

Low-Power Clock Synchronization using Electromagnetic Energy Radiating from AC Power Lines (Apply Directly Where it Hertz)

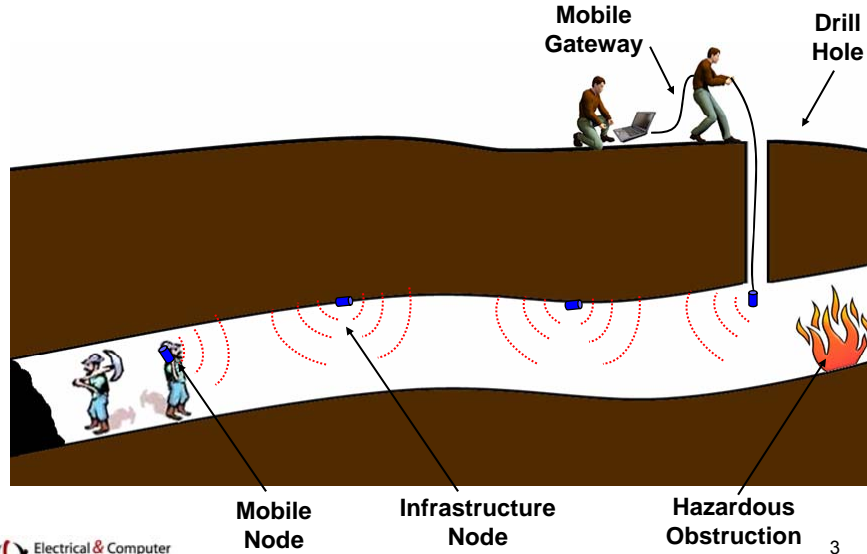
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Why Time Synchronization?

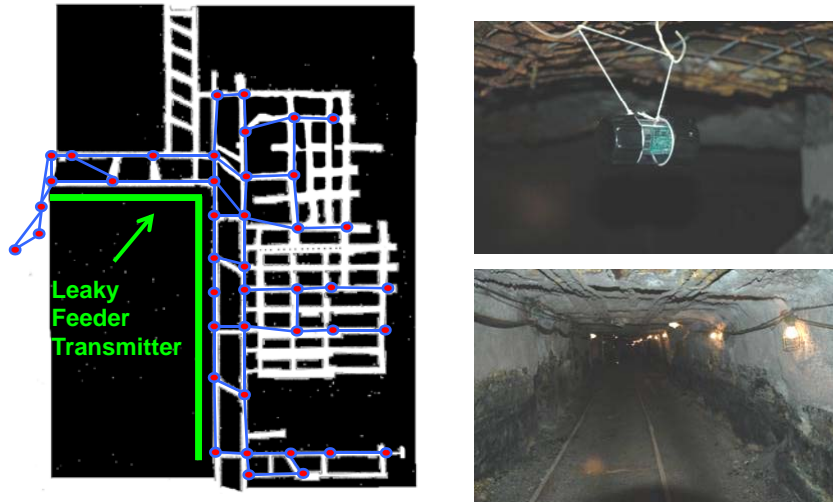
- **Event Ordering**
- **Low Duty Cycle Networking**
- **Time Division Multiple Access (TDMA)**
 - Energy-efficient
 - High-throughput

Looking back at 2006



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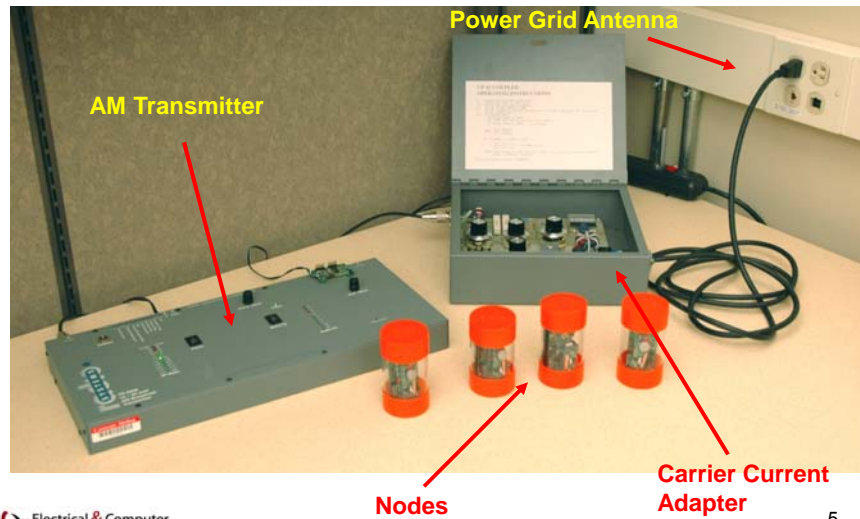
NIOSH Research Coal Mine near Pittsburgh



NIOSH: National Institute for Occupational Safety and Health

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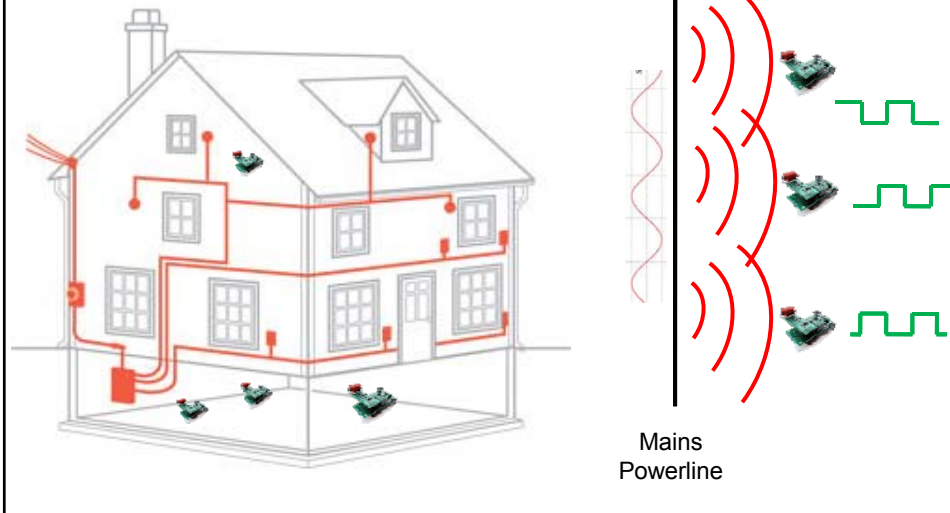
Very Complex. Expensive.



Other Synchronization Approaches

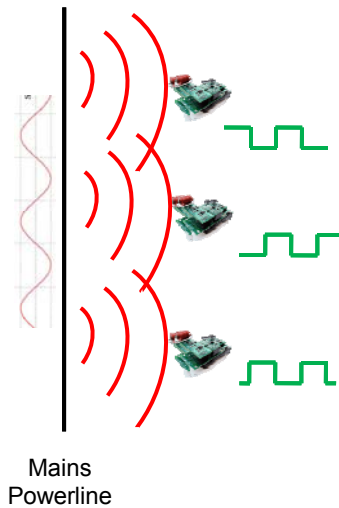
- **Sensor Network Time Synchronization**
 - Flooding Time Sync Protocol, FireFly-inspired Time Sync, Reference Broadcast
 - What about energy?
 - Imagine extremely low duty-cycles...
- **Global Broadcasts**
 - WWVB atomic clock, GPS, Radio Data Service (RDS)
 - Does not work well indoors
- **Simultaneous Observations**
 - Quasar Pulses, Quantum Entangled Particles
 - Not practical (yet)

Wirelessly Receive Power-Line Magnetic Field



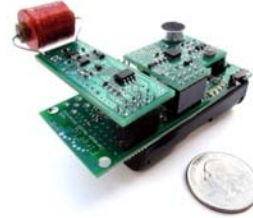
“Syntonization” vs Synchronization

- The 60 Hz frequency from the electrical line acts as a common global clock source
- The phases will differ depending on the angle of the receiver with respect to the magnetic field
- Signal due to imbalances in grounding loops

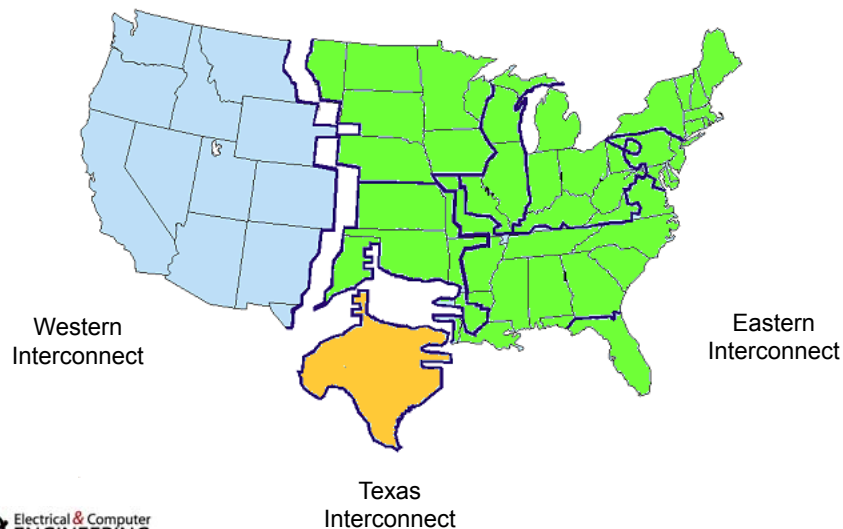


Powerline 60 Hz

- **Field Strength**
 - Home
 - 17 milli-gauss (as much as 10 gauss)
 - Industrial
 - As much as 100 gauss
 - Power Line
 - 3 milli-gauss at 60 meters
 - Earth
 - .02 milli-gauss
- **Stability**
 - 10^{-5} stability (typical oscillator is 10^{-5})
 - 10^{-8} differential delay stability between two points
 - Many old alarm clocks and appliances used the sine wave from direct contact to lines as a cheap clock



Clock Sources



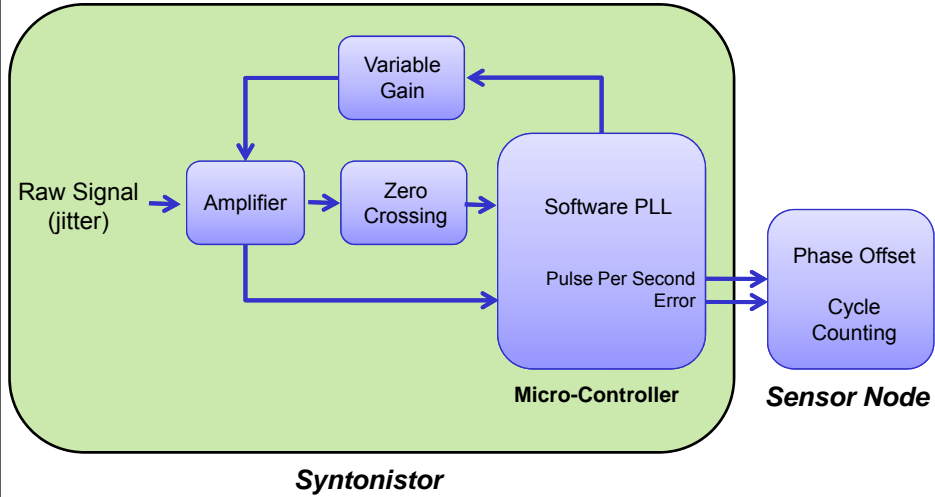
Why use a Syntonistor?

- Once phase offsets have been established, the device remains synchronized for long periods of time without exchanging messages
- Errors can be detected by monitoring for rapid changes in the 60Hz signal

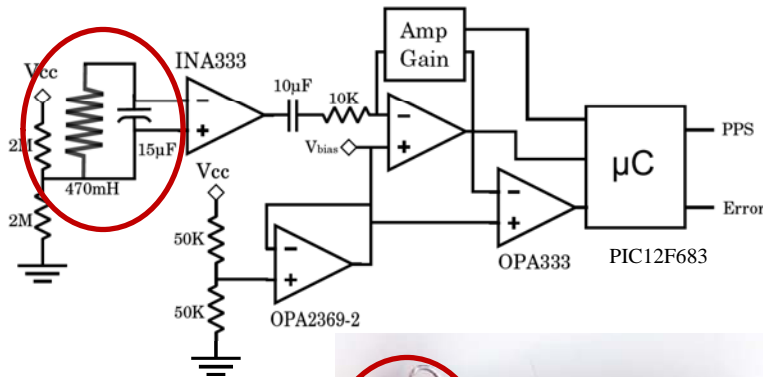
Challenges

- Low-power receiver → *Inductance / Resonance*
 - Robustness to noise → *PLL Filtering*
 - Common time reference
 - Absolute phase adjustment
- } *WSN Protocol*

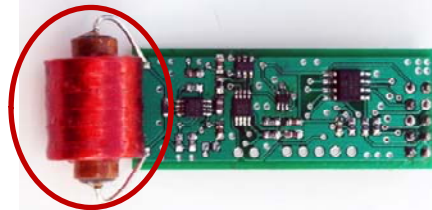
Block Diagram



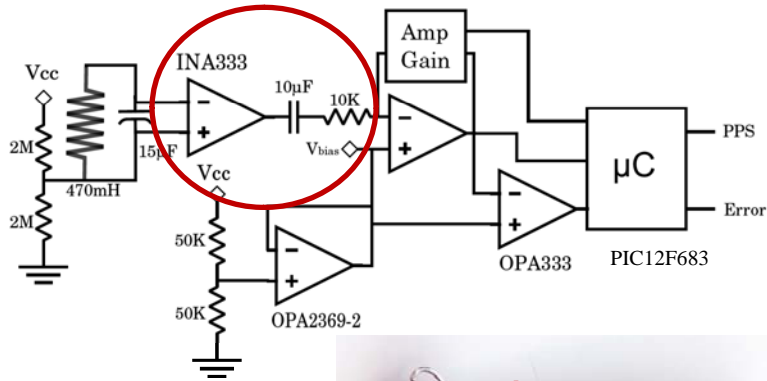
Syntonistor Hardware



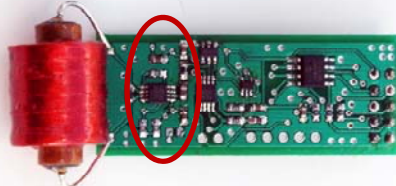
Tank Circuit
Tuned to 60Hz



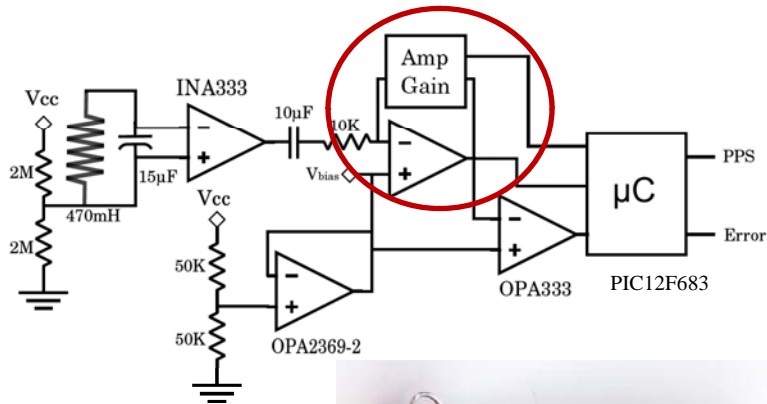
Sytonistor Hardware



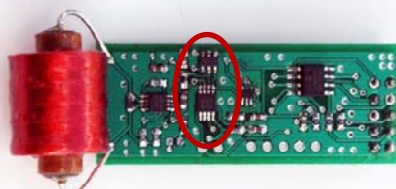
1st Amplifier / High-Pass Filter



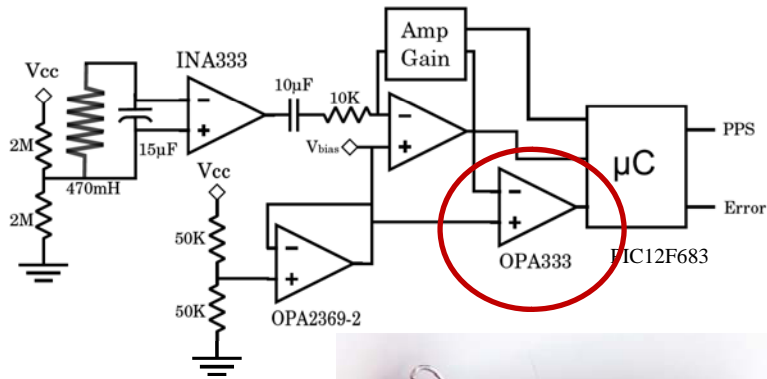
Sytonistor Hardware



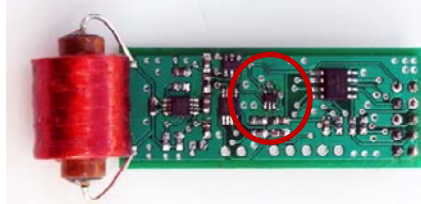
2nd Amplifier / Auto-Gain



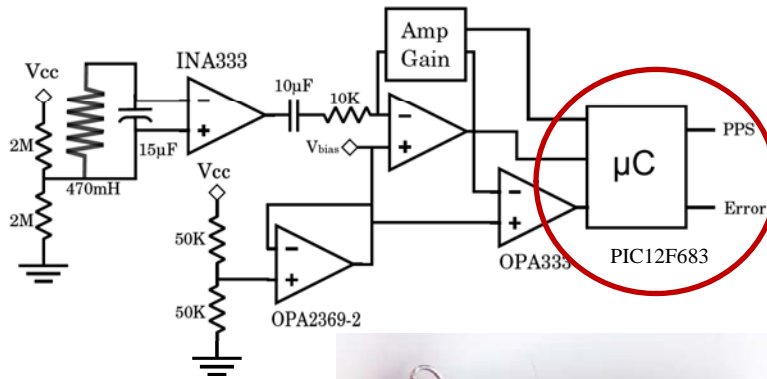
Sytonistor Hardware



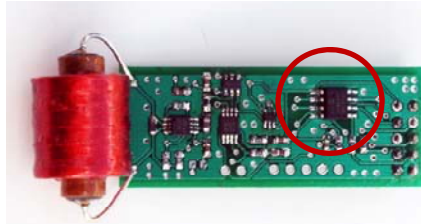
Zero-Crossing
Detector



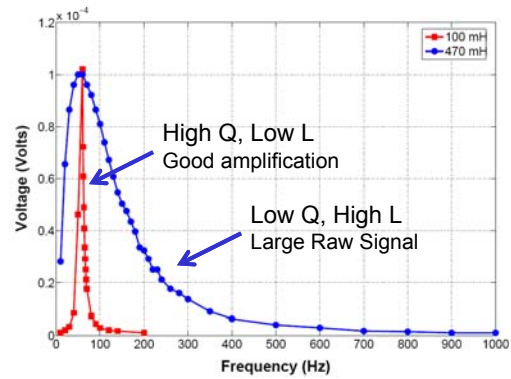
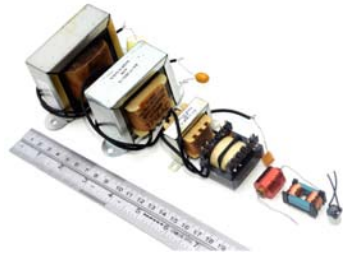
Sytonistor Hardware



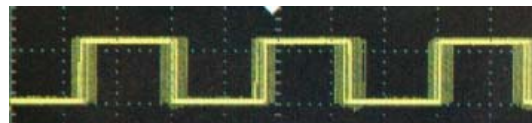
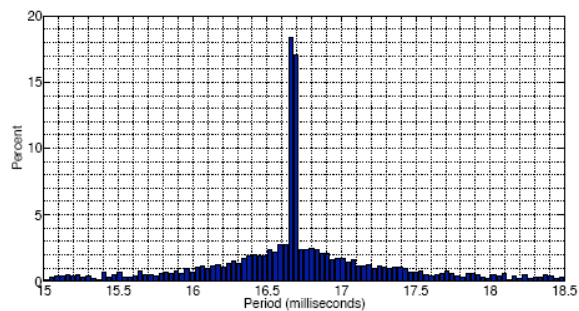
Micro-controller



Tank Circuit (low Q)?



The raw signal

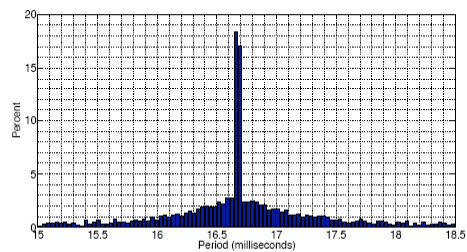
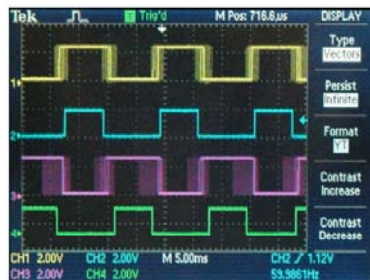


O-scope with delay 10 second persistence

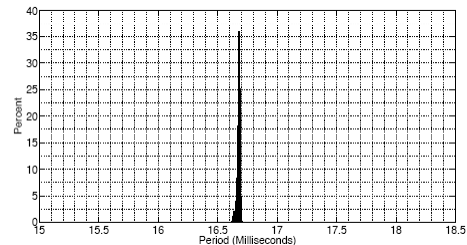
Phase-Locked Loop (PLL)

- Adjust *period* of output signal based on *phase difference* compared to input signal
- Classic controls problem
- We used a Proportional-Integral-Derivative (PID) controller
 - Low gains with reasonable I-term since we do not require extremely fast convergence

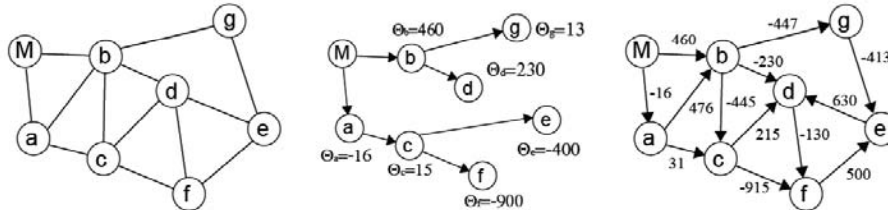
Cleaning up the jitter



(a)

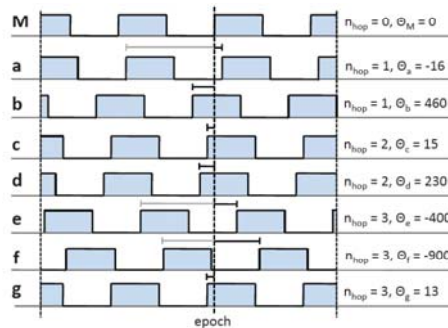
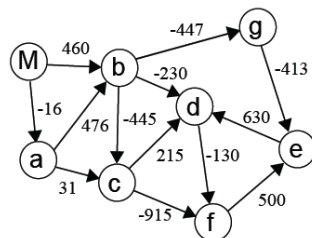


Protocol (1 of 2)



1. Build Spanning Tree
2. Flooding Time Synchronization
 - Determine phase offset from initial epoch
3. Phase Offset Adjustment

Protocol (2 of 2)

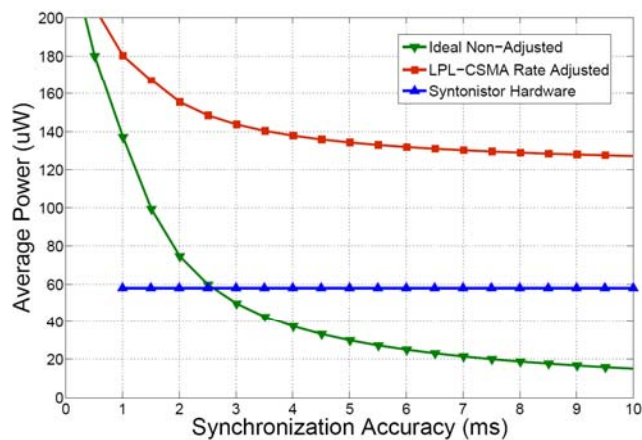


- Simple
- MAC protocol independent

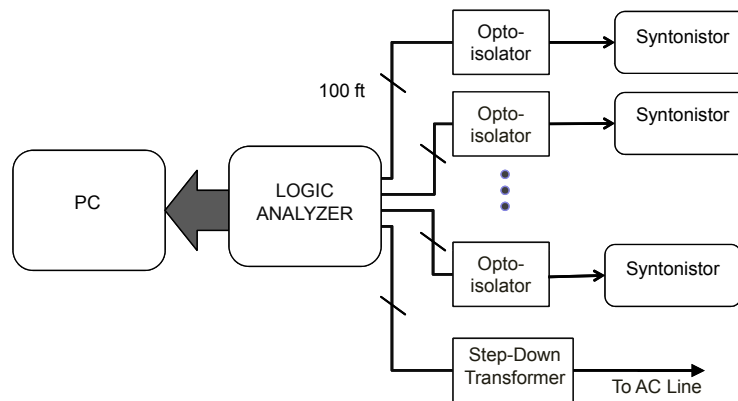
Synchronization Energy (1 of 2)

- **Ideal non-adjusted approach**
 - Send a packet when local clock drift exceeds required synchronization
 - Assume perfect re-sync and ideal MAC protocol
- **LPL-CSMA (B-mac) rate adjusted**
 - Add a MAC protocol to Ideal approach, but now we apply clock rate adjustment based on multiple packets
- **Syntonistor**
 - Consumes 58 μ W

Synchronization Energy (2 of 2)

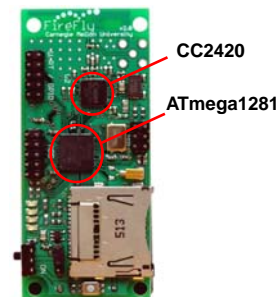


Experimental Setup

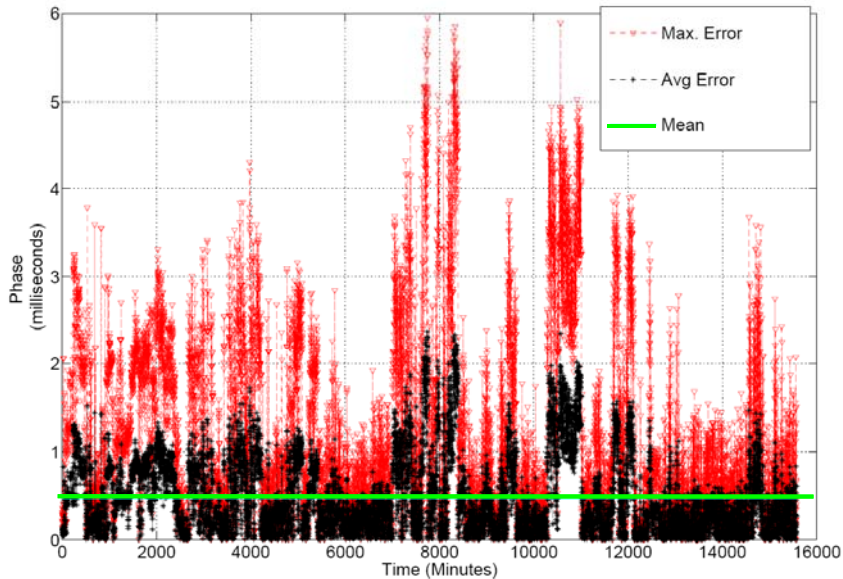


FireFly running Nano-RK

- **C GNU tool-chain**
- **Classical Preemptive Operating System Multitasking Abstractions**
- **Real-Time Priority-Based Scheduling**
 - Rate-Monotonic Scheduling
- **Built-in Fault Handling**
- **Resource Reservations**
 - CPU, Network, Transducer Resource Control
 - Forms Virtual Energy Budget



8 nodes, 10000 ft², 11 days



Interference

- **Indoors**
 - High Frequency sources are bad (computers, TVs, etc.)
 - Some devices are good (lights, etc.)
 - Transformers radiate a clean signal for multiple meters
 - AC adapters are like transmitters
- **Outdoors**
 - Strong signal 50 meters from buildings
 - Near power lines (buried or above ground) works very well
 - Surprising where one finds power lines

Limitations

- **No Mobility**
 - Due to low frequency
- **Only operates near power**
 - Not good for the ocean, space or remote areas
- **Requires extra hardware (cost)**
 - This can be optimized

Conclusion

- **Developed a hardware device that locks onto the magnetic field from power lines**
 - Consumes $58\mu W$
 - Ambient magnetic field energy is already there
- **Using a high-level protocol, network-wide synchronization is possible**
 - Typically less than $1ms$ accuracy
- **Remains synchronized without exchanging any packets**
- **Locally detects errors without sending packets**

Thank You.

Questions?