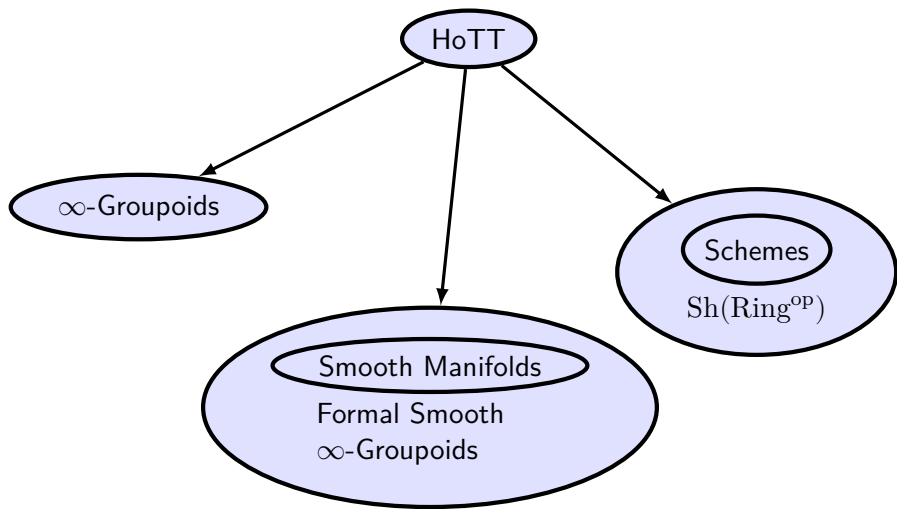
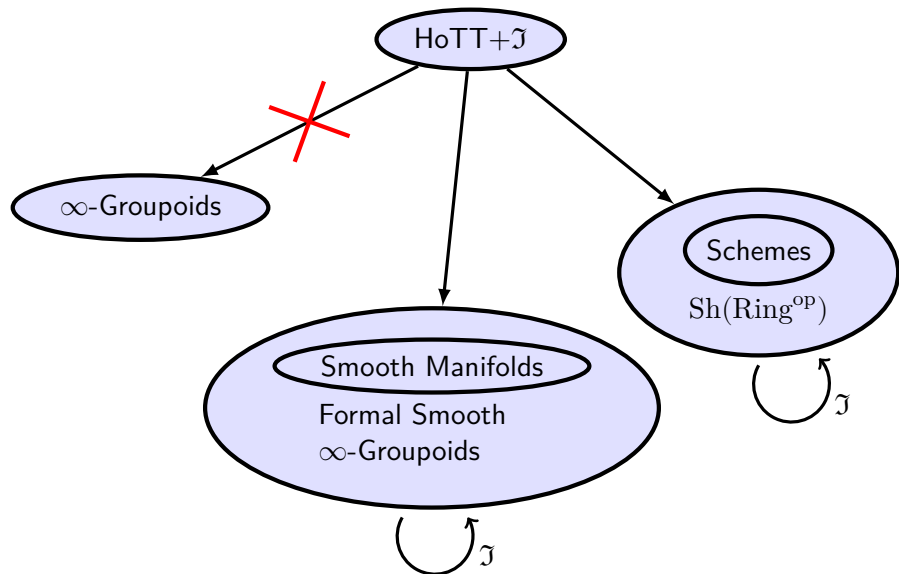


Differential Geometry via Modal HoTT

Felix Wellen



Add a modality $\mathfrak{I}$...



$$\mathfrak{I}: \mathrm{Sh}(\mathrm{Ring}^{\mathrm{op}}) \rightarrow \mathrm{Sh}(\mathrm{Ring}^{\mathrm{op}})$$

$$\mathfrak{I}: \mathrm{Sh}(\mathrm{Ring}^{\mathrm{op}}) \rightarrow \mathrm{Sh}(\mathrm{Ring}^{\mathrm{op}})$$

For $\mathcal{F} \in \mathrm{Sh}(\mathrm{Ring}^{\mathrm{op}})$, $\mathfrak{I}(\mathcal{F})$ is given by:

$$\mathfrak{I}(\mathcal{F})(A) := \mathcal{F}(A_{\mathrm{red}})$$

where A_{red} denotes the quotient of a ring by all nilpotents.

$$\mathfrak{I}: \mathrm{Sh}(\mathrm{Ring}^{\mathrm{op}}) \rightarrow \mathrm{Sh}(\mathrm{Ring}^{\mathrm{op}})$$

For $\mathcal{F} \in \mathrm{Sh}(\mathrm{Ring}^{\mathrm{op}})$, $\mathfrak{I}(\mathcal{F})$ is given by:

$$\mathfrak{I}(\mathcal{F})(A) := \mathcal{F}(A_{\mathrm{red}})$$

where A_{red} denotes the quotient of a ring by all nilpotents.
Why?

$$\mathfrak{I}: \mathrm{Sh}(\mathrm{Ring}^{\mathrm{op}}) \rightarrow \mathrm{Sh}(\mathrm{Ring}^{\mathrm{op}})$$

For $\mathcal{F} \in \mathrm{Sh}(\mathrm{Ring}^{\mathrm{op}})$, $\mathfrak{I}(\mathcal{F})$ is given by:

$$\mathfrak{I}(\mathcal{F})(A) := \mathcal{F}(A_{\mathrm{red}})$$

where A_{red} denotes the quotient of a ring by all nilpotents.

Why?

For a k -scheme S :

$$\{\text{Tangent vectors at } k\text{-points}\} \cong S(k[X]/X^2)$$

$$\mathfrak{I}: \mathrm{Sh}(\mathrm{Ring}^{\mathrm{op}}) \rightarrow \mathrm{Sh}(\mathrm{Ring}^{\mathrm{op}})$$

For $\mathcal{F} \in \mathrm{Sh}(\mathrm{Ring}^{\mathrm{op}})$, $\mathfrak{I}(\mathcal{F})$ is given by:

$$\mathfrak{I}(\mathcal{F})(A) := \mathcal{F}(A_{\mathrm{red}})$$

where A_{red} denotes the quotient of a ring by all nilpotents.

Why?

For a k -scheme S :

$$\{\text{Tangent vectors at } k\text{-points}\} \cong S(k[X]/X^2)$$

But: $(k[X]/X^2)_{\mathrm{red}} \cong k,$

$$\mathfrak{I}: \mathrm{Sh}(\mathrm{Ring}^{\mathrm{op}}) \rightarrow \mathrm{Sh}(\mathrm{Ring}^{\mathrm{op}})$$

For $\mathcal{F} \in \mathrm{Sh}(\mathrm{Ring}^{\mathrm{op}})$, $\mathfrak{I}(\mathcal{F})$ is given by:

$$\mathfrak{I}(\mathcal{F})(A) := \mathcal{F}(A_{\mathrm{red}})$$

where A_{red} denotes the quotient of a ring by all nilpotents.
Why?

For a k -scheme S :

$$\{\text{Tangent vectors at } k\text{-points}\} \cong S(k[X]/X^2)$$

But: $(k[X]/X^2)_{\mathrm{red}} \cong k$, so:

$$\mathfrak{I}(S)(k[X]/X^2) = S((k[X]/X^2)_{\mathrm{red}}) = S(k)$$

Conclusion: $\mathfrak{I}$ removes differential geometric information!

$$\mathfrak{I}: \mathrm{Sh}(\mathrm{Ring}^{\mathrm{op}}) \rightarrow \mathrm{Sh}(\mathrm{Ring}^{\mathrm{op}})$$

For $\mathcal{F} \in \mathrm{Sh}(\mathrm{Ring}^{\mathrm{op}})$, $\mathfrak{I}(\mathcal{F})$ is given by:

$$\mathfrak{I}(\mathcal{F})(A) := \mathcal{F}(A_{\mathrm{red}})$$

where A_{red} denotes the quotient of a ring by all nilpotents.
Why?

For a k -scheme S :

$$\{\text{Tangent vectors at } k\text{-points}\} \cong S(k[X]/X^2)$$

But: $(k[X]/X^2)_{\mathrm{red}} \cong k$, so:

$$\mathfrak{I}(S)(k[X]/X^2) = S((k[X]/X^2)_{\mathrm{red}}) = S(k)$$

Conclusion: $\mathfrak{I}$ removes differential geometric information!
 $\mathfrak{I}$ is a left and right adjoint idempotent monad known by the names *coreduction*, *deRham-stack* and *infinitesimal shape*.

The modality $\mathfrak{J}$

The modality $\mathfrak{J}$

Internally, $\mathfrak{J}$ is given by the following list of axioms:

The modality $\mathfrak{J}$

Internally, $\mathfrak{J}$ is given by the following list of axioms:

- (i) For any type A , there is a type $\mathfrak{J}A$ and a map $\iota_A: A \rightarrow \mathfrak{J}A$.

The modality $\mathfrak{J}$

Internally, $\mathfrak{J}$ is given by the following list of axioms:

- (i) For any type A , there is a type $\mathfrak{J}A$ and a map $\iota_A: A \rightarrow \mathfrak{J}A$.
- (ii) $(A \text{ is coreduced}) \equiv (\iota_A \text{ is an equivalence})$

The modality $\mathfrak{J}$

Internally, $\mathfrak{J}$ is given by the following list of axioms:

- (i) For any type A , there is a type $\mathfrak{J}A$ and a map $\iota_A: A \rightarrow \mathfrak{J}A$.
- (ii) $(A \text{ is coreduced}) : \equiv (\iota_A \text{ is an equivalence})$
- (iii) For any type A , $\mathfrak{J}A$ is coreduced.

The modality $\mathfrak{J}$

Internally, $\mathfrak{J}$ is given by the following list of axioms:

- (i) For any type A , there is a type $\mathfrak{J}A$ and a map $\iota_A: A \rightarrow \mathfrak{J}A$.
 - (ii) $(A \text{ is coreduced}) \equiv (\iota_A \text{ is an equivalence})$
 - (iii) For any type A , $\mathfrak{J}A$ is coreduced.
 - (iv) For any $B: \mathfrak{J}A \rightarrow \mathcal{U}$, such that $\prod_{a: \mathfrak{J}A} B(a)$ is coreduced, a map $s: \prod_{a: \mathfrak{J}A} B(a)$ is defined by $s_0: \prod_{a: A} B(\iota_A(a))$.
 - (v) Coreduced types have coreduced identity types.
- (iv) may be specialized to:
For any coreduced B

$$_ \circ \iota_A: (\mathfrak{J}A \rightarrow B) \rightarrow (A \rightarrow B)$$

is an equivalence.

Internal differential geometric notions

Internal differential geometric notions

Definition

Let A be a type.

(a) For two points $x, y:A$, let

$$(x \sim_{\text{inf}} y) :\equiv (\iota_A(x) =_{\mathfrak{I}A} \iota_A(y)).$$

(Say: “ x is infinitesimally close to y ”)

Internal differential geometric notions

Definition

Let A be a type.

(a) For two points $x, y:A$, let

$$(x \sim_{\text{inf}} y) :\equiv (\iota_A(x) =_{\mathfrak{I}A} \iota_A(y)).$$

(Say: “ x is infinitesimally close to y ”)

(b) For $a:A$, the type

$$\mathbb{D}_a :\equiv \left(\sum_{x:A} x \sim_{\text{inf}} a \right)$$

is called the *formal disk at a* .

Internal differential geometric notions

Definition

Let A be a type.

(a) For two points $x, y:A$, let

$$(x \sim_{\text{inf}} y) :\equiv (\iota_A(x) =_{\mathfrak{I}A} \iota_A(y)).$$

(Say: “ x is infinitesimally close to y ”)

(b) For $a:A$, the type

$$\mathbb{D}_a :\equiv \left(\sum_{x:A} x \sim_{\text{inf}} a \right)$$

is called the *formal disk at a* .

(c) The type

$$\mathbb{T}_{\infty}A :\equiv \sum_{a:A} \mathbb{D}_a$$

is called the *formal disk bundle of A* .

First properties

Lemma

Let A and B be types and $f: A \rightarrow B$ a map.

First properties

Lemma

Let A and B be types and $f: A \rightarrow B$ a map.

(a) For $x, y: A$, there is an induced map

$$\tilde{f}_{x,y}: (x \sim_{\text{inf}} y) \rightarrow (f(x) \sim_{\text{inf}} f(y)).$$

First properties

Lemma

Let A and B be types and $f: A \rightarrow B$ a map.

(a) For $x, y: A$, there is an induced map

$$\tilde{f}_{x,y}: (x \sim_{\text{inf}} y) \rightarrow (f(x) \sim_{\text{inf}} f(y)).$$

(b) For $a: A$, there is an induced map

$$df_a: \mathbb{D}_a \rightarrow \mathbb{D}_{f(a)}.$$

First properties

Lemma

Let A and B be types and $f: A \rightarrow B$ a map.

(a) For $x, y: A$, there is an induced map

$$\tilde{f}_{x,y}: (x \sim_{\text{inf}} y) \rightarrow (f(x) \sim_{\text{inf}} f(y)).$$

(b) For $a: A$, there is an induced map

$$df_a: \mathbb{D}_a \rightarrow \mathbb{D}_{f(a)}.$$

(c) If f is an equivalence, then for $a: A$,

$$df_a: \mathbb{D}_a \rightarrow \mathbb{D}_{f(a)}$$

is an equivalence.

Towards a theorem

Towards a theorem

Definition

A type V is called *homogeneous* if

- (i) There is a point $e:V$.
- (ii) For any $x:V$, there is an equivalence

$$\psi_x: V \rightarrow V$$

such that $\psi_x(e) = x$.

Examples

- (a) Groups
- (b) Pseudogroups
- (c) Loopspaces
- (d) Connected H-spaces

The triviality theorem

Theorem

Let V be a homogeneous type and $\mathbb{D}_e$ the formal disk at its point. Then the following commutes:

$$\begin{array}{ccc} T_{\infty} V & \xrightarrow{\cong} & V \times \mathbb{D}_e \\ & \searrow & \swarrow \\ & V & \end{array}$$

The triviality theorem

Theorem

Let V be a homogeneous type and $\mathbb{D}_e$ the formal disk at its point. Then the following commutes:

$$\begin{array}{ccc} T_{\infty} V & \xrightarrow{\cong} & V \times \mathbb{D}_e \\ & \searrow & \swarrow \\ & V & \end{array}$$

Proof:

The triviality theorem

Theorem

Let V be a homogeneous type and $\mathbb{D}_e$ the formal disk at its point. Then the following commutes:

$$\begin{array}{ccc} T_\infty V & \xrightarrow{\cong} & V \times \mathbb{D}_e \\ & \searrow & \swarrow \\ & V & \end{array}$$

Proof: $d\psi_x: \mathbb{D}_e \rightarrow \mathbb{D}_{\psi_x(e)}$ is an equivalence.

The triviality theorem

Theorem

Let V be a homogeneous type and $\mathbb{D}_e$ the formal disk at its point. Then the following commutes:

$$\begin{array}{ccc} T_\infty V & \xrightarrow{\cong} & V \times \mathbb{D}_e \\ & \searrow & \swarrow \\ & V & \end{array}$$

Proof: $d\psi_x: \mathbb{D}_e \rightarrow \mathbb{D}_{\psi_x(e)}$ is an equivalence.

$\mathbb{D}_{\psi_x(e)}$ and $\mathbb{D}_x$ are equivalent by transport along $\psi_x(e) = x$.

The triviality theorem

Theorem

Let V be a homogeneous type and $\mathbb{D}_e$ the formal disk at its point. Then the following commutes:

$$\begin{array}{ccc} T_\infty V & \xrightarrow{\quad \simeq \quad} & V \times \mathbb{D}_e \\ & \searrow & \swarrow \\ & V & \end{array}$$

Proof: $d\psi_x: \mathbb{D}_e \rightarrow \mathbb{D}_{\psi_x(e)}$ is an equivalence.

$\mathbb{D}_{\psi_x(e)}$ and $\mathbb{D}_x$ are equivalent by transport along $\psi_x(e) = x$.

So, for any $x:V$ there is an equivalence $\varphi_x: \mathbb{D}_e \rightarrow \mathbb{D}_x$.

The triviality theorem

Theorem

Let V be a homogeneous type and $\mathbb{D}_e$ the formal disk at its point. Then the following commutes:

$$\begin{array}{ccc} T_\infty V & \xrightarrow{\quad \simeq \quad} & V \times \mathbb{D}_e \\ & \searrow & \swarrow \\ & V & \end{array}$$

Proof: $d\psi_x: \mathbb{D}_e \rightarrow \mathbb{D}_{\psi_x(e)}$ is an equivalence.

$\mathbb{D}_{\psi_x(e)}$ and $\mathbb{D}_x$ are equivalent by transport along $\psi_x(e) = x$.

So, for any $x:V$ there is an equivalence $\varphi_x: \mathbb{D}_e \rightarrow \mathbb{D}_x$.

$(x, d) \mapsto (x, \phi^{-1}(d)): \left(\sum_{x:V} \mathbb{D}_x\right) \rightarrow V \times \mathbb{D}_e$ is an equivalence.

Thank you for your attention!

One morphism property

One morphism property

Definition

A map $f: A \rightarrow B$ is called *formally étale* if the naturality square

$$\begin{array}{ccc} A & \xrightarrow{\iota_A} & \mathfrak{I}A \\ f \downarrow & & \downarrow \mathfrak{I}f \\ B & \xrightarrow{\iota_B} & \mathfrak{I}B \end{array}$$

is a pullback square.

One morphism property

Definition

A map $f: A \rightarrow B$ is called *formally étale* if the naturality square

$$\begin{array}{ccc} A & \xrightarrow{\iota_A} & \mathfrak{I}A \\ f \downarrow & & \downarrow \mathfrak{I}f \\ B & \xrightarrow{\iota_B} & \mathfrak{I}B \end{array}$$

is a pullback square.

Remark

For smooth manifolds formally étale maps correspond to local diffeomorphisms.

For noetherian schemes, they correspond to étale maps.

Structured spaces

Structured spaces

Definition

Let V be a homogeneous type. A type M is called a V -Manifold, if there is a span of formally étale maps

$$\begin{array}{ccc} & W & \\ \text{ét} \swarrow & & \searrow \text{ét} \\ V & & M \end{array}$$

Structured spaces

Definition

Let V be a homogeneous type. A type M is called a V -Manifold, if there is a span of formally étale maps

$$\begin{array}{ccc} & W & \\ \text{ét} \swarrow & & \searrow \text{ét} \\ V & & M \end{array}$$

Theorem (needs Univalence)

Any V -Manifold has a locally trivial formal disk bundle witnessed by a classifying map

$$\chi_M: M \rightarrow \mathbf{BAut}(\mathbb{D}_e)$$

Cartan Geometry

Cartan Geometry

Remark

If we have a delooping BG of a group G with a map $\varphi: BG \rightarrow \mathrm{BAut}(\mathbb{D}_e)$, we can ask if there is a lift:

$$\begin{array}{ccc} & & BG \\ & \nearrow & \downarrow \varphi \\ M & \xrightarrow{\chi_M} & \mathrm{BAut}(\mathbb{D}_e) \end{array}$$

Cartan Geometry

Remark

If we have a delooping BG of a group G with a map $\varphi: BG \rightarrow \mathrm{BAut}(\mathbb{D}_e)$, we can ask if there is a lift:

$$\begin{array}{ccc} & & BG \\ & \nearrow & \downarrow \varphi \\ M & \xrightarrow{\chi_M} & \mathrm{BAut}(\mathbb{D}_e) \end{array}$$

For example, such a lift for $G = O(n)$ is a Pseudo-Riemannian structure on M .

The topos of formal smooth ∞ -groupoids

The topos of formal smooth ∞ -groupoids

There is an embedding:

$$\mathcal{C}^\infty : (\text{smooth manifolds})^{\text{op}} \hookrightarrow \mathbb{R}\text{-algebras}$$

The topos of formal smooth ∞ -groupoids

There is an embedding:

$$\mathcal{C}^\infty : (\text{smooth manifolds})^{\text{op}} \hookrightarrow \mathbb{R}\text{-algebras}$$

We extend the image $\mathcal{C}^\infty(\{\mathbb{R}^n \mid n \in \mathbb{N}\})$

The topos of formal smooth ∞ -groupoids

There is an embedding:

$$\mathcal{C}^\infty : (\text{smooth manifolds})^{\text{op}} \hookrightarrow \mathbb{R}\text{-algebras}$$

We extend the image $\mathcal{C}^\infty(\{\mathbb{R}^n \mid n \in \mathbb{N}\})$
to get the site of *formal cartesian spaces*

$$\underbrace{\{\mathcal{C}^\infty(\mathbb{R}^n) \otimes_{\mathbb{R}} (\mathbb{R} \oplus V) \mid n \in \mathbb{N} \text{ and } V \text{ nilpotent, } \dim_{\mathbb{R}} V < \infty\}}_{=:(\mathbb{R}^n \times \mathbb{D}_V)^{\text{op}}}$$

The topos of formal smooth ∞ -groupoids

There is an embedding:

$$\mathcal{C}^\infty : (\text{smooth manifolds})^{\text{op}} \hookrightarrow \mathbb{R}\text{-algebras}$$

We extend the image $\mathcal{C}^\infty(\{\mathbb{R}^n \mid n \in \mathbb{N}\})$
to get the site of *formal cartesian spaces*

$$\underbrace{\{\mathcal{C}^\infty(\mathbb{R}^n) \otimes_{\mathbb{R}} (\mathbb{R} \oplus V) \mid n \in \mathbb{N} \text{ and } V \text{ nilpotent, } \dim_{\mathbb{R}} V < \infty\}}_{=:(\mathbb{R}^n \times \mathbb{D}_V)^{\text{op}}}$$

with a topology respecting the smooth structure on the $\mathbb{R}^n$ s and inducing identities on infinitesimals.

The topos of formal smooth ∞ -groupoids

There is an embedding:

$$\mathcal{C}^\infty : (\text{smooth manifolds})^{\text{op}} \hookrightarrow \mathbb{R}\text{-algebras}$$

We extend the image $\mathcal{C}^\infty(\{\mathbb{R}^n \mid n \in \mathbb{N}\})$
to get the site of *formal cartesian spaces*

$$\underbrace{\{\mathcal{C}^\infty(\mathbb{R}^n) \otimes_{\mathbb{R}} (\mathbb{R} \oplus V) \mid n \in \mathbb{N} \text{ and } V \text{ nilpotent, } \dim_{\mathbb{R}} V < \infty\}}_{=:(\mathbb{R}^n \times \mathbb{D}_V)^{\text{op}}}$$

with a topology respecting the smooth structure on the $\mathbb{R}^n$ s and inducing identities on infinitesimals.

On representables ---_{red} is given by reduction of $\mathbb{R}$ -algebras:

$$(\mathbb{R}^n \times \mathbb{D}_V)_{\text{red}} = \mathbb{R}^n$$

Differential Cohesive Toposes

$$\begin{array}{ccccccc} \mathfrak{R} & \dashv & \mathfrak{I} & \dashv & \& \\ & & \cup & & \cup & \\ & & \int & \dashv & \flat & \dashv & \sharp \end{array}$$

$\mathfrak{I}$, $\int$ and $\sharp$ are reflections.

$\mathfrak{R}$, $\&$ and $\flat$ are coreflections.

$\int$ and $\mathfrak{R}$ preserve finite products.