



Asymptotic reasoning in Coq

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1

What this talk is about

Motivation

$$\left\{ \begin{array}{l} \forall \varepsilon > 0. \exists \delta_f > 0. \forall x. |x - a| < \delta_f \Rightarrow |f(x) - l_f| < \varepsilon \\ \forall \varepsilon > 0. \exists \delta_g > 0. \forall x. |x - a| < \delta_g \Rightarrow |g(x) - l_g| < \varepsilon \end{array} \right. ,$$

$$\Rightarrow \forall \varepsilon > 0. \exists \delta > 0. \forall x. |x - a| < \delta \Rightarrow |f(x) + g(x) - (l_f + l_g)| < \varepsilon.$$

$$o_{x \rightarrow 0}(x^n) + o_{x \rightarrow 0}(x^n) = o_{x \rightarrow 0}(x^n)$$

$$o_{x \rightarrow 0}(x^n) + \mathcal{O}_{x \rightarrow 0}(x^n) = \mathcal{O}_{x \rightarrow 0}(x^n)$$

...

Style for writing proofs

Declarative proof style:

- Lots of intermediate statements.
- Relying heavily on powerful automation.
- Scripts are human readable.
- Robustness guaranteed by appropriate choice of intermediate statements and automation.

Imperative proof style:

- Minimal amount of intermediate statements.
- Limited automation needed.
- Script contains orders you give to the system.
- Robustness guaranteed by the determinism in obeying orders.
⇒ Most likely to happen with **small scale orders**.

Example: double limit theorem

$$f : T_1 \rightarrow T_2 \rightarrow U$$

$$g : T_2 \rightarrow U$$

$$h : T_1 \rightarrow U$$

$$l : U$$

$$\begin{array}{ccc} f & \xrightarrow{\text{uniform}} & g \\ \text{simple} \downarrow & & \vdots \\ h & \longrightarrow & l \end{array}$$

Justification:

$$\|l - g(x_2)\| \leq \|l - h(x_1)\| + \|h(x_1) - f(x_1, x_2)\| + \|f(x_1, x_2) - g(x_2)\|$$

Analysis Libraries

In Coq

- C-CoRN
- Coq standard library + CoQUELICOT

Analysis Libraries

In Coq

- C-CoRN \rightarrow **Constructive analysis**
- Coq standard library + COQUELICOT \rightarrow **Constructive** + \mathbb{R} axioms

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Classical analysis in

- HOL LIGHT
- ISABELLE/HOL
- LEAN
- ...

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Disclaimer: the proofs I am going to show have clearly not been reworked to their best shape.

ISABELLE/HOL proof

```
Lemma swap_uniform_limit:
  assumes f: "∀ε n in F. (f n → g n) (at x within S)"
  assumes g: "(g → l) F"
  assumes uc: "uniform_limit S f h F"
  assumes "¬trivial_limit F"
  shows "(h → l) (at x within S)"
proof (rule tendstoI)
  fix e :: real
  define e' where "e' = e/3"
  assume "0 < e"
  then have "0 < e'" by (simp add: e'_def)
  from uniform_limitD[OF uc <0 < e']
  have "∀ε n in F. ∀x∈S. dist (h x) (f n x) < e'"
    by (simp add: dist_commute)
  moreover
  from f
  have "∀ε n in F. ∀f x in at x within S. dist (g n) (f n x) < e'"
    by eventually_elim (auto dest!: tendstoD[OF _ <0 < e'] simp: dist_commute)
  moreover
  from tendstoD[OF g <0 < e'] have "∀f x in F. dist l (g x) < e'"
    by (simp add: dist_commute)
  ultimately
  have "∀f _ in F. ∀f x in at x within S. dist (h x) l < e'"
  proof eventually_elim
    case (elim n)
    note fh = elim(1)
    note gl = elim(3)
    have "∀f x in at x within S. x ∈ S"
      by (auto simp: eventually_at_filter)
    with elim(2)
    show ?case
    proof eventually_elim
      case (elim x)
      from fh[rule_format, OF <x ∈ S>] elim(1)
      have "dist (h x) (g n) < e' + e'"
        by (rule dist_triangle_lt[OF add_strict_mono])
      from dist_triangle_lt[OF add_strict_mono, OF this gl]
      show ?case by (simp add: e'_def)
    qed
  qed
  thus "∀f x in at x within S. dist (h x) l < e'"
  using eventually_happens by (metis <¬trivial_limit F>)
qed
```

COQUELICOT's proof (our benchmark)

```
Lemma filterlim_switch_1 {U : UniformSpace}
  F1 (FF1 : ProperFilter F1) F2 (FF2 : Filter F2) (f : T1 → T2 → U) g h (l : U) :
  filterlim f F1 (locally g) →
  (forall x, filterlim (f x) F2 (locally (h x))) →
  filterlim h F1 (locally l) → filterlim g F2 (locally l).
```

Proof.

```
intros Hfg Hfh Hhl P.
case: FF1 => HF1 FF1.
apply filterlim_locally.
move => eps.

have FF := (filter_prod_filter _ _ F1 F2 FF1 FF2).

assert (filter_prod F1 F2 (fun x => ball (g (snd x)) (eps / 2 / 2)) (f (fst x) (snd x)
  ))) .
  apply Filter_prod with (fun x : T1 => ball g (eps / 2 / 2) (f x)) (fun _ => True).
  move: (proj1 (@filterlim_locally _ _ F1 FF1 f g) Hfg (pos_div_2 (pos_div_2 eps)))
    => {Hfg} /- Hfg.
  by [].
  by apply FF2.
  simpl ; intros.
  apply H.
move: H => {Hfg} Hfg.

assert (filter_prod F1 F2 (fun x : T1 * T2 => ball l (eps / 2) (h (fst x)))) .
  apply Filter_prod with (fun x : T1 => ball l (eps / 2) (h x)) (fun _ => True).
  move: (proj1 (@filterlim_locally _ _ F1 FF1 h l) Hhl (pos_div_2 eps)) => {Hhl} /-
  Hhl.
```

(* next page *)

COQUELICOT' proof (page 2)

```
by [].
by apply FF2.
by [].
move: H => {Hhl} Hhl.

case: (@filter_and _ _ FF _ _ Hhl Hfg) => {Hhl Hfg} /= ; intros.

move: (fun x => proj1 (@filterlim_locally _ _ F2 FF2 (f x) (h x)) (Hfh x) (pos_div_2
(pos_div_2 eps))) => {Hfh} /= Hfh.
case: (HF1 Q f0) => x Hx.
move: (@filter_and _ _ FF2 _ _ (Hfh x) g0) => {Hfh}.
apply filter_imp => y Hy.
```

End of boilerplate, and now, the meaningful part.

```
rewrite (double_var eps).
apply ball_triangle with (h x).
apply (p x y).
by [].
by apply Hy.
rewrite (double_var (eps / 2)).
apply ball_triangle with (f x y).
by apply Hy.
apply ball_sym, p.
by [].
by apply Hy.
Qed.
```

Achievement of our work

Design techniques to:

1. **Do imperative style small scale proofs**
2. Reduce the size of the boilerplate
3. Make it robust to change
4. Go straight to the point

2

Framework

Context

Constraints:

- 1.** Robotics: kinematic chains as composition of MATHEMATICAL COMPONENTS matrices
⇒ Mix COQUELICOT and MATHEMATICAL COMPONENTS
- 2.** Undergraduate classic textbook analysis
- 3.** Catch up with ISABELLE/HOL and LEAN
⇒ COQUELICOT and Hilbert's epsilon

Context

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Conclusion:

- rewrite COQUELICOT, on top of MATHEMATICAL COMPONENTS
- using stronger axioms:
 - Hilbert's epsilon (`constructive_indefinite_description`)
 - Propositional and functional extensionality

Hierarchy

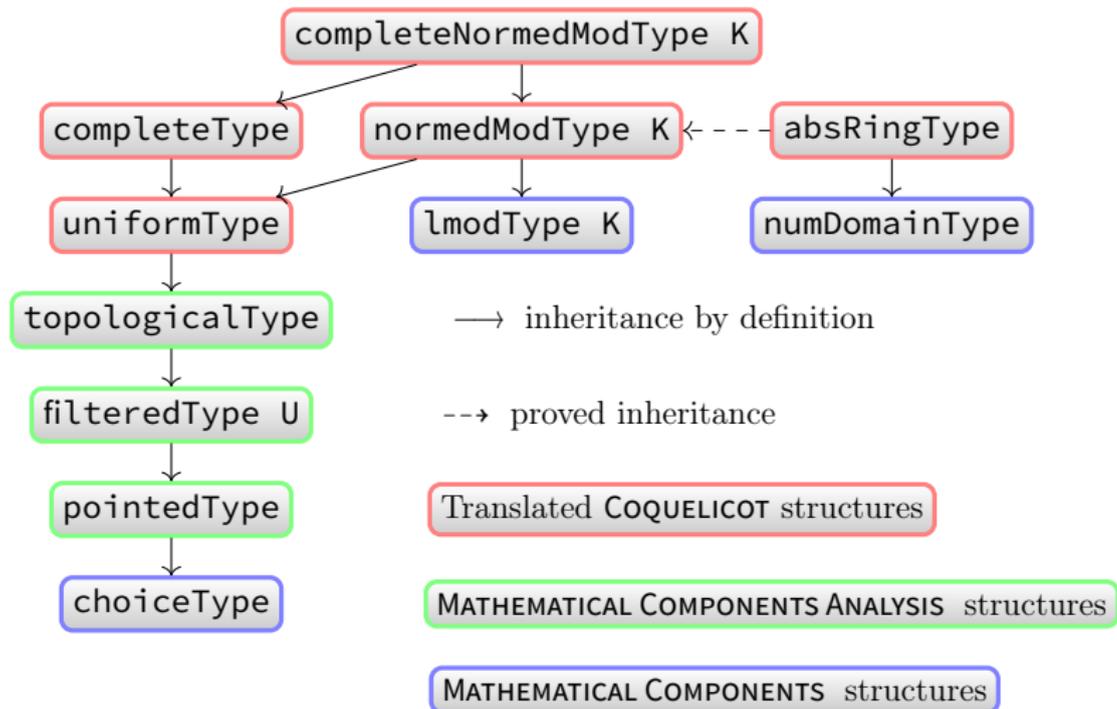


Figure: MATHEMATICAL COMPONENTS ANALYSIS hierarchy

3

Filters

A one-slide introduction to filters

Definition (same as COQUELICOT in COQ)

$\top \in F$, $\forall A, B \in F. A \cap B \in F$ and $\forall A, B. A \subseteq B \Rightarrow A \in F \Rightarrow B \in F$.

Filter of neighborhoods:

$\text{locally}(x) := \{A \mid \exists \varepsilon > 0. \text{ball}_\varepsilon(x) \subseteq A\}$.

A one-slide introduction to filters

Definition (same as COQUELICOT in COQ)

$$\top \in F, \quad \forall A, B \in F. A \cap B \in F \quad \text{and} \quad \forall A, B. A \subseteq B \Rightarrow A \in F \Rightarrow B \in F.$$

Filter of neighborhoods:

$$\text{locally}(x) := \{A \mid \exists \varepsilon > 0. \text{ball}_\varepsilon(x) \subseteq A\}.$$

Filter application:

$$f@F := \{X \mid f^{-1}(X) \in F\}.$$

Limit:

$$f@F \rightarrow G := G \subseteq f@F.$$

Filter Notations

Definitions/notations:

<code>set</code> A	$A \rightarrow \text{Prop}$
A ' <code><=</code> ' B	set inclusion
[<code>set</code> a P a]	the set of elements a that satisfy P
F <code>--></code> G	reverse set inclusion for filters $F \supseteq G$
f @ F	filter $f(F)$
+∞	+∞
<code>\forall</code> x <code>\nearrow</code> x_0, P x	locally(x_0)(P)

Double Limit Theorem

DEMO!

```
Lemma flim_switch_1 {U : uniformType}
  F1 {FF1 : ProperFilter F1} F2 {FF2 : Filter F2}
  (f : T1 → T2 → U) (g : T2 → U) (h : T1 → U) (l : U) :
  f @ F1 → g → (forall x1, f x1 @ F2 → h x1) → h @ F1 → l
  →
  g @ F2 → l.
```

Proof.

```
move=> fg fh hl; apply/flim_ballPpos => e; rewrite near_simpl.
near F1 => x1; first near=> x2.
```

- **apply** : (@ball_split _ (h x1)) ; **first by** near: x1 .
 by apply: (@ball_splitl _ (f x1 x2)); [near: x2| **move**: (x2);
 near: x1].
- **by** end_near; apply/fh/locally_ball .
- **by** end_near; [**exact**/hl/locally_ball|**exact**/(flim_ball fg)].

Qed.

Double limit, comparison with COQUELICOT

Lemma `flim_switch_1` {U : uniformType} F1 {FF1 : ProperFilter F1} F2 {FF2 : Filter F2}
(f : T1 → T2 → U) (g : T2 → U) (h : T1 → U) (l : U) :

f @ F1 → g → (forall x, f x @ F2 → h x) → h @ F1 → l → g @ F2 → l.

Proof.

```
(*...*)  
(*25 lines of boilerplate, then*)  
  
rewrite (double_var eps).  
apply ball_triangle with (h x).  
apply (p x y).  
by [].  
by apply Hy.  
rewrite (double_var (eps / 2)).  
apply ball_triangle with (f x y).  
by apply Hy.  
apply ball_sym, p.  
by [].  
by apply Hy.
```

Qed.

Proof.

```
move=> fg fh hl; apply/flim_ballPpos => e; rewrite !  
near_simpl.  
near F1 => x1; first near=> x2.  
(* 2 lines of boilerplate, then *)  
  
- apply: (@ball_split _ (h x1)); first by near: x1.  
  by apply: (@ball_splitl _ (f x1 x2)); [near: x2|  
    move: (x2); near: x1].  
  
(* Two lines of boilerplate: *)  
- by end_near; apply/fh/locally_ball.  
- by end_near; [exact/hl/locally_ball|exact/(  
  flim_ball fg)].  
  
Qed.
```

Filter tactics

The lemmas that make it all work

Lemma **filterP** T (F : set (set T)) {FF : Filter F} (P : set T) :
(exists2 Q : set T, F Q & forall x : T, Q x → P x) ↔ F P.

Lemma **filter_ex** T (F : set (set T)) '{ProperFilter F} :
forall (Q : set T), F Q → exists x : T, Q x.

Filter tactics

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forall (Q : set T), F Q → exists x : T, Q x.

Tactics

near=> x	applies filterP with metavariable Q
near F => x	takes x from filter_ex with metavariable Q
near: x	given a goal (R _i x), accumulates R _i in Q
end_near	leaves accumulated (F R _i) to be proven

Cauchy completeness

Definition **cauchy_ex** {T : uniformType} (F : set (set T)) :=
forall eps : R, 0 < eps → exists x, F (ball x eps).

or

Definition **cauchy** {T : uniformType} (F : set (set T)) :=
forall e, e > 0 → \forall x & y \nearrow F, ball x e y.

equivalently

Definition **cauchy_entourage** T (F : set (set T)) :=
(F, F) → entourages.

Function space is complete

Lemma **fun_complete** (F : set (set (T → U))) {FF: ProperFilter F} :
cauchy F → cvg F.

Proof.

move=> Fc; have /(_ _) /complete_cauchy Ft_cvg : cauchy (@^~_ @ F).

by move=> t e ?; rewrite near_simpl; apply: filterS (Fc _ _).

apply/cvg_ex; exists (fun t => lim (@^~t @ F)).

apply/flim_ballPpos => e; near=> f => [t|].

near F => g => /=.

by apply: (@ball_splitl _ (g t)); last move: (t); near: g.

by end_near; [exact/Ft_cvg/locally_ball|near: f].

by end_near; apply: nearP_dep; apply: filterS (Fc _ _).

Qed.

4

little- o and big- O

Definition

Context {T : Type} {K : absRingType} {V W : normedModType K}.

Definition **little** (F : set (set T)) (f : T → V) (e : T → W) :=
forall eps : R, 0 < eps →
forall x \nearrow F, |[f x]| <= eps * |[e x]|.

Definition **bigO** (F : set (set T)) (f : T → V) (e : T → W) :=
forall k \nearrow +oo, forall x \nearrow F, |[f x]| <= k * |[e x]|.

Definition

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forall k \nearrow +oo, forall x \nearrow F, |[f x]| <= k * |[e x]|.

But these are not predicates in the mathematical practice!

Use cases

We want to write:

- $$f = o(e) \quad \text{and} \quad f = \mathcal{O}(e)$$
$$f(x) = o(e(x)) \quad \text{and} \quad f(x) = \mathcal{O}(e(x))$$
- $$f = g + o(e) \quad \text{and} \quad f = g + \mathcal{O}(e)$$
$$f(x) = g(x) + o(e(x)) \quad \text{and} \quad f(x) = g(x) + \mathcal{O}(e(x))$$
- Do arithmetic on little- o and big- \mathcal{O} :
 $-o(e) = o(e), \quad o(e)+o(e) = o(e), \quad o(e)+\mathcal{O}(e) = \mathcal{O}(e), \quad \dots$
- Substitute! (these are equalities)

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- Substitute! (these are equalities)

DEMO!

The trick

Definition (little- o with explicit witness):

$$o(e)[h] := \begin{cases} h, & \text{if } h \text{ is a little-}o \text{ of } e \\ 0, & \text{otherwise} \end{cases}$$

Parsing:

$$f = g + o(e) \quad \text{is parsed} \quad f = g + o(e)[f - g]$$

Change of witness:

$$f = g + o(e)[f - g] \Leftrightarrow \exists h, f = g + o(e)[h]$$

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Change of witness:

$$f = g + o(e)[f - g] \Leftrightarrow \exists h, f = g + o(e)[h]$$

Display:

$$f = g + o(e)[h] \quad \text{is displayed} \quad f = g + o(e)$$

Applications

Equivalence:

Notation "f ~_x g" := (f = g + o_x g)

Differential:

Definition **diff** (F : filter_on V) (f : V → W) :=
(get (fun (df : {linear V → W}) =>
continuous ('d_F f) /\ forall x,
f x = f (lim F) + df (x - lim F) + o_(x \nearrow F) (x - lim F))).

Lemma **diff_locallyxP** (x : V) (f : V → W) :
differentiable x f <--> continuous ('d_x f) /\
forall h, f (h + x) = f x + 'd_x f h + o_(h \nearrow 0) h.

A short proof of the chain rule

```
Fact dcomp (U V W : normedModType R)
  (f : U -> V) (g : V -> W) x :
  differentiable x f -> differentiable (f x) g ->

  forall h, g (f (h + x)) =
    g (f x) + ('d_(f x) g \o 'd_x f) h +o_(h \nearrow 0) h.
```

Proof.

```
move=> df dg; apply: eqaddoEx => y.
rewrite diff_locallyx// -addrA diff_locallyxC// linearD.
rewrite addrA -addrA; congr (_ + _ + _).
rewrite diff_eq0 // ['d_x f : _ -> _]diff_eq0 //.
by rewrite {2}eqo0 add0x comp0o_eqox compo0_eqox addox.
Qed.
```

5

Conclusion and future work

Conclusion

- Toolset to give high-level orders, preserving determinism.
- Tested in the library
<http://github.com/math-comp/analysis>

What I did not show:

- Tool for manifest positivity
- Lightweight automatic differentiation (Damien Rouhling, CPP 2018)

Incoming improvements

Improve the workflow of near tactics

Go from this

```
move=> fg fh hl; apply/flim_ballPpos => e; rewrite near_simpl.
near F1 => x1; first near=> x2.
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  by apply: (@ball_splitl _ (f x1 x2)); [near: x2|move: (x2); near: x1].
- by end_near; apply/fh/locally_ball.
- by end_near; [exact/hl/locally_ball|exact/(flim_ball fg)].
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```

to this

```
move=> fg fh hl; apply/flim_ballPpos => e ; rewrite near_simpl; near F1 => x1 x2.
apply: (@ball_split _ (h x1)); first by near: x1; apply/fh/locally_ball.
apply: (@ball_splitl _ (f x1 x2)); first by near: x2; apply/hl/locally_ball.
by near: x1 (x2); apply/(flim_ball fg).
```

Other possible improvements

- Manuel Eberl's multiserries for automated limits, little- o , etc
- Semi-automated bounding tools
(ingredients: same as big- \mathcal{O} and manifest positivity)
- add Lebesgue integration and power series
- find limits, derivatives, differentials, integrals and converging sums in a semi-automated automated way.

Thank you for your attention.