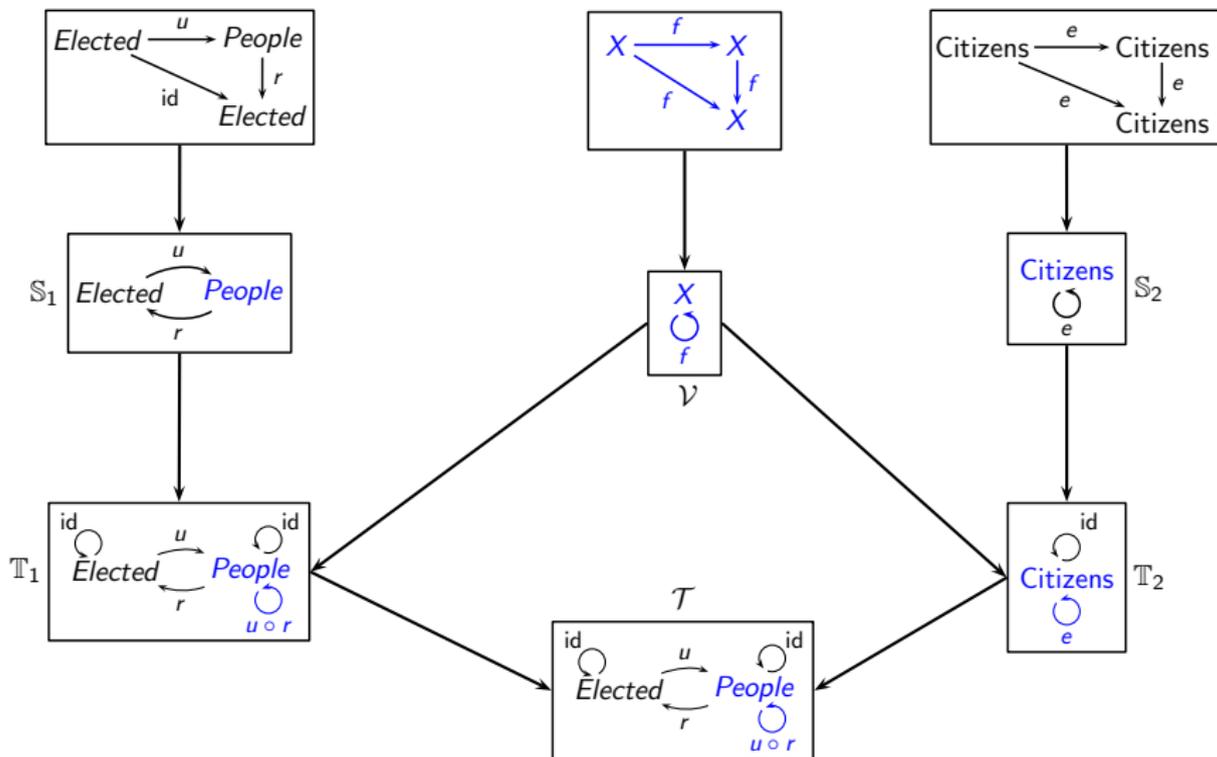
Alternative formulation of the civics concept:

- One class: Citizens
- Citizens have elected representatives via e .
- Elected officials represent themselves via a diagram.



- Number and names of vertices in \mathbb{S}_1 and \mathbb{S}_2 differ.
- The edges u and r of \mathbb{S}_1 have no corresponding edges in \mathbb{S}_2 .
- The edge e of \mathbb{S}_2 has no corresponding edge in \mathbb{S}_1 .

Alignment of the Civics Sketches



Sketch Alignment: Questions

- What algorithms are available for computing the theory of a sketch?
 - Carmody-Walters for linear sketches
 - Others?
 - Lazy algorithms?
- To what extent can the sketch alignment problem be automated?
 - Find appropriate intersection(s)/views
 - Rename of vertices and edges
- Can instance data be used to support sketch alignment?

First-Order Civics Theories \mathbb{T}_1 and \mathbb{T}_2

- \mathbb{T}_1

- **Sorts:** People, Elected

- **Function symbols:**

$u : \text{Elected} \longrightarrow \text{People}$ $r : \text{People} \longrightarrow \text{Elected}$

- **Axiom:** elected officials represent themselves

$$\top \vdash_x (r(u(x)) = x)$$

- \mathbb{T}_2

- **Sorts:** Citizens

- **Function symbols:**

$e : \text{Citizens} \longrightarrow \text{Citizens}$

- **Axiom:** elected officials represent themselves

$$\top \vdash_x (e(e(x)) = e(x))$$

Alignment of Logical Theories

- **Provable equivalence**: applicable to theories over the same signature
- Theories \mathbb{T}_1 and \mathbb{T}_2 are **Morita equivalent** if their categories of models $\text{Mod}_{\mathbb{T}}(\mathcal{D})$ (in any category \mathcal{D} of the appropriate class) are equivalent.

$$\text{Mod}_{\mathbb{T}_1}(\mathcal{D}) \cong \text{Mod}_{\mathbb{T}_2}(\mathcal{D})$$

- Theories are Morita equivalent iff their syntactic categories are.

$$\mathcal{C}_{\mathbb{T}_1} \cong \mathcal{C}_{\mathbb{T}_2}$$

- This solves the alignment problem for the civics theories.
- It can be difficult to use in practice.
 - Types are interpreted as equivalence classes of formulae
 - Functions and relations are interpreted as provable equivalence classes
 - Syntactic categories are typically infinite, even for simple theories
 - No general algorithm
 - Could one develop a lazy algorithm?

First-Order Logic: Sequent Calculus

Structural Rules¹		Implication
$(\varphi \vdash_{\vec{x}} \varphi)$	$\frac{(\varphi \vdash_{\vec{x}} \psi)}{(\varphi[\vec{s}/\vec{x}] \vdash_{\vec{y}} \psi[\vec{s}/\vec{x}])}$	$\frac{((\varphi \wedge \psi) \vdash_{\vec{x}} \chi)}{(\varphi \vdash_{\vec{x}} (\psi \Rightarrow \chi))}$
Equality		Quantification²
$(\top \vdash_x (x = x))$	$((\vec{x} = \vec{y}) \wedge \varphi \vdash_{\vec{z}} \varphi[\vec{y}/\vec{x}])$	$\frac{(\varphi \vdash_{\vec{x}, y} \psi)}{((\exists y)\varphi \vdash_{\vec{x}} \psi)}$
		$\frac{(\varphi \vdash_{\vec{x}, y} \psi)}{(\varphi \vdash_{\vec{x}} (\forall y)\psi)}$
Conjunction		
$(\varphi \vdash_{\vec{x}} \top)$	$((\varphi \wedge \psi) \vdash_{\vec{x}} \varphi)$	$\frac{(\varphi \vdash_{\vec{x}} \psi) (\varphi \vdash_{\vec{x}} \chi)}{(\varphi \vdash_{\vec{x}} (\psi \wedge \chi))}$
	$((\varphi \wedge \psi) \vdash_{\vec{x}} \psi)$	
Disjunction		
$(\perp \vdash_{\vec{x}} \varphi)$	$(\varphi \vdash_{\vec{x}} (\varphi \vee \psi))$	$\frac{(\varphi \vdash_{\vec{x}} \chi) (\psi \vdash_{\vec{x}} \chi)}{((\varphi \vee \psi) \vdash_{\vec{x}} \chi)}$
	$(\psi \vdash_{\vec{x}} (\varphi \vee \psi))$	
Distributive Law³		
$((\varphi \wedge (\psi \vee \chi)) \vdash_{\vec{x}} (\varphi \wedge \psi) \vee (\varphi \wedge \chi))$		
Frobenius Axiom³		
$((\varphi \wedge ((\exists y)\psi)) \vdash_{\vec{x}} (\exists y)(\varphi \wedge \psi))$		
Excluded Middle		
$(\top \vdash_x (\varphi \vee \neg\varphi))$		

Contexts are suitable for the formulae that occur on both sides of \vdash .

¹ In the substitution rule, \vec{y} contains all the variables of \vec{x} .

² Bound variables do not also occur free in any sequent.

³ The Distributive Law and Frobenius Axiom are derivable in full, first-order logic.

Syntactic Categories

- Let \mathbb{T} be a **regular** theory. There is a regular category $\mathcal{C}_{\mathbb{T}}$ that has a model of \mathbb{T} .

objects: α -equivalence classes of formulae-in-context: $\{\vec{x}.\varphi\}$
where φ is regular over \mathbb{T}

morphisms : \mathbb{T} -provable equivalence classes $[\theta]$ with $\{\vec{x}.\varphi\} \xrightarrow{[\theta]} \{\vec{y}.\psi\}$
 $\theta \vdash_{\vec{x}, \vec{y}} \varphi \wedge \psi$ $\varphi \vdash_{\vec{x}} (\exists \vec{y}) \theta$ $\theta \wedge \theta[\vec{z}/\vec{y}] \vdash_{\vec{x}, \vec{y}, \vec{z}} (\vec{z} = \vec{y})$

composition:

$$\begin{array}{ccc}
 \{\vec{x}.\varphi\} & \xrightarrow{[\theta]} & \{\vec{y}.\psi\} \\
 & \searrow & \downarrow [\gamma] \\
 & [(\exists \vec{y})(\theta \wedge \gamma)] & \{\vec{z}.\chi\}
 \end{array}$$

identity: $\{\vec{x}.\varphi\} \xrightarrow{[\varphi \wedge (\vec{x}' = \vec{x})]} \{\vec{x}'.\varphi[\vec{x}'/\vec{x}]\}$

Syntactic Categories (Continued)

- $\mathcal{C}_{\mathbb{T}}$ contains a model of \mathbb{T} .

sorts	A	$\{x.\mathbb{T}\}$ for $x : A$
types	1 $A_1 \times \cdots \times A_n$	$\{\square.\mathbb{T}\}$ $\{\vec{x}.\mathbb{T}\}$ for $x_i : A_i$
function symbols	$f : A_1 \times \cdots \times A_n \rightarrow B$	$\{\vec{x}.\mathbb{T}\} \xrightarrow{[f(x_1, \dots, x_n) = y]} \{y.\mathbb{T}\}$ for $x_i : A_i$ and $y : B$
relation symbols	$R \mapsto A_1 \times \cdots \times A_n$	$\{\vec{x}.R(\vec{x})\} \longrightarrow \{\vec{x}.\mathbb{T}\}$

Soundness

- **Soundness Theorem:** Let \mathbb{T} be a **Horn theory** and let M be a model of \mathbb{T} in a **cartesian** category. If $\varphi \vdash_{\vec{x}} \psi$ is provable from \mathbb{T} in Horn logic, then the sequent is satisfied in M .

Proof: Induction on inference rules using the categorical properties used to define semantics of terms- and formulae-in-context.

- We can replace **Horn** and **cartesian** with other combinations:

Logic	Category
Regular	Regular
Coherent	Coherent
First-order	Heyting
Classical first-order	Boolean coherent
Linear	*-autonomous
Intuitionistic higher-order	Topos
S4 modal (predicate)	sheaves on a topological space

Completeness

- **Completeness Theorem:** Let \mathbb{T} be a **regular theory**. If $\varphi \vdash_{\bar{x}} \psi$ is a regular sequent that is satisfied in all models of \mathbb{T} in **regular categories** \mathcal{D} , then it is provable from \mathbb{T} in regular logic.

Proof: Construct the syntactic category $\mathcal{C}_{\mathbb{T}}$ with a generic model $M_{\mathbb{T}}$

category of models of \mathbb{T} in \mathcal{D}	\cong	category of regular functors $\mathcal{C}_{\mathbb{T}} \rightarrow \mathcal{D}$
$\text{Mod}_{\mathbb{T}}(\mathcal{D}) \cong \text{Reg}(\mathcal{C}_{\mathbb{T}}, \mathcal{D})$		

- We can replace **regular** theories and categories with:

Logic	Category
Cartesian	Cartesian
Coherent	Coherent
First-order	Heyting

- The Completeness Theorem also holds if we replace \mathcal{D} by **Set**.

Proof of $(u(x) = u(y)) \vdash_{x,y} (x = y)$ for Civics Theory \mathbb{T}_1

- 1 $(u(x) = u(y)) \vdash_{x,y} (u(x) = u(y))$ Id
- 2 $(u(x) = u(y)) \vdash_{x,y} \top$ \top
- 3 $\top \vdash_x (r(u(x)) = x)$ axiom
- 4 $\top \vdash_{x,y} (r(u(x)) = x)$ Sub (3)
- 5 $\top \vdash_{x,y} (r(u(y)) = y)$ Sub (3)
- 6 $(x = y) \wedge (r(x) = z) \vdash_{x,y,z} (r(y) = z)$ Eq1
- 7 $(u(x) = u(y)) \wedge (r(u(x)) = x) \vdash_{x,y,z} (r(u(y)) = x)$ Subs (6)
- 8 $(u(x) = u(y)) \wedge (r(u(x)) = x) \vdash_{x,y} (r(u(y)) = x)$ Subs (7)
- 9 $(x = y) \vdash_{x,y} (y = x)$ previous proof
- 10 $(r(u(y)) = x) \vdash_{x,y} (x = r(u(y)))$ Subs (9)
- 11 $(u(x) = u(y)) \wedge (r(u(x)) = x) \vdash_{x,y} (x = r(u(y)))$ Cut (8), (10)
- 12 $(x = y) \wedge (y = z) \vdash_{x,y,z} (x = z)$ previous proof
- 13 $(x = r(u(y))) \wedge (r(u(y)) = y) \vdash_{x,y,z} (x = y)$ Subs (12)
- 14 $(x = r(u(y))) \wedge (r(u(y)) = y) \vdash_{x,y} (x = y)$ Subs (13)
- 15 $(u(x) = u(y)) \vdash_{x,y} (r(u(x)) = x)$ Cut (2), (4)
- 16 $(u(x) = u(y)) \vdash_{x,y} (u(x) = u(y)) \wedge (r(u(x)) = x)$ $\wedge I$ (1), (15)
- 17 $(u(x) = u(y)) \vdash_{x,y} (x = (r(u(y))))$ Cut (16), (11)
- 18 $(u(x) = u(y)) \vdash_{x,y} (r(u(y)) = y)$ Cut (2), (5)
- 19 $(u(x) = u(y)) \vdash_{x,y} (x = r(u(y))) \wedge (r(u(y)) = y)$ $\wedge I$ (17), (18)
- 20 $(u(x) = u(y)) \vdash_{x,y} (x = y)$ Cut (19), (14)

Prover9 Proof

- Input file:

```

formulas(assumptions).
  all x (r(u(x)) = x).
end_of_list.
formulas(goals).
  all x all y (u(x) = u(y)) -> (x = y).
end_of_list.

```

- Proof:

```

1 (all x r(u(x)) = x) .....# label(non_clause). [assumption].
2 (all x all y u(x) = u(y)) -> x = y .....# label(non_clause)
                                           # label(goal). [goal].
3 r(u(x)) = x. ....[clausify(1)].
4 u(x) = u(y). ....[deny(2)].
5 c2 != c1. ....[deny(2)].
6 x = y. ....[para(4(a,1),3(a,1,1)),rewrite([3(2)])].
7 $F. ....[resolve(6,a,5,a)].

```

- The shorter proof by contradiction uses classical first-order logic.
- First-order horn logic has lower computational complexity.

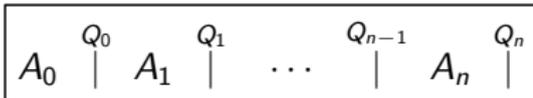
Sketch Inference Strategies

How do we show that a property P , that is not an explicit constraint, holds in a sketch?

- Add a constraint for P then show that the resulting sketch is Morita equivalent to the original one.
 - This could change the sketch class (e.g., from linear to finite limit)
- Show that P holds in every model then apply a completeness theorem.
- Translate the sketch into a Morita equivalent theory, then use a sequent calculus.
- Show that P holds in the theory $\mathcal{T}(\mathbb{S})$ of the sketch
 - Express P as a constraint \mathcal{D} then determine if $\mathcal{T}(\mathbb{S})$ satisfies the constraint $\mathcal{D} \rightarrow \mathcal{T}(\mathbb{S})$
 - Express P as satisfaction of a Q -tree.
 P may be expressible using different Q -trees.

Q-Sequences and Q-Trees (Freyd-Scedrov 1990)

- P. Freyd and A. Scedrov. *Categories, Allegories*. 1990
- A **Q-sequence** $\mathcal{Q} = (A, a, Q)$ in a category \mathcal{D} consists of lists of
 - objects A_0, \dots, A_n
 - morphisms $a_i : A_i \rightarrow A_{i+1}$ for $0 \leq i < n$
 - quantifiers Q_0, \dots, Q_n



- $\sigma \mathcal{Q}$ is:
$$A_1 \quad \begin{array}{c} Q_1 \\ | \\ \end{array} \quad \dots \quad \begin{array}{c} Q_{n-1} \\ | \\ \end{array} \quad A_n \quad \begin{array}{c} Q_n \\ | \\ \end{array}$$

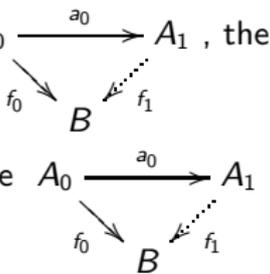
- A morphism $A_0 \xrightarrow{f_0} B$ **satisfies** \mathcal{Q} if one of the following holds:

- $n = 0$ and $Q_0 = \forall$
- $n > 0$, $Q_0 = \forall$, and for every commutative triangle $A_0 \xrightarrow{a_0} A_1$, the

morphism $A_1 \xrightarrow{f_1} B$ satisfies $\sigma \mathcal{Q}$

- $n > 0$, $Q_0 = \exists$, and there exists a commutative triangle $A_0 \xrightarrow{a_0} A_1$

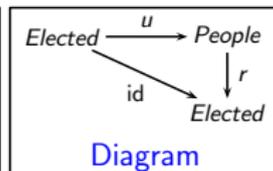
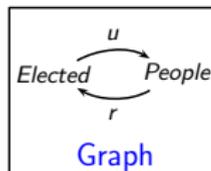
for which $A_1 \xrightarrow{f_1} B$ satisfies $\sigma \mathcal{Q}$



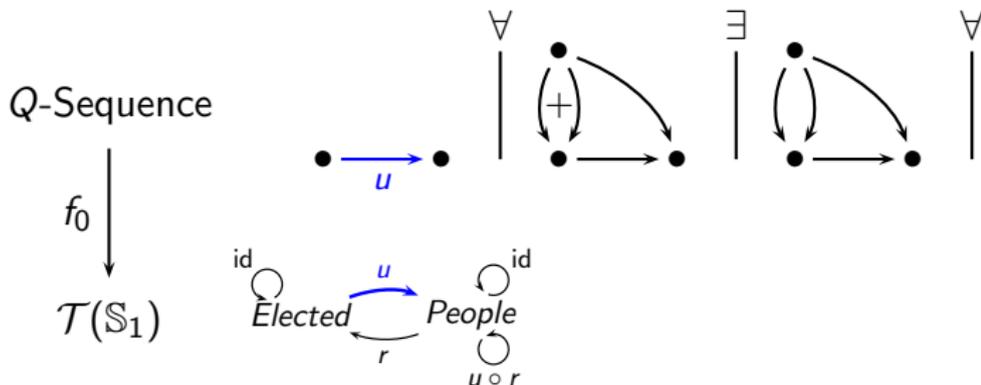
- **Q-trees** generalize Q-sequences by allowing branching.

Sketch Inference

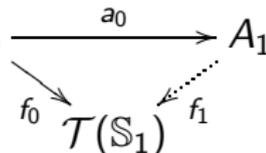
In civics sketch \mathbb{S}_1 , we may conclude that **Elected** is a subclass of **People**.



- In Cat , the indicated f_0 satisfies the given Q -sequence.



- There are two commutative triangles $A_0 \xrightarrow{a_0} A_1$
- In both cases, f_1 satisfies σQ .



Sketch Inference: Questions

- Categories, Allegories 1.398. *Equivalence functors between categories preserve and reflect satisfaction of those Q -trees all of whose functors separate objects.*
 - Morita equivalent sketches (those having equivalent theories) satisfy the same Q -trees.
- Categories, Allegories 1.3(10). *For any elementary property on diagrams preserved and reflected by equivalence functors, there is a finitely presented Q -tree all of whose functors separate objects.*
 - A completeness theorem for sketches?
- What algorithms have been developed for verifying satisfaction of Q -trees?
- Different Q -trees can express the same constraint. Is there a notion of map/equivalence between Q -trees?

Transforming Sketches into First-Order Theories

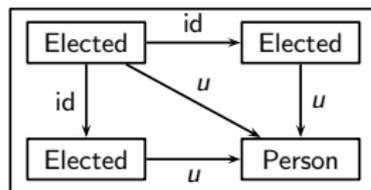
- Sketches are related to first-order logical theories by theorems of the form: Given any sketch \mathbb{S} of class X , there is a logical theory \mathbb{T} of class Y for which \mathbb{S} and \mathbb{T} have equivalent classes of models.
- D2.2 of Johnstone's *Sketches of an Elephant: A Topos Theory Compendium* gives explicit constructions of \mathbb{T} from \mathbb{S} and conversely.

Class of Sketches	Fragment of Predicate Calculus	Logical Connectives
finite limit	cartesian	$=, \top, \wedge, \exists^*$
regular	regular	$=, \top, \wedge, \exists$
coherent	coherent	$=, \top, \wedge, \exists, \perp, \vee$
geometric	geometric	$=, \top, \wedge, \exists, \perp, \bigvee$
σ -coherent	σ -coherent	$=, \top, \wedge, \exists, \perp, \bigvee_{i=1}^{\infty}$
finitary	σ -coherent	$=, \top, \wedge, \exists, \perp, \bigvee_{i=1}^{\infty}$

* In cartesian logic, only certain existentially quantified formulae are allowed.

Example: Transforming the Civics Sketches to Theories

- General construction (D2.2 of *Sketches of an Elephant* by P.T. Johnstone)
 - Vertices become sorts
 - Edges become function symbols
 - No relation symbols
 - Diagrams become axioms
 - Cones and cocones induce axiom schema
- \mathbb{S}_1 induces \mathbb{T}_1 and \mathbb{S}_2 induces \mathbb{T}_2
- Add a finite limit constraint to \mathbb{S}_1



All induced sequents are derivable in \mathbb{T}_1

$$\top \vdash_x (u(x) = u(x))$$

$$((x = y) \wedge (u(x) = u(y)) \wedge (x = y)) \vdash_{x,y} (x = y)$$

$$((u(x) = y) \wedge (u(x') = y)) \vdash_{x,x',y} \exists x_0 ((x_0 = x) \wedge (u(x_0) = y) \wedge (x_0 = x'))$$

Sketch Translations: Questions

- The proof in 2.2.1 of Johnstone's *Sketches of an Elephant* of the existence of a Morita equivalent sketch for a logical theory (both of suitable classes) is not a direct construction.
- Is there an explicit (finite) construction?
- What classes of sketches correspond to OWL dialects?
- How could such mappings be used to solve the ontology alignment problem?
 - transform ontologies to sketches + instance data
 - align the sketches
 - transform back to ontologies (if necessary)