## Homework \#3 Practice

Here is some practice with translation and rotation.
The first line of code must be:
size ( $400,400, ~ P 3 D)$ ):
Then you can translate - use the three argument signature of translate:
translate $x, y, z$ )
like this:
translate( translate( .5*width, .1*height, 0 ):
Then you can draw a sphere or box. Remember that there are two signatures for box. Practice with both:
box( 200, 20, 100 ):


You can also use fill, noFill, stroke, noStroke and strokeWeight in 3-D. Try to draw the following:


It may be easier for you to use the pushMatrix( ) / popMatrix( ) functions for each translation. In these examples the strokeWeight is set to 3. The part of Processing that does the computing and drawing does not always produce a good final product. We will discuss why in class.

